

Corrections to

Hoff, D., and Olver, P.J., Extensions of invariant signatures for object recognition, *J. Math. Imaging Vision* **45** (2013), 176–185 .

Last updated: September 6, 2013.

★ Page 181: In formula (11) replace $h(\sigma^i, \tilde{S}^\Delta)$ by $p(\sigma^i, \tilde{S}^\Delta)$:

$$p(S^\Delta, \tilde{S}^\Delta) = \frac{\sum_{i=1}^N h(\sigma^i, \tilde{S}^\Delta) |\kappa^i|^\alpha}{\sum_{i=1}^N |\kappa^i|^\alpha} \quad (11)$$