

DEFINITIONS AND NOTATIONS

Definition 1.1 (operation). For a set A , an operation on A is a function $\circ : A \times A \rightarrow A$. We usually denote $\circ(a, b)$ by $a \circ b$.

Definition 1.2 (associativity, commutativity). Let $\circ : A \times A \rightarrow A$ be an operation on A .

- We say that \circ is associative if for any $a, b, c \in A$, we have $(a \circ b) \circ c = a \circ (b \circ c)$.
- We say that \circ is commutative or abelian if for any $a, b \in A$, we have $a \circ b = b \circ a$.

Definition 1.3 (identity, inverse). Let $\circ : A \times A \rightarrow A$ be an operation on A .

- We say that $e \in A$ is the identity of (A, \circ) if for any $a \in A$ we have $a \circ e = e \circ a = a$.
- If $e \in A$ is the identity of (A, \circ) , then for $a, b \in A$ we say that b is an inverse of a if they satisfy $a \circ b = b \circ a = e$.

Definition 3.1 (group). Let G be a set with an operation $\circ : G \times G \rightarrow G$. Then (G, \circ) is called a group if

- a) \circ is associative,
- b) the identity element exists in G , and
- c) for any $g \in G$, its inverse exists in G .

Definition 3.2 (abelian group). A group (G, \circ) is called commutative or abelian if \circ is commutative.

Definition 3.3 (set automorphism group). For a set A , define $\text{Aut}_{\text{set}}(A)$ to be the group of bijections $f : A \rightarrow A$ whose operation $\circ : \text{Aut}_{\text{set}}(A) \times \text{Aut}_{\text{set}}(A) \rightarrow \text{Aut}_{\text{set}}(A)$ is given by composition of functions.

Definition 3.4 (group of integers modulo n). For $n \in \mathbb{Z}_{>0}$, \mathbb{Z}_n is defined to be a group $\{0, 1, 2, \dots, n-1\}$ whose operation is given by $a \circ b = a + b \pmod{n}$.

Definition 4.1 (subgroup). Let $(G, *)$ be a group and $H \subset G$ be a subset. Then H is said to be a subgroup of G if $(H, * : H \times H \rightarrow H)$ is a group.

Definition 4.2 (subgroup generated by a subset). Let $(G, *)$ be a group and $A \subset G$ be a subset. We define $\langle A \rangle$ to be the smallest subgroup of G containing A , called the subgroup generated by A . Also we say that $\langle A \rangle$ is generated by A .

Definition 4.3 (cyclic group). A group $(G, *)$ is called a cyclic group if there exists $g \in G$ such that $\langle \{g\} \rangle = G$.

Definition 5.1 (symmetric group). Let $A = \{1, 2, \dots, n\}$ for some $n \in \mathbb{Z}_{>0}$. Then we define \mathcal{S}_n to be $\text{Aut}_{\text{set}}(A)$, called the symmetric (or permutation) group on n elements.

Definition 5.2 (cycles, transposition). Let $\alpha \in \mathcal{S}_n$.

- α is called a cycle if there exist pairwise different elements $a_1, a_2, \dots, a_r \in \{1, 2, \dots, n\}$ such that $\alpha(a_1) = a_2, \alpha(a_2) = a_3, \dots, \alpha(a_{r-1}) = a_r, \alpha(a_r) = a_1$, and $\alpha(b) = b$ if $b \notin \{a_1, a_2, \dots, a_r\}$. In this case we usually write $\alpha = (a_1 a_2 \cdots a_r)$.
- α is called a transposition if $\alpha = (a b)$ for some $a, b \in \{1, 2, \dots, n\}$ such that $a \neq b$.
- α is called an adjacent transposition if $\alpha = (a a + 1)$ for some $1 \leq a \leq n - 1$.

Definition 5.3 (notation of permutations). Let $\alpha \in \mathcal{S}_n$.

- The two-line array notation of α is the two-line array $\begin{pmatrix} 1 & 2 & \cdots & n \\ \alpha(1) & \alpha(2) & \cdots & \alpha(n) \end{pmatrix}$
- The cycle notation of α is the expression of α as a product of disjoint cycles.

Definition 5.4 (even, odd permutation). Let $\alpha \in \mathcal{S}_n$.

- α is called even if it is equal to a product of even number of transpositions.
- α is called odd if it is equal to a product of odd number of transpositions.

Definition 5.5 (alternating group). Let $A_n \mathcal{S}_n$ be a set of even permutations in \mathcal{S}_n . Then A_n is in fact a subgroup of \mathcal{S}_n , called the alternating group.

Definition 6.1 (order). Let G be a group and $g \in G$ is an element.

- The order of G , denoted $|G|$, is the cardinal of G .
- The order of g , denoted $\text{ord}(g)$ or $|g|$, is the smallest $m \in \mathbb{Z}_{>0}$ such that g^m is equal to the identity, or ∞ if such m does not exist.

Definition 7.1 (homomorphism). Let G, H be groups. Then a function $f: G \rightarrow H$ is called a homomorphism if for any $a, b \in G$ it satisfies $f(ab) = f(a)f(b)$.

Definition 7.2 (kernel, image). Let G, H be groups and $f: G \rightarrow H$ be a homomorphism.

- The kernel of f is $f^{-1}(e) \subset G$.
- The image of f is $f(G) \subset H$.

Definition 7.3 (various homomorphisms). Let G, H be groups and $f: G \rightarrow H$ be a homomorphism.

- f is called a monomorphism if f is injective.
- f is called an epimorphism if f is surjective.
- f is called an isomorphism if f is bijective. If so, we say that G and H are isomorphic.
- f is called an endomorphism if $G = H$.
- f is called an automorphism if f is a bijective endomorphism.

Definition 7.4 (automorphism group). For a group G , define $\text{Aut}(G)$ to be the set of automorphisms of G . Then it is naturally a group whose operation is given by composition of functions and called the group of automorphisms of G .

Definition 8.1 (equivalence relation). Let A be a set. Then a relation \sim on A is called an equivalence relation on A if

- for any $a \in A$, $a \sim a$,
- for any $a, b \in A$, if $a \sim b$ then $b \sim a$, and
- for any $a, b, c \in A$, if $a \sim b$ and $b \sim c$ then $a \sim c$.

If $a \sim b$, we say that a is equivalent to b .

Definition 8.2 (equivalence class). For a set A with an equivalence relation \sim and for $a \in A$, the set $\{b \in A \mid a \sim b\}$ is called the equivalence class of a .

Definition 8.3 (partition). For a set A , a partition of A is a set P consisting of subsets of A such that for any $B, C \in P$, either $B \cap C = \emptyset$ or $B = C$.

Definition 8.4 (coset). For a group G and its subgroup $H \subset G$, the set aH (resp. Ha) for some element $a \in G$ is called the left (resp. right) coset of H in G .

Definition 8.5 (coset). For a group G and its subgroup $H \subset G$, the index of H in G is the cardinal of (left) cosets of H in G , denoted $(G : H)$.

Definition 9.1 (dihedral group). For $n \in \mathbb{Z}_{\geq 2}$, the dihedral group D_n is the group of isometries of a plane which stabilize a regular n -gon.

Definition 9.2 (quaternion group). The quaternion group Q_8 is a group $\{\pm 1, \pm i, \pm j, \pm k\}$ whose operation is given by

\circ	1	-1	i	$-i$	j	$-j$	k	$-k$
1	1	-1	i	$-i$	j	$-j$	k	$-k$
-1	-1	1	$-i$	i	$-j$	j	$-k$	k
i	i	$-i$	-1	1	k	$-k$	$-j$	j
$-i$	$-i$	i	1	-1	$-k$	k	j	$-j$
j	j	$-j$	$-k$	k	-1	1	i	$-i$
$-j$	$-j$	j	k	$-k$	1	-1	$-i$	i
k	k	$-k$	j	$-j$	$-i$	i	-1	1
$-k$	$-k$	k	$-j$	j	i	$-i$	1	-1

Definition 10.1 (normal subgroup). Let G be a group and H is a subgroup of G . Then H is called a normal subgroup of G if for any $g \in G$, we have $gHg^{-1} \subset H$.

Definition 10.2 (quotient subgroup). Let G be a group and H is a normal subgroup of G . Then G/H , the set of left cosets of H in G , inherits a natural group structure from G and is called the quotient group (factor group) of G by H .

Definition 11.1 (finitely generated group). A group G is called finitely generated if there exists a finite subset $A \subset G$ such that $G = \langle A \rangle$.

Definition 11.2 (p -group). A group G is called a p -group for some prime number p if the order of any element in G is a power of p .

Definition 12.1 (group action). Let G be a group and X be a set. Then we say that G acts on X , there is an action of G on X , or X is a G -set, and write $G \curvearrowright X$, if there is a homomorphism $G \rightarrow \text{Aut}_{\text{set}}(X)$. In this case, for any $g \in G$ and $x \in X$ we denote by $g \cdot x$ the image of x under the image of g under $G \rightarrow \text{Aut}_{\text{set}}(X)$.

Definition 12.2 (faithful action). Suppose that G acts on X . Then we say that G acts faithfully on X if the corresponding homomorphism $G \rightarrow \text{Aut}_{\text{set}}(X)$ is injective.

Definition 12.3 (transitive action). Suppose that G acts on X . Then we say that G acts transitively on X if for any $x, y \in X$ there exists $g \in G$ such that $g \cdot x = y$.

Definition 12.4 (transitive action). Suppose that G acts on X . For $x \in X$, the set $\{g \in G \mid g \cdot x = x\}$ is naturally a subgroup of G , called the isotropy subgroup (or stabilizer) of x . We denote it by G_x or $\text{Stab}_G(x)$.

Definition 12.5 (fixed point). Suppose that G acts on X . For $g \in X$, the set $\{x \in X \mid g \cdot x = x\}$ is called the set of fixed points by g , denoted by X_g or X^g .

Definition 12.6 (orbit). Suppose that G acts on X .

- For $x \in X$, the set $\{g \cdot x \in X \mid g \in G\}$ is called the orbit of x , denoted $G \cdot x$.
- A subset $Y \subset X$ is called an orbit in X under G if $Y = G \cdot x$ for some $x \in X$.
- For $g \in G$, an orbit of g is an orbit of X under $\langle\{g\}\rangle$.

Definition 13.1 (ring). Let A be a set with two operations $+$ and \cdot . Then $(A, +, \cdot)$ is called a ring (or more precisely a ring with unity) if

- $(A, +)$ is an abelian group,
- $\cdot : A \times A \rightarrow A$ is associative,
- for any $a, b, c \in A$, we have $a \cdot (b + c) = a \cdot b + a \cdot c$ and $(b + c) \cdot a = b \cdot a + c \cdot a$, and
- there exists $1 \in A$ such that $1 \cdot a = a \cdot 1 = a$ for any $a \in A$.

We call $1 \in A$ the multiplicative identity of A or the unity of A .

Definition 13.2 (zero-divisor, nilpotent element, and unit). Let A be a ring. Then,

- $a \in A$ is called a zero-divisor if $a \neq 0$ and there exists $b \in A$ such that $b \neq 0$ and either $ab = 0$ or $ba = 0$.
- $a \in A$ is called a nilpotent element if $a^n = 0$ for some $n \in \mathbb{Z}_{>0}$.
- $a \in A$ is called a unit if there exists $b \in A$ such that $ab = ba = 1$. We denote by A^\times the subset of A consisting of all units of A .

Definition 13.3 (commutative ring, integral domain, and field). Let A be a ring. Then,

- A is called a commutative ring if $\cdot : A \times A \rightarrow A$ is commutative.
- A is called an integral domain if A is commutative and A does not contain any zero-divisor.
- A is called a field if A is commutative and $A^\times = A - \{0\}$.

Definition 13.4 (module). Let $(A, +, \cdot)$ be a ring and $(M, +)$ be an abelian group. Then M is called an A -module if there exists a map $\cdot : A \times M \rightarrow M : (a, m) \mapsto a \cdot m$ such that

- for any $a \in A$ and $m, n \in M$, we have $a \cdot (m + n) = a \cdot m + a \cdot n$,
- for any $a, b \in A$ and $m \in M$, we have $(a + b) \cdot m = a \cdot m + b \cdot m$,
- for any $a, b \in A$ and $m \in M$, we have $(a \cdot b) \cdot m = a \cdot (b \cdot m)$, and
- for any $m \in M$, we have $1 \cdot m = m$.

Definition 13.5 (vector space). Let M be an A -module. Then M is called an A -vector space if A is a field.

Definition 13.6 (algebra). Let A be a commutative ring and B is a ring. Then B is called an A -algebra if B is an A -module and for any $a \in A$ and $x, y \in B$ we have $a \cdot (x \cdot y) = (a \cdot x) \cdot y = x \cdot (a \cdot y)$.

Definition 14.1 (subobject).

- Let A be a ring. Then a subset $B \subset A$ is called a subring of A if B is a ring with respect to $+$ and \cdot inherited from A and B contains the unity of A .
- Let A be a ring and M be an A -module. Then a subset $N \subset M$ is called an A -submodule of M if N is an A -module with respect to $+$ and scalar multiplication inherited from M .
- Let A be a commutative ring and B is an A -algebra. Then a subset $C \subset B$ is called an A -subalgebra of B if C is both a subring and an A -submodule of B .

Definition 14.2 (homomorphism).

- Let A and B be rings. Then a function $f : A \rightarrow B$ is called a ring homomorphism if $f(1) = 1$ and for any $x, y \in A$ we have $f(x + y) = f(x) + f(y)$ and $f(xy) = f(x)f(y)$.
- Let A be a ring and M, N be A -modules. Then a function $f : M \rightarrow N$ is called an A -module homomorphism if for any $a \in A$ and $x, y \in M$ we have $f(x + y) = f(x) + f(y)$ and $f(ax) = af(x)$.
- Let A be a commutative ring and B, C be A -algebras. Then a function $f : B \rightarrow C$ is called an A -algebra homomorphism if f is both a ring homomorphism and an A -module homomorphism.

Definition 14.3 (center of a ring). Let A be a ring. Then the center of A , denoted $Z(A)$, is defined to be $Z(A) := \{a \in A \mid ab = ba \text{ for any } b \in A\}$.

Definition 14.4 (ideal). Let A be a ring. Then a subset $I \subset A$ is called an ideal of A if $(I, +)$ is an abelian subgroup of $(A, +)$ and " I absorbs products in A ," i.e. for any $x \in I$ and $a \in A$ we have $ax, xa \in I$.

Definition 14.5 (quotient).

- Let A be a ring and I be an ideal of A . Then A/I is called the quotient of A by I . Its ring structure is defined such that $A \rightarrow A/I : a \mapsto a + I$ is a ring homomorphism.
- Let A be a ring, M be an A -module, and $N \subset M$ be an A -submodule of M . Then M/N is called the quotient of M by N . Its A -module structure is defined such that $M \rightarrow M/N : m \mapsto m + N$ is an A -module homomorphism.

Definition 14.6 (ideal generated by a subset, principal ideal). Let A be a ring.

- For a subset $S \subset A$, we call (S) the ideal of A generated by S , defined to be the smallest ideal of A containing S .

- If I is an ideal of A generated by a single element, then we say that I is a principal ideal.

Definition 14.7 (module generated by a subset, cyclic submodule). Let A be a ring and M be an A -module.

- For a subset $S \subset M$, we call $\langle S \rangle$ the A -submodule of M generated by S , defined to be the smallest A -submodule of M containing S .
- If N is an A -submodule of M generated by a single element, then we say that N is cyclic.

Definition 14.8 (prime and maximal ideal). Let A be a commutative ring and $I \subset A$ be an ideal of A .

- I is called a prime ideal of A if for any $a, b \in A$, if $ab \in I$ then either $a \in I$ or $b \in I$.
- I is called a maximal ideal of A if $I \neq A$ and any ideal of A containing I is equal to either I or A .

Definition 15.1 (finite dimensional vector space). Let F be a field and V be an F -vector space. Then V is called finite-dimensional (or finitely generated) if $V = \langle S \rangle$ for some finite subset $S \subset V$ as an F -vector space.

Definition 16.1 (Euclidean domain). Let A be an integral domain. Then A is called an Euclidean domain (abbreviated ED) if there exists a function $d : A - \{0\} \rightarrow \mathbb{N}$ such that

- $d(a) \leq d(ab)$ for any $a, b \in A - \{0\}$ and
- for any $a \in A$ and $b \in A - \{0\}$, there exists $q, r \in A$ such that $a = bq + r$ and either $r = 0$ or $d(r) < d(b)$.

Definition 16.2 (Principal ideal domain). Let A be an integral domain. Then A is called a principal ideal domain (abbreviated PID) if every ideal of A is principal.

Definition 16.3 (prime and irreducible element). Let A be an integral domain.

- $p \in A$ is called a prime element of A if $p \neq 0, p \notin A^\times$ and (p) is a prime ideal of A , i.e. if $p|ab$ for some $a, b \in A$, then either $p|a$ or $p|b$.
- $p \in A$ is called an irreducible element of A if $p \neq 0, p \notin A^\times$ and if $p = ab$ for some $a, b \in A$ then either $a \in A^\times$ or $b \in A^\times$.

Definition 16.4 (unique factorization domain). Let A be an integral domain. Then A is called a unique factorization domain (abbreviated UFD) if

- for any $a \in A$ such that $a \neq 0$, there exists $u \in A^\times, r \in \mathbb{N}$, and irreducible elements p_1, p_2, \dots, p_r such that $a = up_1p_2 \cdots p_r$, and

- if $up_1p_2\cdots p_r = vq_1q_2\cdots q_s$ for some $u, v \in A^\times$, $r, s \in \mathbb{N}$, and irreducible elements $p_1, p_2, \dots, p_r, q_1, q_2, \dots, q_s \in A$, then $r = s$ and one can reorder q_1, q_2, \dots, q_s such that $p_i = u_iq_i$ for some $u_i \in A^\times$ for $1 \leq i \leq r = s$.