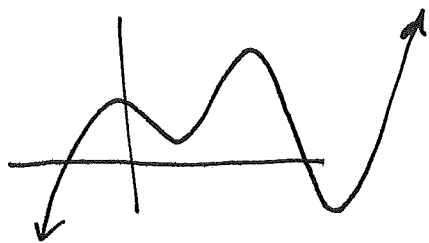


On Wednesday, discussing inverse functions.

Have $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$. Seek g s.t. $g(f(x)) = x$.
 $f(g(y)) = y$

Example: $f: \mathbb{R} \rightarrow \mathbb{R}$ with graph:



Not invertible, since not one-one.

(invertible \Leftrightarrow one-one and onto)

But we could ask for invertibility on subset $(a, b) \in \mathbb{R}$.

Avoid maxima/minima of the function.

(places where $f'(x) = 0$, i.e. derivative is not invertible!)

If we want to know value of $g(7)$, e.g. solve for when $f(x) = 7$

i.e. $f(x) - 7 = 0$ can do this by Newton's method.

Inverse Function Thm (Qualitative Version)

If $f: U \rightarrow \mathbb{R}^n$ continuously differentiable (i.e. first partials continuous)

If $Df(x_0)$ invertible, then f is invertible, with differentiable inverse,

on an open neighborhood of $f(x_0)$.

Intuition: $Df(x_0)$ invertible if $\det [Df(x_0)] \neq 0$.

(from $\mathbb{R}^2 \rightarrow \mathbb{R}^2$)

so if continuous, we can move nearby x_0 and $Df(x)$ will still have non-zero det.
(say to x)

Want to sharpen, then prove, inverse function thm, but

first do example from the book.

Idea: Use inverse function theorem to study image of function.

If $f: \mathbb{R} \rightarrow \mathbb{R}$ (continuous), then image of f is connected region of \mathbb{R} , so need to find max/min.
since diff.

If $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, connected sets much more interesting.

e.g. $F \begin{pmatrix} \theta \\ \phi \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 3 \cos \theta + \cos \phi + 10 \\ 3 \sin \theta + \sin \phi \end{pmatrix}$

(midpoints of lines connecting pts. on two circles)

Key idea: If F invertible in nbhd. of $F \begin{pmatrix} \theta_0 \\ \phi_0 \end{pmatrix}$, then all pts in nbhd are in the image of F . Translating, if $DF \begin{pmatrix} \theta_0 \\ \phi_0 \end{pmatrix}$ is

invertible, then $\begin{pmatrix} \theta_0 \\ \phi_0 \end{pmatrix}$ is an interior point in the image.

Thus boundary of image should be at points where $DF \begin{pmatrix} \theta_0 \\ \phi_0 \end{pmatrix}$ is not invertible (i.e. $\det DF \begin{pmatrix} \theta_0 \\ \phi_0 \end{pmatrix} = 0$)

We compute $DF \begin{pmatrix} \theta \\ \phi \end{pmatrix} = \begin{bmatrix} -\frac{3}{2} \sin \theta & -\frac{1}{2} \sin \phi \\ \frac{3}{2} \cos \theta & \frac{1}{2} \cos \phi \end{bmatrix}$ with $\det =$
 $-\frac{3}{4} (\sin \theta \cos \phi - \cos \theta \sin \phi)$

so $\det = 0$ when $\theta = \phi$ or $\phi + \pi$.

$$= -\frac{3}{4} \sin(\theta - \phi)$$

When $\theta = \phi$: $F \begin{pmatrix} \theta \\ \theta \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 3 \cos \theta + \cos \theta + 10 \\ 3 \sin \theta + \sin \theta \end{pmatrix}$

$$= \begin{pmatrix} 2 \cos \theta + 5 \\ 2 \sin \theta \end{pmatrix}$$

← circle of radius 2 at (5,0)

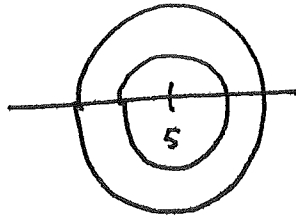
When $\phi = \theta - \pi$:

$$F \begin{pmatrix} \theta \\ \theta - \pi \end{pmatrix} = \begin{pmatrix} \cos \theta + 5 \\ \sin \theta \end{pmatrix}$$

↖ circle of radius 1 at (5,0)

use that $\cos(\theta - \pi) = -\cos \theta$
 $\sin(\theta - \pi) = -\sin \theta$

Looking for a connected region of \mathbb{R}^2 whose boundary is a subset of annulus



only two possibilities:
one of circles or
the annulus.

Argue that $(5,0)$ can't be in image, so must be annulus.

if $(5,0)$ is midpoint of segment
with point on C_2 : circle of
radius 1 at
 $(10,0)$

then other point is on
the circle C_1 of radius 1 at $(0,0)$.

Quantitative Version of Inverse function Thm: $f: U \rightarrow \mathbb{R}^n$ cont. diff.

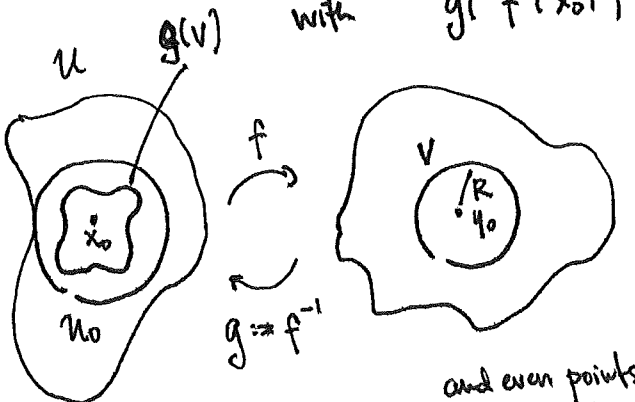
Give radius R for which \exists inverse function to f at $f(x_0)$ is
defined on $B_R(f(x_0))$: Find R s.t.

① $U_0 := \{x \mid |Df(x_0)^{-1}|(x - x_0)| \leq R\} \subseteq U$

② On U_0 , Df is Lipschitz with radius $\frac{1}{2R |Df(x_0)^{-1}|^2}$

then $\exists!$ continuously diff. $g: B_R(f(x_0)) \rightarrow U_0$

with $g(f(x_0)) = x_0$ and $f(g(y)) = y \quad \forall y \in B_R(f(x_0))$



Important, since f may map
points of U outside $B_R(f(x_0))$.
Hence not $g(f(x)) = x \quad \forall x \in U$

of inverse function thm:

Construct inverse via Kantorovich's theorem, with initial point x_0 s.t. $f(x_0) = y_0$

i.e. given $y \in V \subseteq \text{range space}$, use Newton's method to find root x of $f(x) - y = 0$.

Its Jacobian is just $[Df(x)]$ since y fixed const.

$$\text{so } \underline{r} = - [Df(x_0)]^{-1} \cdot (f(x_0) - y)$$

(Maybe $r_0(y)$ is better notation, since want to understand dependence on y)

$$\Rightarrow |\underline{r}| \leq | [Df(x_0)]^{-1} | \cdot R \quad (*)$$

where R : radius of ball defining V .

We've set up U_0 to have radius $2 \cdot$ (right-hand side of $(*)$)

so $x_1 = x_0 + \underline{r}$ and ball of x_1 with radius r_0 still contained in U_0

for Kantorovich's thm to hold, need

$$|f(x_0) - y| \cdot |Df(x_0)^{-1}|^2 M \leq \frac{1}{2}$$

Hence if Df Lipschitz on U_0 , this suffices.

But we chose Lipschitz ratio M precisely so that this holds, noting $|f(x_0) - y| \leq R$.

$\{x_n\} \rightarrow$ root of $f(x) - y$, call the root $x = f^{-1}(y)$.

$$\text{since } f(f^{-1}(y)) = y$$

Works for all $y \in V$ according to proof.

In particular $f^{-1}(y_0) = x_0$.

Still need to show resulting function f^{-1} is continuously diff.

Classic warning example: It may be that $Df(x) \neq 0 \quad \forall x$,

then inverse function theorem says local inverse exists, but not necessarily a global inverse.

Example: $\mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$(x, y) \mapsto \begin{bmatrix} e^x \cos y \\ e^x \sin y \end{bmatrix}$$

$$\det(Df(x, y))$$

$$= e^x \neq 0 \quad \forall x$$

but clearly not one-one since \cos, \sin are 2π period.

Corollary of Inverse Function Thm:

We can compute derivative of f^{-1} using chain rule:

(now that we know it is differentiable)

$$[Df^{-1}(y)] = [Df(f^{-1}(y))]^{-1} \quad \text{since } f \circ f^{-1}(y) = y.$$

To really finish pf. of inverse function thm, need to show

- ① f is injective on U_0 , thus f^{-1} unique inverse.
- ② f^{-1} continuous (messy set of inequalities, see Appendix A.7)
- ③ f^{-1} differentiable
- ④ f^{-1} has continuous partials.

one theme: change coordinates and rescale so that f analyzed at $\underline{0}$

not $\underline{x_0}$, with $Df(\underline{0}) = Id.$

Makes analyzing inequalities much easier.