Mathematics of Image and Data Analysis Math 5467

The Discrete Fourier Transform

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Last time

• Newton's Method

Today

 \bullet Discrete Fourier Transform (DFT)

Audio compression basis

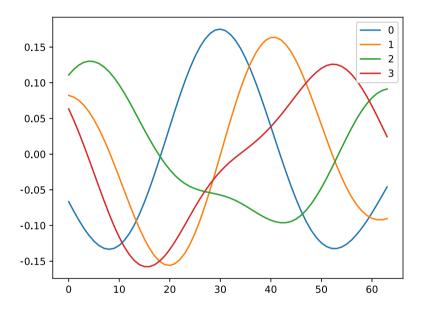


Figure 1: The first 4 principal components computed during PCA-based audio compression. Two of the basis functions strongly resemble the trigonometric functions sin and cos.

A role for a hand-crafted change of basis

- PCA finds the best change of basis that represents your data with as few basis vectors as possible.
- In some setting PCA is too expensive (embedded environments, cell phones, digital cameras, video surveillance, etc.).
- A hand-crafted change of basis can be computed very efficiently and studied much more deeply mathematically.

Complex numbers

We recall that a complex number has the form z=a+ib where $a,b\in\mathbb{R}$ and $i=\sqrt{-1}$. The set of all complex numbers is denoted \mathbb{C} . For a complex number z=a+ib, the *complex conjugate*, denoted \overline{z} , is given by

$$\overline{z} = a - ib.$$

The modulus of z, denoted |z|, is given by

$$|z| = \sqrt{a^2 + b^2} = \sqrt{z\overline{z}}.$$

Complex exponential and Euler's formula

The complex exponential of $z \in \mathbb{C}$ is defined by the Taylor series expansion

$$e^z = \sum_{k=0}^{\infty} \frac{z^k}{k!}.$$

The Taylor series is absolutely convergent in the whole complex plane. A very important identity involving the complex exponential is Euler's identity

$$(1) e^{it} = \cos t + i\sin t$$

for all real numbers $t \in \mathbb{R}$.

Proof of Euler's formula

$$f(t) = \cos(t) + i \sin(t)$$

$$f'(t) = -\sin(t) + i \cos(t)$$

$$= i \left(\cos(t) - \frac{1}{i} \sin(t)\right)$$

$$= \frac{1}{i} - \frac{1}{i} \left(\frac{i}{i}\right) = \frac{i}{i^2} = \frac{i}{-i} = -i$$

$$= i \left(\cos(t) + i \sin(t)\right)$$

= i f(t)

$$\frac{1}{dt} \left(\frac{f(t)}{e^{it}} \right) = \frac{e^{it} f'(t) - f(t) i e^{it}}{(e^{it})^2}$$

$$= \frac{e^{it} i f(t) - f(t) i e^{it}}{e^{ait}}$$

$$= 0$$

$$= 0$$

$$= 0$$

$$f(t) = 0$$

$$= 0$$

$$f(t) = 0$$

$$= 0$$

$$= 0$$

$$= 0$$

The Discrete Fourier Transform (DFT)

Let $\mathbb{Z}_n = \{0, 1, \dots, n-1\}$ be the cyclic group $\mathbb{Z}_n = \mathbb{Z}/n$ (i.e., integers $p, q \in \mathbb{Z}_n$ are added, subtracted, or multiplied, the result is interpreted modulo n).

Example 1. In \mathbb{Z}_4 we have $2+2=4=0 \mod 4$.

 \triangle



Let $L^2(\mathbb{Z}_n)$ denote the vector space of functions $f:\mathbb{Z}_n\to\mathbb{C}$. We define the inner product on $L^2(\mathbb{Z}_n)$ by

$$\langle f, g \rangle = \sum_{k=0}^{n-1} f(k) \overline{g(k)}.$$

The norm of $f \in L^2(\mathbb{Z}_n)$ is defined by $||f|| = \sqrt{\langle f, f \rangle}$.

$$f(k) f(k) = |f(k)|^2$$

The Discrete Fourier Transform (DFT)

The DFT is an orthogonal change of basis in $L^2(\mathbb{Z}_n)$ that expresses a function $f \not \models L^2(\mathbb{Z}_n) \to \mathbb{C}$ in terms sinusoidal basis functions of different frequencies

(2)
$$k \mapsto e^{2\pi i \sigma k} = \cos(2\pi \sigma k) + i\sin(2\pi \sigma k).$$

Which frequencies?

$$N = \frac{1}{5} = 0$$

$$2\pi i \frac{1}{N} = 0$$

$$2\pi i \frac{1}{N}$$

Q=0,1,--, N-1

DFT basis functions

5= &

We define

(3)
$$u_{\ell}(k) := e^{2\pi i k \ell/n} \quad \ell = 0, 1, \dots, n-1.$$

It is often useful to note that we can set $\omega = e^{2\pi i/n}$ and write

$$u_{\ell}(k) = \omega^{k\ell}.$$

The complex number ω is an n^{th} root of unity, meaning that

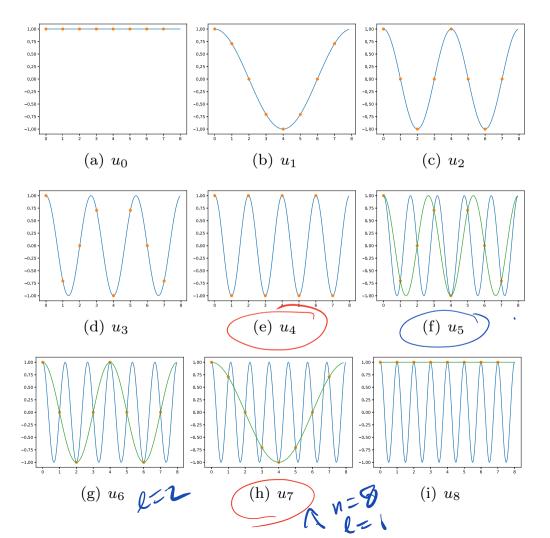
$$\omega^n = e^{2\pi i} = 1.$$

We also have $\overline{\omega} = e^{-2\pi i/n} = \omega^{-1}$.

$$\overline{W} = (\cos(a\pi_n) + i\sin(a\pi))$$

$$= \cos(a\pi) - i\sin(a\pi)$$

= Cos (- ATT) + i sin (-ATT) = C = W



Aliasing
$$U_{N-2}(k) = W^{k(N-2)}$$

$$= W^{k(N-2)}$$

Un-e aliaser to UE(k)
Hishest frequency is $2=\frac{n}{2}$.

Orthogonality

Lemma 1. The functions $u_0, u_1, \ldots, u_{n-1}$ are orthogonal. In particular

(4)
$$\langle u_{\ell}, u_{m} \rangle = \begin{cases} n, & \text{if } \ell = m \\ 0, & \text{otherwise.} \end{cases}$$

Proof: (ue, um) =
$$\sum_{k=0}^{N-1} ue(k) \overline{u}_{m}(k)$$

 $u_{k}(k) = w$
 $u_{k}(k) = w$

Set
$$r = w^{2-m}$$
 so that

$$(u_{e}, u_{m}) = \sum_{k=0}^{\infty} r^{k} = \frac{1-r^{n}(k)}{1-r}$$

$$S_{n} = \sum_{k=0}^{\infty} r^{k} = r^{n} + \sum_{k=1}^{\infty} r^{k}$$

$$= r^{n} + S_{n} - 1$$

$$r S_{n} - S_{n} = r^{n} - 1 = S_{n} = r^{n-1}$$

 $r = \omega^{e-m}$ $r' = (\omega^{n})^{e-m} = 1^{e-m} = 1$ (4) because Sina w= (eatin) = 1 How do we express ft (2/21) f(k) = \(\frac{\sigma^{-1}}{2=0} \) Ce Ue(k)

$$(f, Um) = (\sum_{n=0}^{n-1} CeUe, Um)$$

$$= \sum_{l=0}^{\infty} C_{l} (U_{l}, U_{lm})$$

$$= (n, l=m)$$

$$= n C_{lm}$$

$$= (n, l=m)$$

$$= (n$$

Definition

Definition 2. The Discrete Fourier Transform (DFT) is the mapping $\mathcal{D}: L^2(\mathbb{Z}_n) \to L^2(\mathbb{Z}_n)$ defined by

$$\mathcal{D}f(\ell) = \sum_{k=0}^{n-1} f(k)\omega^{-k\ell} = \sum_{k=0}^{n-1} f(k)e^{-2\pi ik\ell/n},$$

$$= \langle f, \mathcal{M} \rangle \qquad \mathcal{M}_{\ell}(k) = \mathcal{W}$$

where $\omega = e^{2\pi i/n}$.

Proposition 3. If $f \in L^2(\mathbb{Z}_n)$ is real-valued (i.e., $f(k) \in \mathbb{R}$ for all k), then

$$\mathcal{D}f(\ell) = \overline{\mathcal{D}f(n-\ell)}.$$

$$\text{Proof:} \quad \mathcal{D}f(\ell) = (f, 4\ell) = (f, 4n-e)$$

$$= \sum_{k=0}^{n-1} f(k) U_{n-e}(k)$$

$$= \sum_{k=0}^{n-1} f(k) U_{n-e}(k)$$

$$= (f, U_{n-e})$$

= D+(n-0)

Inverse Fourier Transform

Theorem 4 (Fourier Inversion Theorem). For any $f \in L^2(\mathbb{Z}_n)$ we have

(5)
$$f(k) = \frac{1}{n} \sum_{\ell=0}^{n-1} \mathcal{D}f(\ell)\omega^{k\ell} = \frac{1}{n} \sum_{\ell=0}^{n-1} \mathcal{D}f(\ell)e^{2\pi i k\ell/n}.$$

Definition 5 (Inverse Discrete Fourier Transform). The *Inverse Discrete Fourier Transform (IDFT)* is the mapping $\mathcal{D}^{-1}: L^2(\mathbb{Z}_n) \to L^2(\mathbb{Z}_n)$ defined by

$$\mathcal{D}^{-1}f(\ell) = \frac{1}{n} \sum_{k=0}^{n-1} f(k)\omega^{k\ell} = \frac{1}{n} \sum_{k=0}^{n-1} f(k)e^{2\pi ik\ell/n}.$$



 $f = \frac{1}{2} \left(f, 4e \right) \mathcal{L}$ \mathcal{L} \mathcal{L} \mathcal{L}

Matrix version

Remark 6. Define the $n \times n$ complex-valued matrix with entries $W(k, \ell) = \omega^{k\ell}$, that is

(6)
$$W = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega & \omega^2 & \cdots & \omega^{n-1} \\ 1 & \omega^2 & \omega^4 & \cdots & \omega^{2(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \cdots & \omega^{(n-1)(n-1)} \end{bmatrix}$$

Then the DFT can be expressed via matrix multiplication as $\mathcal{D}f = \overline{W}f$. The inverse DFT can be expressed as $\mathcal{D}^{-1}f = \frac{1}{n}Wf$. In both cases we treat f as a vector $f \in \mathbb{C}^n$. Theorem 4 (Fourier Inversion) can be restated as saying that $W\overline{W} = nI$.

Basic properties

Exercise 7. Show that the DFT enjoys the following basic shift properties.

1. Recall that $u_{\ell}(k) := e^{2\pi i k \ell/n} = \omega^{k\ell}$. Show that

$$\mathcal{D}(f \cdot u_{\ell})(k) = \mathcal{D}f(k+\ell).$$

2. Let $T_{\ell}: L^2(\mathbb{Z}_n) \to L^2(\mathbb{Z}_n)$ be the translation operator $T_{\ell}f(k) = f(k-\ell)$. Show that

$$\mathcal{D}(T_{\ell}f)(k) = e^{-2\pi i k\ell/n} \mathcal{D}f(k).$$

[Hint: You can equivalently show that $\mathcal{D}^{-1}(f \cdot u_{\ell})(k) = \mathcal{D}^{-1}f(k-\ell)$, using an argument similar to part 1.]

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Intro to DFT (.ipynb)