

Math 5588 Final Exam Information

- The final exam will take place on Tuesday, May 9 4:45pm-6:45pm in Vincent Hall 206 (Please note the room number!). Please arrive early so we can start on time.
- The exam can potentially cover anything in the course, with the exception of the lectures on differential games.
- The exam is closed book. No textbooks, notes, or calculators are allowed. The formula sheet below will be provided on the exam.
- The exam will have 8 questions, ranging in levels of difficulty. It is a good idea to look through the questions first and complete the ones you are most comfortable with early in the exam. Below are a collection of sample questions from the last third of the course. Please see the sample problems for midterms 1 and 2 for practice problems from the first two thirds of the semester.

Sample questions

1. Determine whether the following statements are true or false. No justification is required.
 - (a) Disturbances in the wave equation travel at exactly the wavespeed c in $n = 3$ dimensions.
 - (b) Disturbances in the wave equation travel at exactly the wavespeed c in $n = 2$ dimensions.
 - (c) The Rankine-Hugoniot condition selects a unique weak solution of a scalar conservation law.
 - (d) If $u(x, t)$ is a solution of a Hamilton-Jacobi equation in $n = 1$ spatial dimensions, then $v = u_x$ is the solution of a scalar conservation law.
 - (e) The Hopf-Lax formula gives the unique viscosity solution a Hamilton-Jacobi equation of the form $u_t + H(\nabla u) = 0$ when H is convex and superlinear.
 - (f) The Lax-Oleinik formula is an alternative to the Hopf-Lax formula for Hamilton-Jacobi equations.
2. Use the Hopf-Lax formula to solve the Hamilton-Jacobi equation

$$u_t + \frac{1}{2}u_x^2 = 0$$

with initial condition $u(x, 0) = f(x)$ where

- (a) $f(x) = x$
 - (b) $f(x) = x^2$
 - (c) $f(x) = 1 - x$
3. Solve Burger's equation $u_t + uu_x = 0$ with initial condition $u(x, 0) = f(x)$ where
 - (a) $f(x) = x$

- (b) $f(x) = x^2$
(c) $f(x) = 1/x$

4. Find the entropy solution of Burger's equation $u_t + uu_x = 0$ with initial condition $u(x, 0) = f(x)$ where

$$f(x) = \begin{cases} 1, & \text{if } x < 0 \\ 0, & \text{if } 0 < x < 1 \\ 1, & \text{if } x > 1. \end{cases}$$

5. Find the entropy solution of Burger's equation $u_t + uu_x = 0$ with initial condition $u(x, 0) = f(x)$ where

$$f(x) = \begin{cases} 0, & \text{if } x < 0 \\ 1, & \text{if } 0 < x < 1 \\ 0, & \text{if } x > 1. \end{cases}$$

6. Calculate the elemental stiffness k_{ij}^s for an isosceles triangle with base of length 1 and height $h > 0$.
7. Consider the optimal control problem with dynamics

$$\dot{x}(s) = \alpha(s) - x(s) + b, \quad t < s \leq T$$

and cost

$$C_{x,t}(\alpha) = \int_t^T |\alpha(s)|^2 + |x(s)|^2 ds,$$

where $b \in \mathbb{R}^n$, $\alpha : [0, T] \rightarrow \mathbb{R}^n$ is the control and $x : [0, T] \rightarrow \mathbb{R}^n$ is the state. Write down the Hamilton-Jacobi-Bellman equation for the value function

$$u(x, t) = \min_{\alpha: [0, T] \rightarrow \mathbb{R}^n} C_{x,t}(\alpha).$$

Formula Sheet

$$L(u(x), u'(x)) - u'(x)L_p(u(x), u'(x)) = \text{Constant}$$

$$L_z(x, u(x), u'(x)) - \frac{d}{dx}L_p(x, u(x), u'(x)) = 0.$$

$$\nabla I(u) = L_z(x, u, \nabla u) - \text{div}(\nabla_p L(x, u, \nabla u)) = 0$$

$$\int_U u_{x_i} dx = \int_{\partial U} u \nu_i dS.$$

$$\int_U u \Delta v dx = \int_{\partial U} u \frac{\partial v}{\partial \nu} dS - \int_U \nabla u \cdot \nabla v dx$$

$$\int_U u \Delta v - v \Delta u dx = \int_{\partial U} u \frac{\partial v}{\partial \nu} - v \frac{\partial u}{\partial \nu} dS$$

$$\int_U \Delta v dx = \int_{\partial U} \frac{\partial v}{\partial \nu} dS$$

$$\int_U u \text{div}(F) dx = \int_{\partial U} u F \cdot \nu dS - \int_U \nabla u \cdot F dx.$$

$$\mathcal{F}(u) = \hat{u}(k) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} u(x) e^{-ik \cdot x} dx.$$

$$\mathcal{F}^{-1}(\hat{u}) = u(x) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} \hat{u}(k) e^{ik \cdot x} dk.$$

$$\mathcal{F}(u_{x_j}) = ik_j \hat{u}(k).$$

$$\mathcal{F}(u * v) = (2\pi)^{n/2} \hat{u}(k) \hat{v}(k).$$

$$\int_{\mathbb{R}^n} |\hat{u}(k)|^2 dk = \int_{\mathbb{R}^n} |u(x)|^2 dx.$$

$$\mathcal{F}(e^{-|x|^2/2}) = e^{-|k|^2/2}.$$

$$u(x, t) = \frac{1}{|\partial B(x, t)|} \int_{\partial B(x, t)} tg(y) + f(y) + \nabla f(y) \cdot (y - x) dS(y).$$

$$u(x, t) = \frac{1}{2\pi t^2} \int_{B(x, t)} \frac{tf(y) + t\nabla f(y) \cdot (y - x) + t^2 g(y)}{\sqrt{t^2 - |x - y|^2}} dy.$$

$$k_{ij}^s = -\frac{(\mathbf{x}_i - \mathbf{x}_\ell) \cdot (\mathbf{x}_j - \mathbf{x}_\ell)}{4\text{Area}(T_s)}, \quad k_{ii}^s = \frac{|\mathbf{x}_j - \mathbf{x}_\ell|^2}{4\text{Area}(T_s)}.$$

$$\frac{dx}{dt} = \frac{F(u_\ell) - F(u_R)}{u_\ell - u_R}, \quad u_\ell > u_R.$$

$$u(x, t) = \min_{y \in \mathbb{R}^n} \left\{ f(y) + tL \left(\frac{x - y}{t} \right) \right\}, \quad L = H^*$$

$$H^*(q) = \max_{p \in \mathbb{R}^n} \{p \cdot q - H(p)\}.$$

$$H(p, x) = \min_{a \in A} \{f(x, a) \cdot p + r(x, a)\}.$$