

(145)

PROPOSITION: If  $V \xrightarrow{T} W$  had matrix  $A$  w.r.t. <sup>basis</sup>  $B = (v_1, \dots, v_n)$   
 $(a_{ij}) \in F^{n \times n}$

(4, 3, 5)

then w.r.t. a new basis  $B' = (v'_1, \dots, v'_n)$

that has  $v'_j = \sum_{i=1}^n p_{ij} v_i$  for  $P = (p_{ij}) \in GL_n(F)$ ,  
 as change-of-basis matrix

$T$  will have matrix  $A' = P^{-1}AP$  i.e. conjugation of  $A$  by  $P$ .  
 (similarity transformation)

12/10/2018 &gt;

proof: Follows from what we did, but let's just do a sanity check.

$$\text{we have } T(v_j) = \sum_{i=1}^n a_{ij} v_i$$

for  $j=1, \dots, n$

$$\text{and also } v_j = \sum_{i=1}^n p_{ij}^{-1} v_i,$$

$$\text{so } T(v'_j) = T\left(\sum_{i=1}^n p_{ij}^{-1} v_i\right) = \sum_{i=1}^n p_{ij}^{-1} T(v_i)$$

$$= \sum_{i=1}^n p_{ij}^{-1} \sum_{k=1}^n a_{ki} v_k$$

$$= \sum_{i=1}^n p_{ij}^{-1} \sum_{k=1}^n a_{ki} \sum_{l=1}^n p_{lk} v'_l$$

$$= \sum_{l=1}^n \left( \sum_{k=1}^n \sum_{i=1}^n p_{lk}^{-1} a_{ki} p_{ij} \right) v'_l, \text{ as desired} \blacksquare$$

$(P^{-1}AP)_{lj}$

So the idea of §4.4, 4.5, 4.6<sup>4.7</sup> is to figure out how to make  
 particularly useful changes-of-basis  $B \rightsquigarrow B'$

so that  $A \rightsquigarrow PAP^{-1}$  becomes  
 particularly simple.

(146) § 4.4, 4.5 Eigenvectors & diagonalization

Q: When we can pick a basis for  $V$  that makes  $V \xrightarrow{T} V$  having matrix that is diagonal  $A = \begin{matrix} & v_1 & v_2 & \dots & v_n \\ \begin{matrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{matrix} & \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \end{matrix}$  ?

A: This would mean  $T(v_i) = \lambda_i v_i$  for  $i=1, 2, \dots, n$ , that is,  $V$  has a basis  $B = (v_1, \dots, v_n)$  of eigenvectors for  $T$ ...

DEFIN: One says  $v \in V$  is an eigenvector for  $T: V \rightarrow V$  with eigenvalue  $\lambda$  if  $Tv = \lambda v$  (and  $v \neq 0$ !)

Thus we noted above  $T$  or its matrix  $A$  is diagonalizable, meaning  $\exists$  a basis  $B = (v_1, \dots, v_n)$  for  $V$  which is diagonal  $\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$  (or equivalently  $\exists P \in GL_n(F)$  with  $P^{-1}AP = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$ )  
 $\iff V$  has a basis of eigenvectors for  $T$

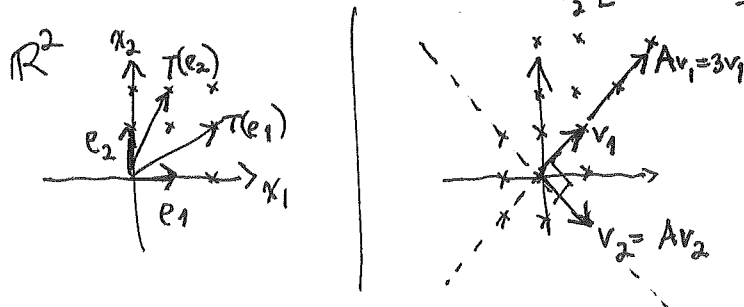
EXAMPLES: ①  $\mathbb{R}^2 \xrightarrow{A} \mathbb{R}^2$  has  $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

satisfying  $Av_1 = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 3v_1$

$Av_2 = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 1 \cdot \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 1 \cdot v_2$

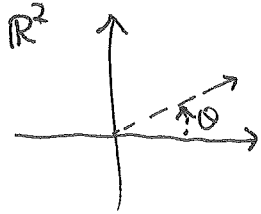
and hence in the new basis  $B' = (v_1, v_2)$  one has  $P = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \in GL_2(\mathbb{R})$

satisfying  $A' = P^{-1}AP = \begin{matrix} & v_1 & v_2 \\ \begin{matrix} v_1 \\ v_2 \end{matrix} & \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \end{matrix}$ . This makes  $A'$ 's action on  $\mathbb{R}^2$  easier to understand:



(147) ② Sometimes  $A \in F^{n \times n}$  is not diagonalizable until you pass to a bigger field  $\bar{F} \supset F$  where eigenvalues/eigenvectors exist!

e.g.  $\mathbb{R}^2 \xrightarrow[A \in \mathbb{R}^{2 \times 2}]{\neq} \mathbb{R}^2$  has no eigenvectors in  $\mathbb{R}^2$  (unless  $\theta = 0$  or  $\pi$ )

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$


but if we think of  $A_\theta \in \mathbb{C}^{2 \times 2}$ , then it becomes diagonalizable:

$$v_1 = \begin{bmatrix} i \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$\text{have } Av_1 = \begin{bmatrix} i \cos \theta - \sin \theta \\ i \sin \theta + \cos \theta \end{bmatrix} = \begin{bmatrix} i e^{i\theta} \\ e^{i\theta} \end{bmatrix} = e^{i\theta} \begin{bmatrix} i \\ 1 \end{bmatrix} = e^{i\theta} v_1$$

$$Av_2 = \begin{bmatrix} -i \cos \theta - \sin \theta \\ -i \sin \theta + \cos \theta \end{bmatrix} = \begin{bmatrix} -i e^{-i\theta} \\ e^{-i\theta} \end{bmatrix} = e^{-i\theta} \begin{bmatrix} -i \\ 1 \end{bmatrix} = e^{-i\theta} v_2$$

$$\text{so } P = \begin{bmatrix} | & | \\ v_1 & v_2 \\ | & | \end{bmatrix} = \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix} \in GL_2(\mathbb{C}) \text{ satisfies}$$

$$P^{-1}AP = \begin{matrix} v_1 & v_2 \\ \begin{bmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{bmatrix} \end{matrix}, \text{ diagonal in } \mathbb{C}^{2 \times 2}$$

③ Sometimes  $A$  will not be diagonalizable, even after enlarging  $F$  to  $\bar{F}$

e.g.  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \in \mathbb{R}^{2 \times 2} \subset \mathbb{C}^{2 \times 2}$  is diagonalizable nowhere, but at least its upper triangular (so triangulizable, i.e.  $P^{-1}AP = \begin{bmatrix} \lambda_1 & * \\ 0 & \lambda_2 \end{bmatrix}$ )

Let's understand this better, with three goal theorems in mind:

THEOREM: Every linear map  $\mathbb{C}^n \xrightarrow{T} \mathbb{C}^n$  can be triangulized:  $T = \begin{matrix} v_1 & \dots & v_n \\ \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & * \\ & & \ddots & \\ 0 & & & \lambda_n \end{bmatrix} \\ \vdots & & & \end{matrix}$

(PROP. 4.6.1)

THEOREM: "Most" linear maps  $\mathbb{C}^n \xrightarrow{T} \mathbb{C}^n$  can be diagonalized, at least those for which  $P_T(t) = \det(tI - A) = (t - \lambda_1)(t - \lambda_2) \dots (t - \lambda_n)$  has distinct roots  $\lambda_1, \dots, \lambda_n$

(4.6.6)

(any matrix for  $T$ )

("Spectral") THEOREM: If  $A \in \mathbb{R}^{n \times n}$  is symmetric then  $\exists$  real eigenvalues  $\lambda_1, \dots, \lambda_n$  and an orthogonal matrix  $P = (P^T)^{-1}$  in  $GL_n(\mathbb{R})$  with  $P^{-1}AP = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$

(8.6.10)

$P^TAP = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$

(148) The key tool is that eigenvalues are roots of  $p_A(t)$ :

DEFIN: Given  $V \xrightarrow{T} V$ , its characteristic polynomial is

$$\begin{array}{ccc} & & \\ \uparrow & & \uparrow \\ F^n & \xrightarrow{A} & F^n \end{array}$$

$$\begin{aligned} p_A(t) &:= \det(tI_n - A) \\ &= \det \begin{bmatrix} t-a_{11} & -a_{12} & \dots & -a_{1n} \\ -a_{21} & t-a_{22} & & \\ \vdots & & \ddots & \\ -a_{n1} & & & t-a_{nn} \end{bmatrix} \\ &= t^n - \underbrace{(a_{11} + \dots + a_{nn})}_{\text{Trace}(A)} t^{n-1} + \dots + (-1)^n \det A \end{aligned}$$

a polynomial in  $t$

NOTE:  $p_A(t)$  depends only on  $T$ , since if we change bases,

we get  $A' = P^{-1}AP$  with  $\det(tI_n - P^{-1}AP)$

$$\begin{aligned} &= \det(P^{-1}(tI_n)P - P^{-1}AP) \\ &= \det(P^{-1} \cdot (tI_n - A) \cdot P) \\ &= \det(P^{-1}) \cdot \det(tI_n - A) \cdot \det(P) \\ &= \det(tI_n - A) \end{aligned}$$

PROPOSITION:  $\lambda \in F$  is an eigenvalue for  $T \iff t = \lambda$  is a root of  $p_A(t) = 0$   
 (say with an eigenvector  $v \neq 0$ )  $Tv = \lambda v$  (and  $v \in \ker(AI_n - A)$ )

proof:  $Tv = \lambda v$  for some  $v \neq 0$  in  $V$

$$\iff Av = \lambda v \quad \text{--- " ---}$$

$$\iff \lambda v - Av = 0 \quad \text{--- " ---}$$

$$\iff (\lambda I_n - A)v = 0 \quad \text{--- " ---}$$

$$\iff \lambda I_n - A \text{ is noninvertible in } F^{n \times n}$$

$$\iff \det(\lambda I_n - A) = 0 \quad \text{i.e. } t = \lambda \text{ is a root of } \det(tI - A) =: p_A(t) \quad \blacksquare$$