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A seemingly obvious property of $\dim(V)$ is a bit subtle (and comes up a lot).

PROPOSITION: If V is finite-dimensional, and $U \subseteq V$ is a subspace,
(3.4.23)

then U is also finite-dimensional,

$\dim U \leq \dim V$, and equality holds $\Leftrightarrow U = V$.

Proof: Build a basis for U one step at a time by starting with
the \emptyset indep. set, and adding vectors until it spans U .

That is, let $\{u_1, \dots, u_k\} \subset U$ be independent, and if

$U \not\supseteq \text{span}_{\mathbb{F}}\{u_1, \dots, u_k\}$ then pick $u_{k+1} \in U - \text{span}_{\mathbb{F}}\{u_1, \dots, u_k\}$,

so $\{u_1, \dots, u_k, u_{k+1}\}$ is still independent, in U , and in V .

Hence this stops before k reaches $n+1$, so it must stop with
a basis $\{u_1, \dots, u_k\}$ of U having $k \leq n$, i.e. $\dim U \leq \dim V$.
(and it's finite)

If $k=n$, then this basis $\{u_1, \dots, u_n\}$ for U must also span V ,
else one has some $v \in V - \text{span}\{u_1, \dots, u_n\}$ that one could add to
get $\{u_1, \dots, u_n, v\}$ ~~is~~ independent of size $n+1$ in V ; contradiction.

Hence $V = \text{span}\{u_1, \dots, u_n\} = U \blacksquare$

§ 3.5 Computing with bases

Picking an ordered basis $B = (v_1, \dots, v_n)$ for an F -vector space V
 let's one identify V with F^n .

PROPOSITION: Given an ordered set $(v_1, \dots, v_n) \subset V$,
 (3.5.4)

the map $F^n \xrightarrow{\psi} V$:

$$\underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \longrightarrow \psi(\underline{x}) = x_1 v_1 + \dots + x_n v_n$$

is always F -linear, and
 is injective $\Leftrightarrow \{v_1, \dots, v_n\}$ independent

surjective $\Leftrightarrow \{v_1, \dots, v_n\}$ spanning V

and thus bijection $\Leftrightarrow \{v_1, \dots, v_n\}$ is a basis for V .

(so an F -vector space isomorphism) In this case, call $\psi(v) = \underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$, the coordinates of v with respect to $\{v_1, \dots, v_n\} = B$

proof: ~~xxxxxxxxxx~~ Linearity is pretty clear - check $\psi(ax + bx') = a\psi(x) + b\psi(x')$

Since linear maps are group homomorphisms $(F^n)^* \xrightarrow{\psi} V^*$,

ψ is injective $\Leftrightarrow \ker \psi = \{0\} \Leftrightarrow x_1 v_1 + \dots + x_n v_n = 0$ implies $x = 0$
 $\Leftrightarrow \{v_1, \dots, v_n\}$ independent.

The rest proves itself! ■

EXAMPLE: Recall $V = \{ \text{twice differentiable } y(t) \text{ solving } y'' + y = 0 \}$

was an \mathbb{R} -vector space under pointwise + and \mathbb{R} -scaling.

In differential equations, one considers the basic solutions or fundamental

$$y_1 = \cos(t), \quad y_2 = \sin(t)$$

with $\begin{bmatrix} y_1(0) \\ y_1'(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$
 $\begin{bmatrix} \cos(0) \\ \sin(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} y_2(0) \\ y_2'(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

 $\begin{bmatrix} \sin(0) \\ \cos(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

, and shows every solution y can be written uniquely as
 $y = C_1 y_1 + C_2 y_2$ where $C_1 = y(0)$
 $C_2 = y'(0)$

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(The idea is that then $f(t) = y(t) - (c_1y_1(t) + c_2y_2(t))$ has $f'' + f = 0$
 $f(0) = 0$
 $f'(0) = 0$
forcing $f(t) = 0 \forall t$)

In other words $B = (y_1 = \cos t, y_2 = \sin t)$ is an ordered basis for V ,
and hence one has a R-vector space isomorphism

$$\begin{array}{ccc} \mathbb{R}^2 & \xrightarrow{\psi} & V \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} & \longmapsto & x_1 \cos(t) + x_2 \sin(t) \end{array}, \text{ showing } V \cong \mathbb{R}^2.$$

Suppose someone suggests a different subset $(v'_1, \dots, v'_n) = B' \subset V$
might be a basis. How to check if it is, and ~~if so~~ if so
how to relate the coordinates \underline{x}' for v with respect to $B' = (v'_1, \dots, v'_n)$
and coordinates \underline{x} for v — " — $B = (v_1, \dots, v_n)$?

PROPOSITION: Given ~~a basis~~ ^{proven} $B = (v_1, \dots, v_n) \subset V$
(3.5.9) and n vectors $B' = (v'_1, \dots, v'_n) \subset V$,
define the matrix $P = (P_{ij}) \in F^{n \times n}$ by uniquely expressing $v'_j = \sum_{i=1}^n P_{ij} v_i$
for $j = 1, \dots, n$

Then (i) B' is another basis $\Leftrightarrow P$ is invertible

and (ii) if so, then a vector $v \in V$ with coordinates \underline{x} in B
and \underline{x}' in B'

will have $P \underline{x}' = \underline{x}$

and $\underline{x}' = \hat{P}' \underline{x}$

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Proof: For (i), if P is invertible and $\bar{P}^{-1} = (\bar{p}_{ij}^{\top})$ then $\{v'_1, \dots, v'_n\}$ span V

$$\text{since } \sum_{i=1}^n \bar{p}_{ij}^{\top} v'_i = \sum_{i=1}^n \bar{p}_{ij}^{\top} \left(\sum_{k=1}^n P_{ki} v_k \right) = \sum_{k=1}^n \underbrace{\left(\sum_{i=1}^n \bar{p}_{ki} \bar{p}_{ij}^{\top} \right)}_{(P \cdot P^{-1})_{kj}} v_k = v_j$$

and this is reversible: if $\{v'_1, \dots, v'_n\}$ span V

$$\text{then } \exists (g_{ij}) \text{ with } v_j = \sum_{i=1}^n g_{ij} v'_i = \sum_{i=1}^n g_{ij} \left(\sum_{k=1}^n P_{ki} v_k \right) = \sum_{k=1}^n \underbrace{\left(\sum_{i=1}^n P_{ki} g_{ij} \right)}_{\substack{\text{must be} \\ \{1 \text{ if } k=j\} \\ \{0 \text{ else}\}}} v_k$$

since v_1, \dots, v_n are independent

Thus $Q = (g_{ij}) = \bar{P}^{-1}$.

So $\{v'_1, \dots, v'_n\}$ span $V \Leftrightarrow P$ invertible

hence they're a basis $\Leftrightarrow P$ invertible (since $\dim V = n$)

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For (ii), if $v \in V$ has coordinates x for B

$$\text{then } v = x_1 v_1 + \dots + x_n v_n = \sum_{i=1}^n x_i v_i$$


and hence $x' = \bar{P}^{-1} x$ has

$$\begin{aligned} x'_1 v'_1 + \dots + x'_n v'_n &= \sum_{i=1}^n x'_i v'_i = \sum_{i=1}^n \left(\sum_{j=1}^n \bar{p}_{ij}^{\top} x_j \right) \left(\sum_{k=1}^n P_{ki} v_k \right) \\ &= \sum_{k=1}^n \left(\sum_{j=1}^n \underbrace{\left(\sum_{i=1}^n \bar{p}_{ki} \bar{p}_{ij}^{\top} \right)}_{(P \cdot P^{-1})_{kj}} x_j \right) v_k \\ &= \sum_{k=1}^n x_k v_k = v \quad \blacksquare \end{aligned}$$