#### MATH 2243: Linear Algebra & Differential Equations

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**Big idea**: Solutions to homogeneous linear systems of equations are subspaces that can be generated (spanned) by a few vectors.

# 4.3: Linear Combinations and Independence of Vectors



#### The Span of a Set of Vectors:

Let  $V' = \{\vec{v}_1, \vec{v}_2, ..., \vec{v}_k\}$  be a subset of vectors in *V*. (for example,  $V' = \{(-1, 2, 1), (1, -2, 1)\}$  in  $\mathbb{R}^3$ )

Let *W* be the set of all linear combinations of *V'*. (*W* for our example would be a plane in  $\mathbb{R}^3$ )

Then, W is a subspace of V.

We write:  $W = span(V') = span(\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}).$ 

In particular, recall in the class notes for 4.2 that the homogeneous system:

$$x_1 - 4x_2 - 3x_3 - 7x_4 = 0$$
  

$$2x_1 - x_2 + x_3 + 7x_4 = 0$$
  

$$x_1 + 2x_2 + 3x_3 + 11x_4 = 0$$

gives us solution space W consisting of  $\vec{x} = a\vec{u} + b\vec{v}$ , where  $\vec{u} = (-1, -1, 1, 0)$  and  $\vec{v} = (-5, -3, 0, 1)$ .

We can visualize (??) W as a plane in  $\mathbb{R}^4$  determined by  $\vec{u}, \vec{v}$ . In other words,  $W = span(\{\vec{u}, \vec{v}\})$ .

Is  $\vec{w} = (2, -6, 3)$  a linear combination of  $\vec{v}_1 = (1, -2, -1)$  and  $\vec{v}_2 = (3, -5, 4)$ ? In other words, can we find unknowns  $c_1, c_2$  such that  $c_1\vec{v}_1 + c_2\vec{v}_2 = \vec{w}$ ?

$$c_{1}\begin{bmatrix}1\\-2\\-1\end{bmatrix}+c_{2}\begin{bmatrix}3\\-5\\4\end{bmatrix}=\begin{bmatrix}2\\-6\\3\end{bmatrix}$$
$$1 \quad 3 + 2\\-2 \quad -5 \quad | \quad -6\\-1 \quad 4 \quad | \quad 3\end{bmatrix} \Rightarrow \begin{bmatrix}1 \quad 3 \quad | \quad 2\\0 \quad 1 \quad | \quad -2\\0 \quad 7 \quad | \quad 5\end{bmatrix} \Rightarrow \begin{bmatrix}1 \quad 3 \quad | \quad 2\\0 \quad 1 \quad | \quad -2\\0 \quad 0 \quad | \quad 19\end{bmatrix}$$

Alternatively for  $\vec{w} = (2, -6, -16)$ ,  $\vec{v}_1 = (1, -2, -1)$  and  $\vec{v}_2 = (3, -5, 4)$ :

$$c_{1} \begin{bmatrix} 1\\ -2\\ -1 \end{bmatrix} + c_{2} \begin{bmatrix} 3\\ -5\\ 4 \end{bmatrix} = \begin{bmatrix} 2\\ -6\\ -16 \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 3 & 1 & 2\\ -2 & -5 & 1 & -6\\ -1 & 4 & 1 & -16 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 3 & 1 & 2\\ 0 & 1 & 1 & -2\\ 0 & 7 & 1 & -14 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 8\\ 0 & 1 & 1 & -2\\ 0 & 0 & 1 & 0 \end{bmatrix}.$$

 $c_1 = 8$  and  $c_2 = -2$ .

### Linear Independence:

The vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$  in a vector space V are said to be linearly independent provided:

 $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \ldots + c_k \vec{v}_k = \vec{0}$  has only the trivial solution:  $c_1 = c_2 = \ldots = c_k = 0$ .

**Corollary**: Vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$  are linearly dependent if and only if at least one of them is a linear combination of the others.

Uniqueness of Subspace Linear Combination: Any vector  $\vec{w}$  in the subspace W spanned by the independent vectors

 $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$  is *uniquely* expressible as a linear combination of these vectors. **Proof:** If both  $\vec{w} = a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_k \vec{v}_k$  and  $\vec{w} = b_1 \vec{v}_1 + b_2 \vec{v}_2 + \dots + b_k \vec{v}_k$ , then

$$a_1 \overrightarrow{v}_1 + a_2 \overrightarrow{v}_2 + \ldots + a_k \overrightarrow{v}_k = b_1 \overrightarrow{v}_1 + b_2 \overrightarrow{v}_2 + \ldots + b_k \overrightarrow{v}_k$$

$$\Rightarrow (a_1 - b_1)\vec{v}_1 + (a_2 - b_2)\vec{v}_2 + \dots + (a_k - b_k)\vec{v}_k = \vec{0}$$

But since  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$  are linearly independent,  $a_i = b_i$ .

Standard Unit Vectors for  $n: \vec{e}_1 = (1, 0, 0, ..., 0), \vec{e}_2 = (0, 1, 0, 0, ..., 0), ..., \vec{e}_n = (0, 0, ..., 1).$ 

Note: for any  $\vec{v} = (a_1, a_2, \dots, a_n)$ , we have  $\vec{v} = a_1 \vec{e}_1 + a_2 \vec{e}_2 + \dots + a_n \vec{e}_n$ ,

the *unique* linear combination of standard unit vectors for  $\vec{v}$ .

However, note  $\{(5,0,0,0), (0,7,0,0), (0,0,9,0), (0,0,9,1)\}$  and  $\{(1,1,1,0), (1,0,1,1), (1,1,0,1), (0,1,1,1)\}$  are (non-standard) bases for  $\mathbb{R}^4$ .

## Linear Independence of k < n Vectors:

 $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  in  $\mathbb{R}^n$  with k < n are linearly independent if and only if  $(\Leftrightarrow)$ 

there is some  $k \times k$  submatrix  $\mathbf{B}^{k \times k}$  of  $\mathbf{A}^{n \times k} = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_k \end{bmatrix}$ 

with a nonzero determinant  $(|\mathbf{B}^{k \times k}| \neq 0)$ .

(justification in the book)

Example :  $\{\vec{u}_1, \vec{u}_2\} = \{(1, 1, 0), (2, 3, 1)\}$  $\mathbf{A}^{3 \times 2} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 0 & 1 \end{bmatrix}$   $|\mathbf{B}_1| = \begin{vmatrix} 1 & 2 \\ 2 & 4 \end{vmatrix} = 0, \quad |\mathbf{B}_2| = \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} = 1, \quad |\mathbf{B}_3| = \begin{vmatrix} 2 & 4 \\ 0 & 1 \end{vmatrix} = 2.$ Alternatively :  $\{\vec{u}_1, \vec{u}_2\} = \{(1, 1, 0), (2, 2, 0)\}$   $\mathbf{A}^{3 \times 2} = \begin{bmatrix} 1 & 2 \\ 1 & 2 \\ 0 & 0 \end{bmatrix}$   $|\mathbf{B}_1| = \begin{vmatrix} 1 & 2 \\ 1 & 2 \\ 0 & 0 \end{vmatrix} = 0, \quad |\mathbf{B}_2| = \begin{vmatrix} 1 & 2 \\ 0 & 0 \end{vmatrix} = 0, \quad |\mathbf{B}_3| = \begin{vmatrix} 1 & 2 \\ 0 & 0 \end{vmatrix} = 0.$ 



**Problem:** #16 If possible, express  $\vec{w} = (7, 7, 9, 11)$  as a linear combination of  $\vec{v}_1 = (2, 0, 3, 1), \ \vec{v}_2 = (4, 1, 3, 2), \ \vec{v}_3 = (1, 3, -1, 3).$ 

If not, show that it is impossible.

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{w}$$
  $c_1(2,0,3,1) + c_2(4,1,3,2) + c_3(1,3,-1,3) = (7,7,9,11)$ 

$$\mathbf{A}\vec{c} = \vec{w} \Rightarrow \begin{bmatrix} 2 & 4 & 1 \\ 0 & 1 & 3 \\ 3 & 3 & -1 \\ 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 7 \\ 7 \\ 9 \\ 11 \end{bmatrix} \text{ trust me} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 6 \\ -2 \\ 3 \\ 0 \end{bmatrix}$$

Has the unique solution...

 $c_1 = 6, c_2 = -2, c_3 = 3, so...$ 

 $\vec{w} = 6\vec{v}_1 - 2\vec{v}_2 + 3\vec{v}_3.$ 

Want to be sure you got the right answer? Substitute into this equation the relevant vectors to ensure you get  $\vec{w} = (7, 7, 9, 11)$ .

Otherwise, find a nontrivial linear combination of them that is equal to the zero vector.

 $\vec{v}_1 = (3,9,0,5), \ \vec{v}_2 = (3,0,9,-7), \ \vec{v}_3 = (4,7,5,0)$ 

	3	3	4	٦	Γ	1	0	$\frac{7}{9}$	
<b>A</b> =	9	0	7			0	1	$\frac{5}{9}$	
	0	9	5			0	0	0	
	5	-7	0			0	0	0	
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We see that the system of 4 equations in 3 unknowns has a one-dimensional solution space.

$$c_{3} = s, \qquad c_{1} = -\frac{7}{9}s, \qquad c_{2} = -\frac{5}{9}s$$
  
 $\vec{c} = \begin{bmatrix} c_{1} \\ c_{2} \\ c_{3} \end{bmatrix} = \begin{bmatrix} -\frac{7}{9}s \\ -\frac{5}{9}s \\ s \end{bmatrix} = \begin{bmatrix} 7 \\ 5 \\ -9 \end{bmatrix}, \text{ when } s = -9.$ 

Since s is a parameter, and can therefore be any real number, I have chosen -9 as its value for convenience.

So, we have  $c_1 = 7$ ,  $c_2 = 5$ , and  $c_3 = -9$ .

Therefore  $7\vec{v}_1 + 5\vec{v}_2 - 9\vec{v}_3 = \vec{0}$ .

(on a test, you will want to double check this by making sure the equality holds by plugging in the vectors)

**Problems: #26** Let's assume the set of vectors  $\{\vec{v}_i\}$  are linearly independent. Apply the definition of linear independence to show that the vectors below are also linearly independent.

 $\vec{u}_1 = \vec{v}_2 + \vec{v}_3, \qquad \vec{u}_2 = \vec{v}_1 + \vec{v}_3, \qquad \vec{u}_3 = \vec{v}_1 + \vec{v}_2$ 

 $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{0}$ , has only the trivial solution  $c_1 = c_2 = c_3 = 0$ .

Want to show that  $b_1\vec{u}_1 + b_2\vec{u}_2 + b_3\vec{u}_3 = \vec{0}$ , has only the trivial solution  $b_1 = b_2 = b_3 = 0$ .

(\*) 
$$b_1\vec{u}_1 + b_2\vec{u}_2 + b_3\vec{u}_3 = b_1(\vec{v}_2 + \vec{v}_3) + b_2(\vec{v}_1 + \vec{v}_3) + b_3(\vec{v}_1 + \vec{v}_2)$$

$$= (b_2 + b_3)\vec{v}_1 + (b_1 + b_3)\vec{v}_2 + (b_1 + b_2)\vec{v}_3$$

Setting this equal to zero, by our previous assumption it must be that  $b_2 + b_3 = 0$ ,  $b_1 + b_3 = 0$ , and  $b_1 + b_2 = 0$ .

From the first equation we have:  $b_3 = -b_2$ .

Applying this to the second equation, we have:  $b_1 = b_2$ . And then from the third equation, we get:  $2b_2 = 0$  or  $b_2 = 0$ . But then  $b_1 = 0$ , and  $b_3 = 0$ .

Therefore, only the trivial solution satisfies the equation (\*), and the vectors  $\{\vec{u}_i\}$  are therefore linearly independent.

**Problem: #28** Prove: If a set *S* of vectors is linearly dependent and a (finite) set *T* contains *S*, then *T* is also linearly dependent. Assume  $S = {\vec{v}_1, \vec{v}_2, ..., \vec{v}_k}$  and  $T = {\vec{v}_1, \vec{v}_2, ..., \vec{v}_m}$ , with m > k.

Because the set *S* of vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$  is linearly dependent,

there exist scalars  $c_1, c_2, \ldots, c_k$  not all zero such that  $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \ldots + c_k \vec{v}_k = \vec{0}$ .

Now let  $c_{k+1} = ... = c_m = 0$ .

So we have:  $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \ldots + c_k \vec{v}_k + c_{k+1} \vec{v}_{k+1} + \ldots + c_m \vec{v}_m = \vec{0}$  with the coefficients  $c_1, c_2, \ldots, c_m$  not all zero.

This means that the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m$  that define *T* are linearly dependent.