

## Corrections to the First Printing of

Olver, P.J., *Applications of Lie Groups to Differential Equations*,  
Second Edition, Springer–Verlag, New York, 1993.

Last updated: May 7, 2019

\*\*\* On page 5, lines 24–27, change

Thus  $T^2$  can be covered by two coordinate charts

$$U_1 = \{(\theta, \rho) : 0 < \theta < 2\pi, 0 < \rho < 2\pi\},$$

$$U_2 = \{(\theta, \rho) : \pi < \theta < 3\pi, \pi < \rho < 3\pi\},$$

with overlap function ...

to

Thus  $T^2$  can be covered by three coordinate charts, e.g.

$$U_1 = \{(\theta, \rho) : 0 < \theta < 2\pi, 0 < \rho < 2\pi\},$$

$$U_2 = \{(\theta, \rho) : \pi < \theta < 3\pi, \pi < \rho < 3\pi\},$$

$$U_3 = \{(\theta, \rho) : \frac{1}{2}\pi < \theta < \frac{5}{2}\pi, \frac{1}{2}\pi < \rho < \frac{5}{2}\pi\}.$$

The first overlap function is ...

\*\*\* On page 10, line 6, change

$$\phi \circ \tilde{\phi}^{-1} : \mathbb{R} \rightarrow \mathbb{R}$$

to

$$\phi^{-1} \circ \tilde{\phi} : \mathbb{R} \rightarrow \mathbb{R}$$

\*\*\* On page 19, line 17, change

$$x \in V_0 = \{x : |x| < \frac{1}{2}\}$$

to

$$x \in V_0 = \{-1 < x < \frac{1}{3}\}$$

\*\*\* On page 36, line 9, change

for all  $\varepsilon, \theta \in \mathbb{R}$ ,  $x \in M$ , such that both sides are defined, if and only if

to

for all  $x \in M$ , and  $(\varepsilon, \theta) \in V$ , where  $V \subset \mathbb{R}^2$  is a connected open subset containing  $(0, 0)$  such that both sides of (1.34) are defined at all points therein, if and only if

\*\*\* On page 37, lines 7–9, change

... plane:

$$V = \{(\theta, \varepsilon) : \text{both sides of (1.34) are defined at } (\theta, \varepsilon)\}$$

and

$$U = \{(\theta, \varepsilon) : \text{both sides of (1.34) are defined and equal at } (\theta, \varepsilon)\}$$

to

... plane: first  $V$  is the connected component of

$$\widehat{V} = \{(\theta, \varepsilon) : \text{both sides of (1.34) are defined at } (\theta, \varepsilon)\}$$

containing the origin; second  $U = \widehat{U} \cap V$ , where

$$\widehat{U} = \{(\theta, \varepsilon) : \text{both sides of (1.34) are defined and equal at } (\theta, \varepsilon)\}$$

\*\*\* On page 37, line 10, delete the sentence

Note that  $U \subset V$ , and that  $V$  is a connected subset of the  $(\theta, \varepsilon)$  plane.

\*\*\* On page 37, line 14, add the following sentence after the final  $U = V$ .

*Warning:* It is not, in general, true that  $\widehat{U} = \widehat{V}$ !

**Remark:** The preceding corrections are because Theorem 1.34 had a subtle flaw in it, first pointed out to me by James Devlin. The following exercise gives a counterexample to the original version. More details can be found in my paper: Olver, P.J., Non-associative local Lie groups, *J. Lie Theory* **6** (1996) 23–51. Thanks also to Hans Lundmark for comments.

**Exercise:** Let  $M = \{(r, \theta) \mid r > 0\}$ . Prove that the two vector fields

$$\mathbf{v} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}, \quad \mathbf{w} = \sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta},$$

commute,  $[\mathbf{v}, \mathbf{w}] = 0$  on  $M$ , but their flows do not globally commute. *Hint:* Consider  $r, \theta$  as polar coordinates.

\*\*\* On page 43, line 23, change

smoth vector fields

to

smooth vector fields

\*\*\* On page 52, Example 1.58, change

Lie proved that

to

Lie proved, [4], that

\*\*\* On page 64, line 10, delete the middle terms between the two = signs. Thus, the equation should read

$$\exp(\varepsilon \mathbf{v}_0)^* [\omega|_{\exp(\varepsilon \mathbf{v}_0)x}] = \sum_I \alpha_I(e^\varepsilon x) e^{k\varepsilon} dx^I,$$

\*\*\* On page 64, line 18, change

to 
$$\int_{\log \varepsilon}^1$$

to 
$$\int_{\exp \varepsilon}^1$$

\*\*\* On page 64, line 19, change

$$\lambda = \log \tilde{\varepsilon}$$

to 
$$\lambda = e^{\tilde{\varepsilon}}$$

\*\*\* On page 67, line 15, change

sort

to

short

\*\*\* On page 70, Exercise 1.8, change

in polar coordinates,

to

in polar coordinates with  $r > 0$ ,

\*\*\* On page 72, Exercise 1.24(b), change

$\mathfrak{h} \subset \mathfrak{g}$  has the property

to

$\mathfrak{h} \subset \mathfrak{g}$  is a *normal subalgebra* (or *ideal*), meaning that it has the property

\*\*\* On pages 79–81, the ends of the proofs of Proposition 2.6 and Theorem 2.8 that refer back to (1.40) are subtly flawed, in that, under our definition of a local group action, even when  $g = g_1 \cdot g_2$  with  $g, g_1, g_2 \in G_x$ , there is no guarantee that  $g_1 \in G_{g_2 \cdot x}$ , i.e., that  $g_1 \cdot (g_2 \cdot x)$  is defined even though  $g \cdot x = (g_1 \cdot g_2) \cdot x$  is defined.

However, a more direct argument, that avoids this difficulty, is to replace the end of the proof of Proposition 2.6 by the following:

... Conversely, if (2.1) holds everywhere, then

$$\frac{d}{d\varepsilon} \zeta(\exp(\varepsilon \mathbf{v})x) = 0$$

where defined, and hence  $\zeta(\exp(\varepsilon \mathbf{v})x) = \zeta(x) = c$  is constant for  $\varepsilon$  in the connected interval containing 0 in  $\{\varepsilon \in \mathbb{R} \mid \exp(\varepsilon \mathbf{v}) \in G_x\}$ . Using the fact that the exponential map is a local diffeomorphism from a neighborhood of  $0 \in \mathfrak{g}$  to a neighborhood of  $e \in G_x$ , we conclude that  $\zeta(g \cdot x) = c$  for all  $g$  in an open neighborhood of the identity in  $G_x$ . Now, set  $\tilde{G}_x = \{g \in G_x \mid \zeta(g \cdot x) = c\}$ . Applying the preceding argument at the point  $g \cdot x$  for any  $g \in \tilde{G}_x$  proves that  $\tilde{G}_x$  is open, while continuity proves that it is closed in  $G_x$ . Thus, by connectivity,  $\tilde{G}_x = G_x$ , and the result follows.  $\square$

*Similarly, replace the end of the proof of Theorem 2.8 by:*

... We have thus shown that if  $x_0$  is a solution to  $F(x) = 0$ , and  $\mathbf{v}$  is an infinitesimal generator of  $G$ , and  $\varepsilon$  is sufficiently small, then  $\exp(\varepsilon \mathbf{v})x_0$  is also a solution. As in the proof of Proposition 2.6, one then shows that  $\tilde{G}_x = \{g \in G_x \mid F(g \cdot x_0) = 0\}$  is both open and closed in  $G_x$ , and hence, by connectivity,  $\tilde{G}_x = G_x$ .  $\square$

- *Thanks to Colin James Stockdale Klaus for correspondence on this point.*

\*\*\* *On page 83, line 14, change*

following

to

following

\*\*\* *On page 93, line 8, change*

functon

to

function

\*\*\* *On page 106, line -5, the term inside the parentheses should be  $\Xi_\varepsilon(x)$ . Thus, the equation should read*

$$\sum_l \frac{\partial^2 \Xi_\varepsilon^k}{\partial \tilde{x}^j \partial \tilde{x}^l} (\Xi_\varepsilon(x)) \frac{d \Xi_\varepsilon^l}{d\varepsilon}(x) = 0,$$

\*\*\* *On page 111, line 3, change*

$J\tilde{f}_\varepsilon(x)$

to

$J\tilde{f}_\varepsilon(\tilde{x})$

\*\*\* *On page 113, line 4, change*

$\xi = u$

to

$\xi = -u$

\*\*\* On page 123, line 5, change

$\tau \frac{\partial}{\partial \tau}$   
to

$\tau \frac{\partial}{\partial t}$

\*\*\* On page 151, line after (2.110), change

normal subalgebra of  $\mathfrak{g}$

to

normal subalgebra (ideal) of  $\mathfrak{g}$

\*\*\* On page 163, line -3, change

differential equatons

to

differential equations

\*\*\* On page 167, line 2, change

$\binom{p+k-1}{k} \cdot l$

to

$\binom{p+k}{k} \cdot l$

\*\*\* On page 167, Definition 2.83, change

differential equatons

to

differential equations

\*\*\* On page 169, line -9, change

Exercise 2.32

to

Exercise 2.33

- Thanks to Mariano Hermida de La Rica for the preceding four corrections.

\*\*\* On page 187, line 8, change

with respect  $y$

to

with respect to  $y$

\*\*\* On page 187, line 14, change

$$\frac{\partial \delta}{\partial \hat{x}} + \frac{\partial \delta}{\partial y} \frac{\partial \eta}{\partial x} + \frac{\partial \delta}{\partial v} \frac{\partial v}{\partial y} \frac{\partial \eta}{\partial x}$$

to

$$\frac{\partial \delta}{\partial \hat{x}} \frac{\partial \hat{x}}{\partial x} + \frac{\partial \delta}{\partial y} \frac{\partial \eta}{\partial x} + \frac{\partial \delta}{\partial v} \frac{\partial v}{\partial y} \frac{\partial \eta}{\partial x}$$

- Thanks to Wen-xiu Ma and his class for catching this and several other errors.

\*\*\* On page 197, line -10, change

SO(3)–invariant solutions exist.

to

SO(3)–invariant solutions can be constructed by this technique.

\*\*\* On page 202, lines 13–14, change

linear system of ordinary differential equations,

to

linear, constant coefficient system of ordinary differential equations,

\*\*\* On page 207, line -2, change

Example 2.64

to

Example 2.44

\*\*\* On page 212, on both line 12 and line 13, change

$M/G$

to

$M/G^2$

\*\*\* On page 214, line 13, change

$$\tilde{F}(x) = F[\pi(x)]$$

to

$$F(x) = \tilde{F}[\pi(x)]$$

\*\*\* On page 215, line -1, change

$$\tilde{F} = \tilde{F}(\pi_1, \dots, \pi_{m-s})$$

to

$$\tilde{F} = \hat{F}(\pi_1, \dots, \pi_{m-s})$$

\*\*\* On page 217, line 6, change

$$F(R, K) = 0$$

to

$$\widehat{F}(R, K) = 0$$

\*\*\* On page 238, Exercise 3.7, change the formula to

$$R = \left( \frac{t^2 E}{p_0} \right)^{1/5} h \left[ p_0 \left( \frac{t^6}{\rho_0^3 E^2} \right)^{1/5} \right]$$

- Thanks to Kameron Decker Harris for spotting this.

\*\*\* On page 273, line -7, change

tecniq

to

technique

\*\*\* On page 280, in the table, change

$$I_x = xD - yA + \frac{1}{2} x u u_t + t M_x$$

to

$$I_x = xD + yA + \frac{1}{2} x u u_t + t M_x$$

- Thanks to Gehrt Hartjen for checking through this table and the table on page 340 in his *Mathematics Diplomarbeit in Aachen, 2001*.

\*\*\* On page 285, line 5, change

4.13. (a)

to

\*\* 4.13. (a)

\*\*\* On page 285, line 7, change

Prove that the reduced system  $\Delta/G$  for the  $G$ -invariant solutions of  $\Delta$  is also the Euler-Lagrange equations for some variational problem on the quotient manifold  $M/G$ . Does this generalize to nonvariational symmetry groups?

to

Is the reduced system  $\Delta/G$  for the  $G$ -invariant solutions of  $\Delta$  necessarily the Euler-Lagrange equations for some variational problem on the quotient manifold  $M/G$ ? See I.M. Anderson and M. Fels, Symmetry reduction of variational bicomplexes and the principle of symmetric criticality, *Amer. J. Math.* **119** (1997) 609–670, for details.

\*\*\* On page 290, line -4, change

Exercise 2.33

to

Exercise 2.35

\*\*\* On page 323, line -8 change

a third order evolution equation is integrable

to

a third order evolution equation in which  $u_{xxx}$  occurs linearly is integrable

\*\*\* On page 328, line 10, change

Bluman and Kumei, [3],

to

Bluman and Kumei, [2],

\*\*\* On page 331, insert minus sign after equals sign in second displayed equation:

$$D_{\Delta}^* Q = -q_t - q_{xx} + u q_x$$

\*\*\* On page 340, in line 4 of the table, change

$$-y u_{xxx} + x u_{xyy} + u_{xy}$$

to

$$-y u_{xxx} + x u_{xxy} + u_{xy}$$

\*\*\* On page 340, in line 5 of the table, change

$$u_{xx}(y u_{yt} + \frac{1}{2} u_t) - u_{yy}(x u_{xt} + \frac{1}{2} u_t)$$

to

$$-u_{xx}(y u_{yt} + \frac{1}{2} u_t) + u_{yy}(x u_{xt} + \frac{1}{2} u_t)$$

\*\*\* On page 350, lines -8 to -7, change

the their Fréchet

to

their Fréchet

\*\*\* On page 364, Theorem 5.92, first line, change

$$P[u] \in \mathcal{A}^p$$

to

$$P[u] \in \mathcal{A}^q$$

- Thanks to Thomas von Schroeter for spotting this.



\*\*\* On page 366, line -7, change

$J \setminus I$

to

$I \setminus J$

- Thanks to Rob Thompson for catching this and several other errors.

\*\*\* On page 381, Exercise 3.16a:

The system does not, in fact have a recursion operator, although there is a recursive formula for generating the higher order symmetries. On the other hand, the related system

$$u_t = u_{xx} + v^2, \quad v_t = v_{xx},$$

does admit a recursion operator. Details can be found in: Beukers, F., Sanders, J.A., and Wang, J.P., On integrability of systems of evolution equations, *J. Diff. Eq.* **172** (2001), 396-408.

\*\*\* On page 381, Exercise 3.16b:

A proof that the Bakirov system has only one generalized symmetry can now be found in: Beukers, F., Sanders, J.A., and Wang, J.P., One symmetry does not imply integrability, *J. Diff. Eq.* **146** (1998), 251-260.

\*\*\* On page 397, equation (6.17), change closing } to ) :

$$\{F, H\}(x) = \langle x; [\nabla F(x), \nabla H(x)] \rangle, \quad x \in \mathfrak{g}^*, \quad (6.17)$$

\*\*\* On page 420, line -8, change

rocedure.

to

procedure.

\*\*\* On page 427, lines 23-24, change

Recently, Weinstein, [3], proposed the less historically motivated term “Casimir function” for these objects, ...

to

Recently, R. Littlejohn, *AIP Conference Proc.* **88** (1982), 47-66, and A. Weinstein, *AIP Conference Proc.* **88** (1982), 1-11, and [3], have proposed the less historically motivated term “Casimir function” for these objects, ...

- Thanks to Phil Morrison for alerting me to these earlier references.

\*\*\* On page 469, change title of second reference by H. Bateman to

On dissipative systems and related variational principles

\*\*\* On page 480, line 2 change

*Leipz. Berich.* **1** (1895)

to

*Leipz. Berichte* **47** (1895)

\*\*\* On page 480, line 5 change

*Leipz. Berich.* **3** (1897)

to

*Leipz. Berichte* **49** (1897)