

Math 4242: Linear Algebra  
Midterm I : February 23, 2018

Key

Directions:

PLEASE DO NOT OPEN EXAM UNTIL DIRECTED TO DO SO.

This is a closed book exam. No books. No notes. No crib sheets. No calculators.

You are allowed 50 minutes to complete this exam.

Please show all your work on the enclosed pages. You are not allowed any scratch paper of your own.

There are 7 questions. Including this title page, there are 11 pages (the last two of which are blank).

Please make sure all the pages are here before beginning your 50 minutes of work.

Scores:

- (1) (5 pts) \_\_\_\_\_
- (2) (3 pts) \_\_\_\_\_
- (3) (5 pts) \_\_\_\_\_
- (4) (5 pts) \_\_\_\_\_
- (5) (5 pts) \_\_\_\_\_
- (6) (5 pts) \_\_\_\_\_
- (7) (5 pts) \_\_\_\_\_

Thanks to following  
students for solutions.

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(1) (5 pts) Consider the following linear system of equations,

$$\begin{aligned}x + \frac{1}{2}y + \frac{7}{2}z &= \frac{5}{2} \\ 2x - y + z &= 3.\end{aligned}$$

Using Gaussian elimination with partial pivoting on an augmented matrix, determine whether the system is consistent. If the system is consistent, find all solutions. If it is not consistent, explain why. Show all the steps in your work and be sure to use partial pivoting in your work (and to show this work on these exam pages).

*Partial Pivoting  $\rightarrow$  switch row to highest magnitude top*

$$\left( \begin{array}{ccc|c} 1 & \frac{1}{2} & \frac{7}{2} & \frac{5}{2} \\ 2 & -1 & 1 & 3 \end{array} \right) \xrightarrow{R2 \leftrightarrow R1} \left( \begin{array}{ccc|c} 2 & -1 & 1 & 3 \\ 1 & \frac{1}{2} & \frac{7}{2} & \frac{5}{2} \end{array} \right) \xrightarrow{R2 - \frac{1}{2}R1}$$

$$\left( \begin{array}{ccc|c} 2 & -1 & 1 & 3 \\ 0 & 1 & \frac{6}{2} & \frac{2}{2} \end{array} \right) = \left( \begin{array}{ccc|c} 2 & -1 & 1 & 3 \\ 0 & 1 & 3 & 1 \end{array} \right)$$

The system is consistent.  
Using back substitution,

$$z = \text{free}$$

$$y + 3z = 1 \Rightarrow y = 1 - 3z$$

$$2x - y + z = 3$$

$$2x - (1 - 3z) + z = 3$$

$$2x - 1 + 4z = 3$$

$$x = 2 - 2z$$

Solutions: The set  $\left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -2 \\ -3 \\ 1 \end{pmatrix} \mid z \in \mathbb{R} \right\}$

5

- (1) (5 pts) Consider the following linear system of equations,

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Using Gaussian elimination with partial pivoting on an augmented matrix, determine whether the system is consistent. If the system is consistent, find all solutions. If it is not consistent, explain why. Show all the steps in your work and be sure to use partial pivoting in your work (and to show this work on these exam pages).

$$\begin{bmatrix} 1 & \frac{1}{2} & \frac{7}{2} & | & \frac{5}{2} \\ 2 & -1 & 1 & | & 3 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 2 & -1 & 1 & | & 3 \\ 1 & \frac{1}{2} & \frac{7}{2} & | & \frac{5}{2} \end{bmatrix} \xrightarrow{-\frac{1}{2}R_1 + R_2} \begin{bmatrix} 2 & -1 & 1 & | & 3 \\ 0 & 1 & 3 & | & 1 \end{bmatrix}$$

Consistent system,  $\infty$  many solutions

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} -2 \\ -3 \\ 1 \end{pmatrix}, \lambda \in \mathbb{R}$$

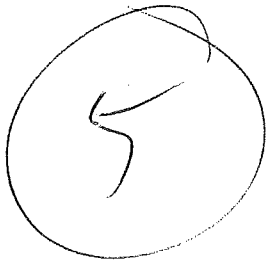
$$x_3 = x_3$$

$$x_2 = 1 - 3x_3$$

$$2x_1 = 3 + x_2 - x_3$$

$$x_1 = \frac{3 + (1 - 3x_3) - x_3}{2}$$

$$= 2 - 2x_3$$



(2) . (3pts) Suppose that

$$A = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 2 & 1 & 1 & 1 \\ 0 & 1 & 1 & 2 \end{pmatrix}$$

Write down a single Matrix  $B$  which, when we multiply  $A$  on the right by  $B$ , it adds 3 times the 2nd column of  $A$  to the 3rd column of  $A$ , and also switches the first column and the fourth column of  $A$ . In other words, find a matrix  $B$  so that

$$AB = \begin{pmatrix} 1 & 2 & 7 & 1 \\ 1 & 1 & 4 & 2 \\ 2 & 1 & 4 & 0 \end{pmatrix}$$

You need not explain your answer, but show any work that you do on these test pages. (Note: Very little partial credit will be given on this problem.)

$$\begin{pmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

3

- (3) (5 pts) Use Gauss-Jordan elimination to find out whether or not the following matrix  $A$  is invertible (nonsingular). If it is invertible, write down the value of  $A^{-1}$ . If it is not invertible, explain briefly why not.

$$A = \begin{pmatrix} 1 & 2 & 2 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{pmatrix}$$

You should show all work.

$$\left( \begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 1 & 3 & 1 & 0 & 1 & 0 \\ 1 & 1 & 3 & 0 & 0 & 1 \end{array} \right) \begin{array}{l} p_2 + (-1)p_1 \\ p_3 + (-1)p_1 \end{array} \sim \left( \begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & -1 & 1 & -1 & 0 & 1 \end{array} \right) \begin{array}{l} \\ p_3 + p_2 \end{array}$$

$$\sim \left( \begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 0 & -2 & 1 & 1 \end{array} \right)$$

$A$  is not invertible.  $A \in \text{Mat}(3 \times 3)$ , yet  $\text{rank}(A) = 2$ . Therefore,  $A$  is not invertible.

5! Mat

(4). (5 pts) True or False: If  $A$  and  $B$  are symmetric matrices, then their product  $AB$  is also symmetric.

$$\begin{array}{l}
 A, B \text{ are symmetric} \begin{cases} \rightarrow A^T = A \\ \rightarrow B^T = B \end{cases} \\
 \downarrow \\
 (AB)^T = B^T A^T = BA
 \end{array}$$

we found that  $(AB)^T = BA$

only way that  $AB$  is symmetric is when  $AB = BA$

$\therefore$  This is not always true.

Example.

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \text{ is symmetric}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}^T = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \text{ is symmetric}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

$$AB = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 4 & 2 \end{bmatrix}$$

$$(AB)^T = \begin{bmatrix} 1 & 4 \\ 2 & 2 \end{bmatrix} \neq AB$$

$\therefore AB$  is not symmetric  $\neq$

Nice!  
5

False #

(4). (5 pts) True or False: If  $A$  and  $B$  are symmetric matrices, then their product  $AB$  is also symmetric.

~~False - In the matrix multiplication of the product, the element  $a_{ij}$  is the dot-product of the  $i$ th row of  $A$  and the  $j$ th column of  $B$ . Its symmetric counterpart is  $a_{ji}$ , where this is the dot-product of the  $j$ th row of  $A$  and the  $i$ th column of  $B$ .~~

$$\begin{array}{ccc} A & B & AB \\ \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} & = \begin{pmatrix} 2 & 2 \\ 1 & 1 \end{pmatrix} \end{array}$$

False -  $A$  and  $B$  are both symmetric but the product  $AB$  is not

5 Nice!

(5). (5 pts) True or False: If  $A$  is an arbitrary  $m \times n$  matrix, then the product  $AA^*$  is Hermitian. (Your answer also must carefully define what it means to be a Hermitian matrix.)

Hermitian:  $A = A^* = \overline{A^T}$  complex conjugate transpose

Let  $S = AA^*$

$S^* = (AA^*)^*$

$S^* = (A^*)^* A^*$

$S^* = AA^*$

$S = AA^*$

$S^* = AA^*$

$S = S^*$  so  $AA^*$  is Hermitian  
True

simple case w/o ii

$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$   $A^* = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$

$AA^* = \begin{bmatrix} 5 & 14 \\ 14 & 20 \end{bmatrix}$   
Hermitian





(5). (5 pts) True or False: If  $A$  is an arbitrary  $m \times n$  matrix, then the product  $AA^*$  is Hermitian. (Your answer also must carefully define what it means to be a Hermitian matrix.)

means  $A^* = A$

$$AA^* \rightarrow (AA^*)^* = (A^*)^* A^* ; (A^*)^* = A \\ = AA^*$$

Since  $(AA^*)^* = AA^*$

$\uparrow$                        $\uparrow$   
 same                      same

Nice!

We can conclude that  $AA^*$  is Hermitian #

Side note:  $A \in \text{mat}(m \times n)$

$A^* \in \text{mat}(n \times m)$

$AA^* \in \text{mat}(m \times m) \rightarrow$  A square matrix

$\therefore$  Hermitian property does exist #

True

SF

(6). (5 pts) True or False: If  $A$  is an  $n \times n$  matrix such that  $(I - A)$  is invertible (i.e. nonsingular), then we can always conclude that,

$$A(I - A)^{-1} = (I - A)^{-1}A.$$

(In other words, we can conclude that the matrices  $A$  and  $(I - A)^{-1}$  must commute.)

True.

Since  $(I - A)$  is invertible,  $(I - A)^{-1}$  exists.

$$A(I - A) = (I - A)A \quad \text{is true since } AI - A^2 = IA - A^2$$

$$\Leftrightarrow A - A^2 = A - A^2.$$

multiply  $(I - A)^{-1}$  on both side of  $A(I - A)$ , as well as  $(I - A)A$

$$(I - A)^{-1}A(I - A)(I - A)^{-1} = (I - A)^{-1}(I - A)A(I - A)^{-1}$$

$$\Leftrightarrow (I - A)^{-1}A I = I A (I - A)^{-1}$$

$$\Leftrightarrow A(I - A)^{-1} = (I - A)^{-1}A.$$

Nice!

(6). (5 pts) True or False: If  $A$  is an  $n \times n$  matrix such that  $(I - A)$  is invertible (i.e. nonsingular), then we can always conclude that,

$$A(I - A)^{-1} = (I - A)^{-1}A.$$

(In other words, we can conclude that the matrices  $A$  and  $(I - A)^{-1}$  must commute.)

True!

Clearly,  $A = A$ . We can also say that  $AI = IA$ , and that  $AI - A^2 = IA - A^2$ .

Using the distributive property carefully,  $A(I - A) = (I - A)A$ . Since  $I - A$  is invertible, we can multiply  $(I - A)^{-1}$  on the right on both sides to get

$$A(I - A)(I - A)^{-1} = (I - A)A(I - A)^{-1}.$$

Now let's multiply on the left on both sides by  $(I - A)^{-1}$ :

$$(I - A)^{-1}A(I - A)(I - A)^{-1} = (I - A)^{-1}(I - A)A(I - A)^{-1}$$

We have that  $(I - A)(I - A)^{-1} = I$  by the definition of inverses, so:

$$(I - A)^{-1}AI = IA(I - A)^{-1}$$

So, we are left with:

$$(I - A)^{-1}A = A(I - A)^{-1}$$

as desired.

✓  
Nice!

(7) (5 points) Suppose that  $M = \{\vec{m}_1, \vec{m}_2, \dots, \vec{m}_r\}$  and  $N = \{\vec{m}_1, \vec{m}_2, \dots, \vec{m}_r, \vec{v}\}$  are two sets of vectors from the same vector space. True or False: If we are told also that  $\vec{v} \in \text{span}(M)$  then we can always conclude  $\text{span}(M) = \text{span}(N)$ .

True

If  $\vec{v} \in \text{span}(M)$ , then  $\vec{v} = \sum_{i=1}^r \alpha_i \vec{m}_i$  where  $\alpha_i$  is a scalar of the vector  $\vec{m}_i$ .  $\text{Span}(M)$

is all linear combinations of the vector.

$$\text{Span}(M) = \sum_{i=1}^r (\beta_i) \vec{m}_i \quad \text{Span}(N) = \left( \sum_{i=1}^r \lambda_i \vec{m}_i \right) + T \cdot \vec{v}$$
$$= \sum_{i=1}^r \lambda_i \vec{m}_i + T \sum_{i=1}^r (\alpha_i \vec{m}_i) = \sum_{i=1}^r (\lambda_i + T \cdot \alpha_i) \vec{m}_i$$

Consequently,  $\text{span}(N)$  is all linear combinations of the vectors of  $M$ . Since  $M$  and  $N$  share the

same spanning vectors, they must share the same

$\text{span}(M) = \text{span}(N)$ .

Yes! Mine!