

10/19/18 Last time we discussed that shear coordinates transform under Quadrilateral Flips (of edge E_i) as

$$b_L(E_j; T') = \begin{cases} -b_L(E_i; T) & \text{if } j=i \\ b_L(E_j; T) + b_{ij} \cdot (b_L(E_i; T) \oplus 0) & \text{if } b_{ij} > 0 \\ b_L(E_j; T) - b_{ij} \cdot (-b_L(E_i; T) \oplus 0) & \text{if } b_{ij} < 0 \\ b_L(E_j; T) & \text{if } b_{ij} = 0 \end{cases}$$

where $(a \oplus b) = \max(a, b)$

$$\text{Trop}(1) = 0$$

$$\text{Trop}(x) = +$$

$$\text{Trop}(\oplus) = \oplus$$

Tropical analogue of χ -coord/cross-ratio transforms

Today we similarly define a tropical version of λ -lengths.

For any arc or boundary segment γ and certain Laminations L (Bounded, i.e. no spiralling into punctures)

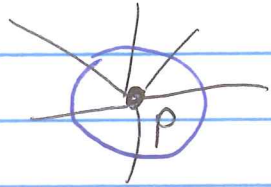
we define $a_2(\gamma) := \frac{\# \text{ crossings w/ } L \text{ w/ } \gamma}{2}$.

Rem: For technical reasons, we focus only on unpunctured marked surfaces (S, M) today.

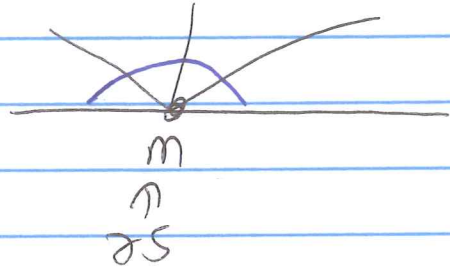
would need to use "opened surfaces" to deal w/ otherwise # of infinite crossings between L & γ if involving punctures.

(2)

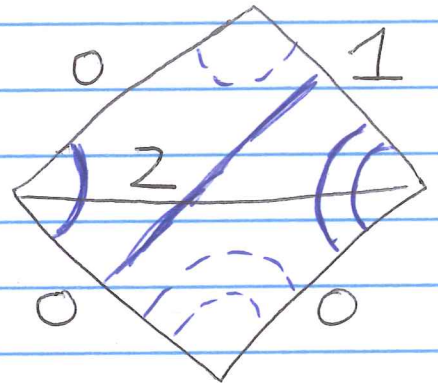
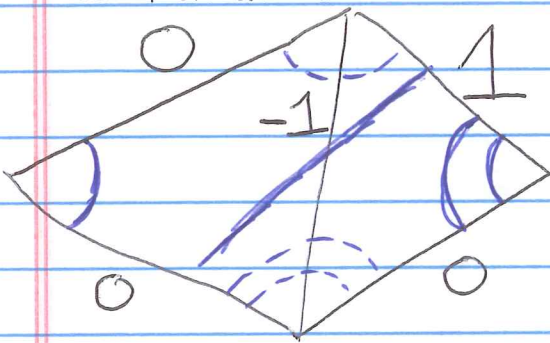
Furthermore, we allow our laminations to have negatively-valued weights on elem. laminations that were previously disallowed, e.g.,



or



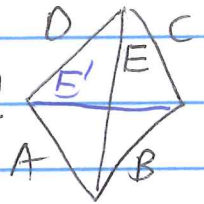
Eg. Given Lamination L on a Quadrilateral, with some negative weights (denoted as dashed curves), we obtain $a_L(\gamma)$'s as indicated.



Note that we can flip $E \rightarrow E'$ w/ same lamination
vertical horizontal
and get a new $a_L(E')$ but other values unchanged.

Claim: $a_L(\gamma)$'s satisfy Tropical Ptolemy Relation

$$a_L(E) + a_L(E') = \max(a_L(A) + a_L(C), a_L(B) + a_L(D))$$



Claim: Relation between $b_L(\gamma)$'s & $a_L(\gamma)$'s as tropical cross-ratio

$$b_L(E) = a_L(A) - a_L(B) + a_L(C) - a_L(D)$$

(3)

E.g. continued

$$-1 + 2 = \max(0+1, 0+0) \quad \checkmark$$

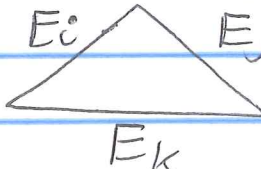
$$b_L(E_j; T) = +1 = 0 - 0 + 1 - 0 \quad \checkmark$$

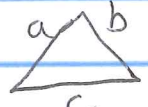
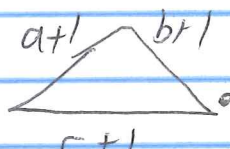
$$b_L(E'_j; T) = -1 = 0 - 0 + 0 - 1 \quad \checkmark$$

Additionally, can reconstruct L from arbitrary $\vec{a} \in \mathbb{Z}^{n+c}$
($n = |T|$, $c = \#$ boundary segments)
so that $a_L(E_i) = a_i$ for each $i \in \{1, 2, \dots, n+c\}$.

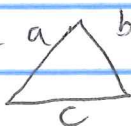
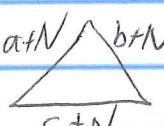
Step 1 (Assuming no self-folded triangles) For any $\vec{a} \in \mathbb{Z}^{n+c}$,
there exists $N \gg 0$ s.t. the triangle inequality

$$|\tilde{a}_i - \tilde{a}_j| \leq \tilde{a}_k \leq \tilde{a}_i + \tilde{a}_j \quad \left[\text{where } \tilde{a}_i = a_i + N \forall i \right]$$

satisfied for each  in $T \cup \{\text{Boundary Arcs}\}$.

Firstly, once  satisfies the triangle inequality,  so does

$$\left[|a-b| \leq c \leq a+b \Rightarrow |(a+1)-(b+1)| = |a-b| \leq c+1 \leq (a+1)+(b+1) = (a+b+1)+1 \right]$$

And if  doesn't satisfy triangle inequality, 

will for large enough N , since spread in inequalities widening.

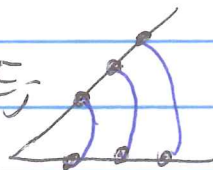
(4)

Step 2:

Given \tilde{a}_i 's [$\tilde{a}_i = a_i + N \forall i$] such that triangle inequalities satisfied, we place $2\tilde{a}_i$ points along each E_i .

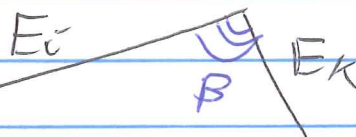
For each corner E_i opposite edge E_k ,

connect $(\tilde{a}_i + \tilde{a}_j - \tilde{a}_k)$ marked points on $E_i \& E_j$



Triangle inequality \Rightarrow this value ≥ 0 and leads to the unique configuration.

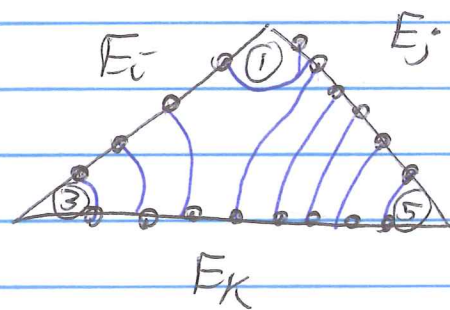
Then along edge E_i , we see



$$2\tilde{a}_i = \alpha + \beta$$

$$= (\tilde{a}_i + \tilde{a}_j - \tilde{a}_k) + (\tilde{a}_i + \tilde{a}_k - \tilde{a}_j) \quad \checkmark$$

E.g. $\tilde{a}_i = 2, \tilde{a}_j = 3, \tilde{a}_k = 4$



$$\tilde{a}_i + \tilde{a}_j - \tilde{a}_k = 1$$

$$\tilde{a}_i + \tilde{a}_k - \tilde{a}_j = 2$$

$$\tilde{a}_j + \tilde{a}_k - \tilde{a}_i = 5$$

We glue together full triangulation in this way.

step 3:

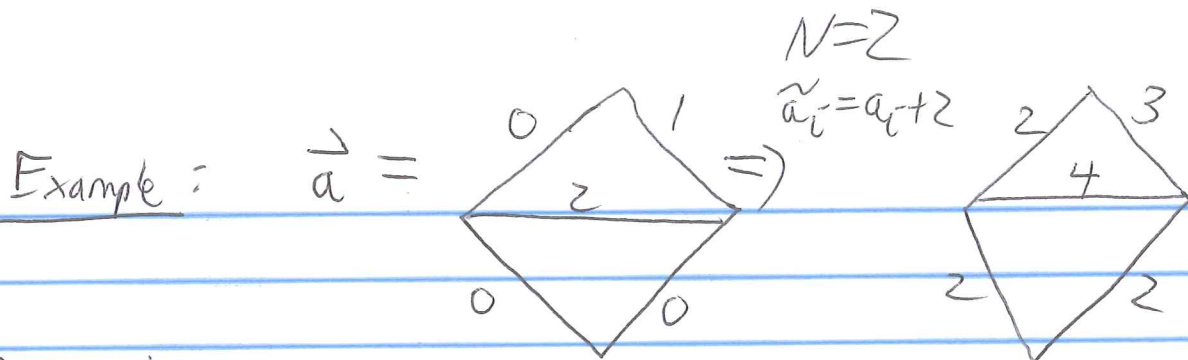
Lastly, we add in "negative" elem. laminations associated to boundary segments

to cancel out the parameter of N added to achieve triangle inequality everywhere.

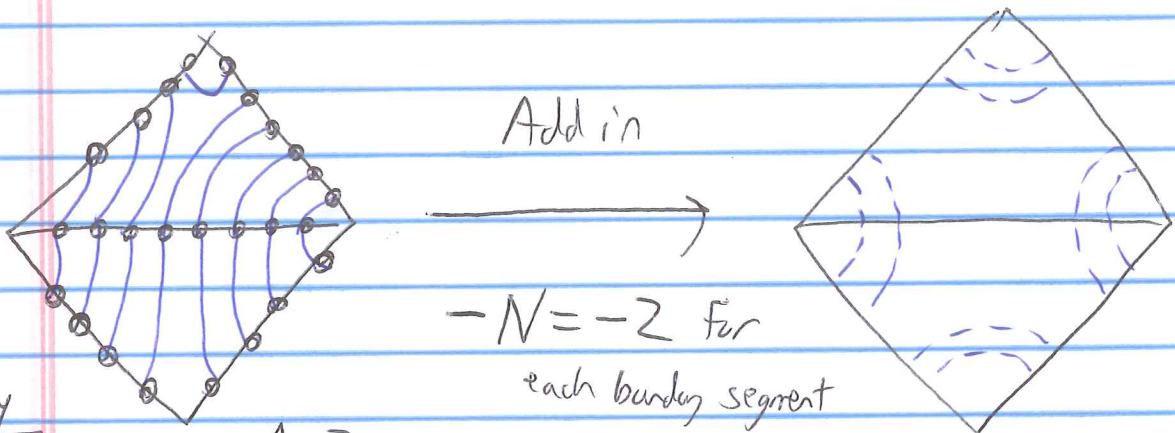


Positive & negative elem. laminations cancel each other out.

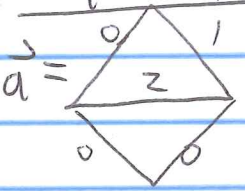
5



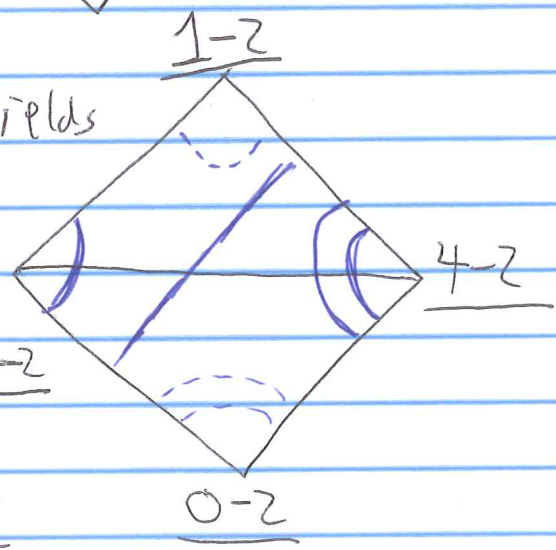
Building lamination according to step 2



Equivalently



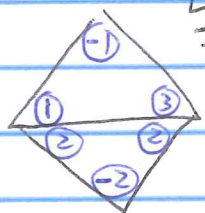
yields



agreeing w/
our running example.

yields

locally



using $(a_i + a_j - a_k)$'s

We now switch topics and next week see how cluster algebras relate to discrete integrable systems.

We begin with Y-system Dynamics. Historically, this was one of the first applications of Cluster Algebras and also is a natural bridge from our discussion of \mathcal{X} - and cross-ratio coordinates.

See Sections 3,3 or 6 of [GR18]

or Sections 3,3, 3,5, 3,6 of [FWZ].

⑥

We can ~~also~~ define Y -system associated to every cluster mimicing τ - or cross ratio coordinates

Def: For $n \times n$ B (or Q) initialize $\{Y_1, Y_2, \dots, Y_n\}$
Then define Y -mutation by (in k th direction)

$$Y_j' = \begin{cases} Y_k^{-1} & \text{if } j=k \\ Y_j \cdot (1 + Y_k)^{b_{jk}} & \text{if } j \neq k \ \& \ b_{jk} > 0 \\ Y_j \cdot \left(1 + \frac{1}{Y_k}\right)^{b_{jk}} & \text{if } j \neq k \ \& \ b_{jk} < 0 \\ Y_j & \text{if } j \neq k \ \& \ b_{jk} = 0 \end{cases}$$

Rem: Equivalent to write $Y_j' = Y_j \cdot Y_k^{[-b_{jk}]_+} (1 + Y_k)^{b_{jk}}$
 since $\frac{1 + Y_k}{Y_k} = \left(1 + \frac{1}{Y_k}\right)$ (for $b_{jk} < 0$) for $j \neq k$

Claim: Given $(n+m)$ -by- n extended exchange matrix B
 and letting $\hat{Y}_j = \prod_{i=n+1}^{n+m} X_i^{b_{ij}}$, then

$$\mu_k \left((\hat{Y}_1, \dots, \hat{Y}_n), B \right) = \left((\hat{Y}_1', \dots, \hat{Y}_n'), B' \right)$$

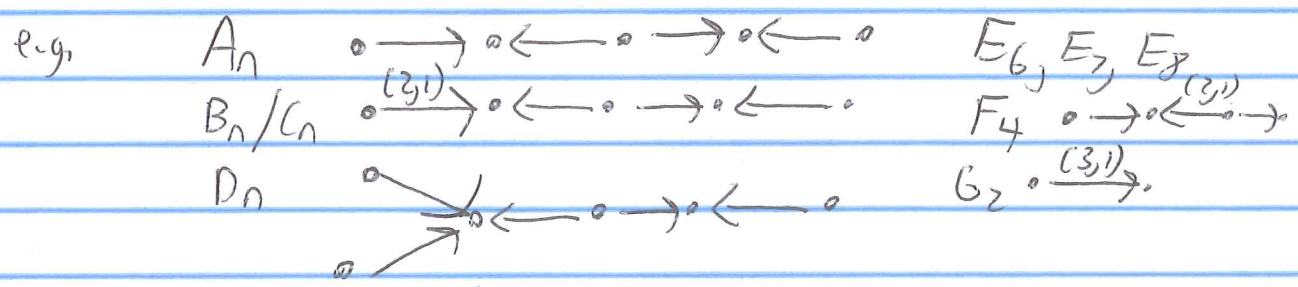
given by Y -mutation

where we define \hat{Y}_j' using new cluster var X_k' & matrix B' exchange i

PF: Essentially the τ -coordinate change-of-basis from earlier.

⑦ Zamolodchikov Periodicity (Conjecture until Fomin-Zelevinsky '02)

Let Q be an oriented Dynkin Diagram (oriented in alternating or bipartite fashion)



Color vertices black/white if source/sink.

Mutate at all sources first, then all sinks, then iterate

yields $Y_{i,t+1} Y_{i,t-1} = \prod_{j \neq i} (Y_{j,t} + 1)^{-a_{ij}}$ is periodic.

(where $[a_{ij}] =$ Cartan matrix of assoc. root system
i.e. $a_{ij} = -|b_{ij}|$ for $i \neq j$)

periodic of order $2(h+2)$ w/ $h =$ Coxeter # assoc. to Dynkin Diagram/root system.

E.g. $Q = 1 \rightarrow 2$ (Type A_2) $u_1, u_2, u_1, u_2, \dots$

($h=3$ in this case)

	$t=0$	$t=1$	$t=2$	$t=3$	$t=4$	$t=5$
$Y_{1,t}$	Y_1	Y_1^{-1}	Y_2	$\frac{Y_1 Y_2 + Y_1 + 1}{Y_2}$	Y_2^{-1}	Y_2
$Y_{2,t}$	Y_2	$\frac{Y_1 Y_2}{Y_1 + 1}$	$\frac{Y_1 + 1}{Y_1 Y_2}$	$\frac{Y_1(Y_2 + 1)}{Y_1(Y_2 + 1)}$	$Y_1(Y_2 + 1)$	Y_1

⑧ We see $Y_{z, \text{odd}} Y_{z, \text{odd}+2} = \left(Y_{z, \text{odd}+1}^{+1} + 1 \right)^{+1}$

$$Y_{z, \text{even}} Y_{z, \text{even}+2} = \left(Y_{z, \text{even}+1}^{+1} + 1 \right)^{+1}$$

$$Y_{z, \text{even}} Y_{z, \text{even}+2} = \left(Y_{z, \text{even}+1}^{-1} + 1 \right)^{-1}$$

$$Y_{z, \text{odd}} Y_{z, \text{odd}+2} = \left(Y_{z, \text{odd}+1}^{-1} + 1 \right)^{-1}$$

e.g.,

$$Y_{1,0} Y_{1,3} = \left(\frac{1}{Y_1} \right) \left(\frac{Y_1 Y_2 + Y_1 + 1}{Y_2} \right) = \left(Y_{2,2} + 1 \right)$$

\parallel
 $\frac{Y_1 + 1}{Y_1 Y_2}$

$$Y_{2,0} Y_{2,2} = Y_2 \left(\frac{Y_1 + 1}{Y_1 Y_2} \right) = \left(Y_{1,1} + 1 \right) = \left(\frac{1}{Y_1} + 1 \right)$$

$$Y_{1,0} Y_{1,2} = Y_1 \left(\frac{Y_2}{Y_1 Y_2 + Y_1 + 1} \right) = \left(Y_{2,1}^{-1} + 1 \right)^{-1} = \left[\frac{Y_1 + 1}{Y_1 Y_2} + 1 \right]^{-1}$$

$$Y_{2,1} Y_{2,3} = \frac{Y_1 Y_2}{Y_1 + 1} \cdot \frac{1}{Y_1 (Y_2 + 1)} = \left(Y_{1,2}^{-1} + 1 \right)^{-1} = \left[\frac{Y_1 Y_2 + Y_1 + 1}{Y_2} + 1 \right]^{-1}$$