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proof: For (i), if P is invertible and $P^{-1} = (p_{ij}^{-1})$ then $\{v_1', \dots, v_n'\}$ span V

$$\text{since } \sum_{i=1}^n p_{ij}^{-1} v_i' = \sum_{i=1}^n p_{ij}^{-1} \left(\sum_{k=1}^n p_{ki} v_k \right) = \sum_{k=1}^n \underbrace{\left(\sum_{i=1}^n p_{ki} p_{ij}^{-1} \right)}_{(P \cdot P^{-1})_{kj} = I_{kj}} v_k = v_j$$

and this is reversible: if $\{v_1', \dots, v_n'\}$ span V

$$\text{then } \exists (q_{ij}) \text{ with } v_j = \sum_{i=1}^n q_{ij} v_i' = \sum_{i=1}^n q_{ij} \left(\sum_{k=1}^n p_{ki} v_k \right) = \sum_{k=1}^n \underbrace{\left(\sum_{i=1}^n p_{ki} q_{ij} \right)}_{\substack{\text{must be} \\ \begin{cases} 1 & \text{if } k=j \\ 0 & \text{else} \end{cases}}} v_k$$

since v_1, \dots, v_n are independent

$$\text{Thus } Q = (q_{ij}) = P^{-1}.$$

So $\{v_1', \dots, v_n'\}$ span $V \iff P$ invertible

hence they're a basis $\iff P$ invertible (since $\dim V = n$)

For (ii), if $v \in V$ has coordinates x for B

$$\text{then } v = x_1 v_1 + \dots + x_n v_n = \sum_{i=1}^n x_i v_i$$

and hence $x' = P^{-1}x$ has

$$\begin{aligned} x_1' v_1' + \dots + x_n' v_n' &= \sum_{i=1}^n x_i' v_i' = \sum_{i=1}^n \left(\sum_{j=1}^n p_{ij}^{-1} x_j \right) \left(\sum_{k=1}^n p_{ki} v_k \right) \\ &= \sum_{k=1}^n \left(\sum_{j=1}^n \underbrace{\left(\sum_{i=1}^n p_{ki} p_{ij}^{-1} \right)}_{(P \cdot P^{-1})_{kj} = I_{kj}} x_j \right) v_k \\ &= \sum_{k=1}^n x_k v_k = v \quad \blacksquare \end{aligned}$$

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EXAMPLE: For $V = \{ \text{solutions to } y'' + y = 0 \}$,

instead of fundamental solutions $y_1 = \cos(t)$ as $B = (y_1, y_2)$
 $y_2 = \sin(t)$

one might learn $y'' + y = 0$ has characteristic equation $r^2 + 1 = 0$
 $(r-i)(r+i) = 0$

with roots $r_1, r_2 = \pm i$

different
 and hence a basis of solutions $B' = (e^{it}, e^{it})$
 $= (e^{it}, e^{-it})$.

To check this, Euler's equation $e^{i\theta} = \cos\theta + i\sin\theta$ lets one write

~~$$e^{it} = \cos(t) + i\sin(t) = y_1 + iy_2$$~~

$$e^{-it} = \cos(t) - i\sin(t) = y_1 - iy_2$$

$$\leadsto P = \overset{B'}{\underset{B}{\begin{bmatrix} \cos(t) & \sin(t) \\ 1 & i \\ 1 & -i \end{bmatrix}}} \leftarrow \text{base change matrix from } B \text{ to } B' \text{ invertible!}$$

$$\text{Since } P^{-1} = \frac{1}{-2i} \begin{bmatrix} -i & -1 \\ -i & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -i \\ 1 & i \end{bmatrix},$$

given $y = x_1 \cos(t) + x_2 \sin(t)$ with coordinates $\underline{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ in B ,

it will have $y = x'_1 e^{it} + x'_2 e^{-it}$ that is coordinates $\underline{x}' = \begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix}$ in B'

$$\text{where } \underline{x}' = \begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix} = P^{-1} \underline{x} = \frac{1}{2} \begin{bmatrix} 1 & -i \\ 1 & i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}(x_1 - ix_2) \\ \frac{1}{2}(x_1 + ix_2) \end{bmatrix}.$$

Chap. 4 Linear transformations

§ 4.1 The dimension formula

Recall $V \xrightarrow{T} W$ a map between F -vector spaces V, W

is linear if $T(v_1+v_2) = T(v_1) + T(v_2)$
 $T(cv) = cT(v)$

DEFIN: $\ker(T) := \{v \in V : T(v) = 0\} = T^{-1}(0)$, a subspace of V

~~kernel~~
kernel of T
or nullspace of T , $\dim_F \ker(T) \stackrel{\text{DEFIN}}{=} \text{nullity}(T)$

$\text{im}(T) := T(V) = \{w \in W : \exists v \in V \text{ with } T(v) = w\}$,
image of T , a subspace of W ,

$\dim_F \text{im}(T) \stackrel{\text{DEFIN}}{=} \text{rank}(T)$

EXAMPLE: Consider $V \xrightarrow{T = \frac{d}{dx}} V$

$\left\{ \begin{array}{l} \text{quadratic} \\ \text{polynomials} \\ f(x) = ax^2 + bx + c \\ a, b, c \in \mathbb{R} \end{array} \right\}$

$f(x) \xrightarrow{T} T(f)(x) = f'(x) = \frac{df}{dx}$

$\dim(V) = 3$ since $\mathbb{R}^3 \xrightarrow{\psi} V$ is an isomorphism.
 $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \mapsto ax^2 + bx + c$

What is $\ker(T)$?
 $= \{f(x) = ax^2 + bx + c : \frac{df}{dx} = 0\}$
 $= \{f(x) = c\}$, $\text{nullity}(T) = 1$

What is $\text{im}(T)$?
 $= \left\{ \begin{array}{l} f'(x) \\ \text{"} \\ 2ax + b \end{array} : f(x) = ax^2 + bx + c \right\} = \left\{ \begin{array}{l} \text{linear} \\ \text{polynomials} \\ ax + b \end{array} \right\}$, $\text{rank}(T) = 2$

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THEOREM (The dimension formula) For any linear transformation,
(4.1.6)

$$V \xrightarrow{T} W, \text{ one has } \text{nullity}(T) + \text{rank}(T) = \dim V,$$

$\dim \ker(T) \qquad \dim \text{im}(T)$

proof:

We'll show something stronger:

given any basis $\{u_1, u_2, \dots, u_k\}$ for $\ker(T)$,

and any basis $\{w_1, w_2, \dots, w_r\}$ for $\text{im}(T)$,

if we pick any pre-images $\{v_1, \dots, v_r\}$ with $T(v_i) = w_i, \dots, T(v_r) = w_r$,

then $\{u_1, u_2, \dots, u_k, v_1, \dots, v_r\}$ gives a basis for V

(so $\dim V = k+r$
 $= \dim \ker(T) + \dim \text{im}(T)$).

They span V because for any $v \in V$,

one can write $T(v) \in \text{im}(T)$

$$\begin{aligned} & \parallel \\ & c_1 w_1 + \dots + c_r w_r = c_1 T(v_1) + \dots + c_r T(v_r) \\ & = T(c_1 v_1 + \dots + c_r v_r) \end{aligned}$$

$$\text{so } T(v - (c_1 v_1 + \dots + c_r v_r)) = 0$$

$$\text{i.e. } v - (c_1 v_1 + \dots + c_r v_r) \in \ker T$$

$$\Rightarrow v - (c_1 v_1 + \dots + c_r v_r) = d_1 u_1 + \dots + d_k u_k$$

$$\Rightarrow v = d_1 u_1 + \dots + d_k u_k + c_1 v_1 + \dots + c_r v_r, \text{ as desired.}$$

They are independent because if $d_1 u_1 + \dots + d_k u_k + c_1 v_1 + \dots + c_r v_r = 0$

then applying T shows $d_1 T(u_1) + \dots + d_k T(u_k) + c_1 T(v_1) + \dots + c_r T(v_r) = T(0) = 0$

$$\text{i.e. } c_1 T(v_1) + \dots + c_r T(v_r) = 0$$

$$\Rightarrow c_1 = \dots = c_r = 0$$

But then $d_1 u_1 + \dots + d_k u_k = 0$, so $d_1 = \dots = d_k = 0$ also ■

similar in spirit to EXERCISE 7.10.2

EXAMPLES:

① $V \xrightarrow{T = \frac{d}{dx}} V$ had $\text{null}(T) + \text{rank}(T) = \dim(V)$
 $\{ax^2+bx+c : a,b,c \in \mathbb{R}\}$ $\uparrow + \uparrow = \uparrow$
 $1 + 2 = 3$

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② Sums and direct sums (part of § 3.6)
 $V_1 + V_2$ $V_1 \oplus V_2$

Given two vector spaces V_1, V_2 their direct sum $V_1 \oplus V_2 = V_1 \times V_2$ with componentwise + and scaling

is another F -vector space, with $\dim(V_1 \oplus V_2) = \dim(V_1) + \dim(V_2)$

because one can get a basis for $V_1 \oplus V_2$ by

~~concatenating~~ a basis ~~for~~ $\{a_1, a_2, \dots, a_{\dim V_1}\}$ for V_1
and a basis $\{b_1, b_2, \dots, b_{\dim V_2}\}$ for V_2

and concatenating $\{(a_1, 0), \dots, (a_{\dim V_1}, 0), (0, b_1), \dots, (0, b_{\dim V_2})\}$
to get a basis for $V_1 \oplus V_2$

On the other hand, given two subspaces $V_1, V_2 \subset V$

one can form a new subspace $V_1 + V_2 := \{v_1 + v_2 : v_1 \in V_1, v_2 \in V_2\} \subset V$
called their sum.

Q: What is $\dim(V_1 + V_2)$? It depends on how V_1, V_2 intersect $\dim(V_1), \dim(V_2)$ and...

e.g. $V = \mathbb{R}^3$

