## Lecture 11: Quick review from previous lecture

- To check if  $W \subset V$  is a subspace of V, it is enough to check the following 3 conditions:
  - 1. W must contain zero element of V,
  - 2. If  $\mathbf{v}$  and  $\mathbf{w}$  in W, then  $\mathbf{v} + \mathbf{w} \in W$ ,
  - 3. If  $\mathbf{v} \in W$  and  $c \in \mathbb{R}$ , then  $c\mathbf{v} \in W$ .
- A linear combination of  $\mathbf{v}_1, \ldots, \mathbf{v}_n$  is

$$c_1\mathbf{v}_1+\cdots+c_n\mathbf{v}_n$$

• We define the set of collecting all possible linear combinations of  $\mathbf{v}_1, \ldots, \mathbf{v}_n$  by

span{
$$\mathbf{v}_1,\ldots,\mathbf{v}_n$$
} =  $\left\{\sum_{i=1}^n c_i \mathbf{v}_i : c_1,\ldots,c_n \in \mathbb{R}\right\}$ 

Today we will discuss the linear independent (dependent).

• Quiz 3 (covers sec. 1.8, 1.9, 2.1, 2.2) will take place in the beginning of the class on Wed. 2/19

## **Remark:**

- If  $\mathbf{v}_1 \neq 0$  in  $\mathbb{R}^3$ , then span $\{\mathbf{v}_1\}$  is the line  $\{c\mathbf{v}_1: c \in \mathbb{R}\}$ .
- If  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are two non-zero vectors in  $\mathbb{R}^3$  that are not parallel to each other (i.e.  $\mathbf{v}_1 \neq c\mathbf{v}_2$  for any scalar c), then span{ $\mathbf{v}_1, \mathbf{v}_2$ } defines a *plane*.

This will lead us naturally into the topic of **linear independence**, which we'll see soon.

Example 5. Determine the span of  $f_1(x) = 1$ ,  $f_2(x) = x$ ,  $f_3(x) = x^2$ . Span{( $L, X, X^2$ ) = {  $a + bx + cX^2$  |  $a, b, c \in \mathbb{R}$ ] =  $P^{(2)}$ , polynomials of degree  $\leq 2$ .

In general, span{ $1, \times, \dots, \times^n$ } =  $P^{(n)}$ .#

## § Linear Independence and Dependence

**Definition:** If  $\mathbf{v}_1, \ldots, \mathbf{v}_n$  are vectors in a vector space V, we say they are **linearly dependent** if there exist scalars  $c_1, \ldots, c_n$ , not all of which are zero, so that

$$c_1\mathbf{v}_1+\cdots+c_n\mathbf{v}_n=\mathbf{0}.$$

If  $\mathbf{v}_1, \ldots, \mathbf{v}_n$  are not linearly dependent, we say they are **linearly independent**.

In other words,  $\mathbf{v}_1, \ldots, \mathbf{v}_n$  are **linearly independent** if the *only* linear combination  $\sum_{i=1}^n c_i \mathbf{v}_i$  that is equal to **0** is when all the  $c_i$ 's are equal to **0**.  $c_1 \vee c_1 \vee c_2 \vee c_3 \vee c_4 = 0$ 

**Example 5.** (1) From Example 1, we have seen that  $2(1,2)^T - (-2,4)^T + 3(5,-1)^T - (19,-3)^T = 0^T$ 

thus  $(1,2)^T, (-2,4)^T, (5,-1)^T, (19,-3)^T$  are linearly dependent.

(2) Let's consider  

$$a(1,2)^{T} + b(-2,4)^{T} = 0^{T}.$$
What are  $a, b$ ?  

$$a\begin{pmatrix} 1\\ 2 \end{pmatrix} + b\begin{pmatrix} -2\\ 4 \end{pmatrix} = \begin{pmatrix} 0\\ 0 \end{pmatrix}$$

$$A^{2}\begin{pmatrix} 1 & -2\\ 2 & 4 \end{pmatrix} \begin{pmatrix} 1 & -2\\ 2 & 4 \end{pmatrix} \begin{pmatrix} a\\ b \end{pmatrix} = \begin{pmatrix} 0\\ 0 \end{pmatrix}$$

$$A^{2}\begin{pmatrix} 1 & -2\\ 2 & 4 \end{pmatrix} \begin{pmatrix} a\\ b \end{pmatrix} = \begin{pmatrix} 0\\ 0 \end{pmatrix}$$

$$A^{2} = \begin{pmatrix} 0\\ 0 \end{pmatrix}$$

$$A^{2} = \begin{pmatrix} 1 & -2\\ 2 & 4 \end{pmatrix} \begin{pmatrix} a\\ b \end{pmatrix} = \begin{pmatrix} 0\\ 0 \end{pmatrix}$$

$$A^{2} = \begin{pmatrix} 0$$

**Example 6.** We take the three vectors

$$\mathbf{v}_1 = \begin{pmatrix} 1\\2\\3 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} -1\\2\\4 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} 5\\-2\\-6 \end{pmatrix}.$$

Determine if they are linearly independent or not?

$$C_{1} V_{1} + C_{2} V_{2} + C_{3} V_{3} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \text{ Findl } C_{1}, C_{2}, C_{7}, C_$$

[Example 6 continue...]

We can then conclude that

**Theorem:** Let  $\mathbf{v}_1, \ldots, \mathbf{v}_k$  in  $\mathbb{R}^n$  and let  $A = [\mathbf{v}_1, \ldots, \mathbf{v}_k]$ :

- (1)  $\{\mathbf{v}_1, \ldots, \mathbf{v}_k\}$  is linearly dependent if and only if there is a nonzero solution  $\mathbf{x}$  to the homogeneous linear system  $A\mathbf{x} = \mathbf{0}$ .
- (2)  $\{\mathbf{v}_1, \ldots, \mathbf{v}_k\}$  is linearly independent if and only if the only solution to the homogeneous linear system  $A\mathbf{x} = \mathbf{0}$  is the trivial one,  $\mathbf{x} = \mathbf{0}$ .

(3) A vector  $\mathbf{b} \in \operatorname{span}\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  if and only if  $A\mathbf{x} = \underbrace{\mathbf{b}}_{l_l}$  is compatible (i.e., has at least one solution).  $A \neq \overline{\left[ \int_{I_l} \nabla_{I_l} \nabla_{I_l} \int_{C_l} \int_{C_l} \int_{C_l} \nabla_{I_l} \nabla_{I_l} \int_{C_l} \int_{C_l} \int_{C_l} \int_{C_l} \nabla_{I_l} \nabla$  **Example 7.** Suppose we take any four vectors in  $\mathbb{R}^3$ ; call them  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ ,  $\mathbf{v}_3$  and  $\mathbf{v}_4$ . Can they be linearly independent? For instance, we take the 4 vectors

$$\mathbf{v}_{1} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \quad \mathbf{v}_{2} = \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix}, \quad \mathbf{v}_{3} = \begin{pmatrix} 1 \\ -4 \\ 6 \end{pmatrix}, \quad \mathbf{v}_{4} = \begin{pmatrix} 4 \\ 2 \\ 3 \end{pmatrix}, \\ \begin{pmatrix} 1 & 3 & 1 & 4 \\ -4 & 4 & 3 \end{pmatrix} \begin{pmatrix} \zeta_{1} \\ \zeta_{2} \\ \zeta_{4} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad \begin{pmatrix} C_{1} \cup_{1} + \cdots + C_{4} \cup_{4} = \delta \end{pmatrix} \\ \begin{pmatrix} 1 & 3 & 1 & 4 \\ 2 & 0 & -4 & 2 \\ -1 & 4 & 4 & 3 \end{pmatrix} \begin{pmatrix} \zeta_{1} \\ \zeta_{4} \\ \zeta_{4} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad \begin{pmatrix} C_{1} \cup_{1} + \cdots + C_{4} \cup_{4} = \delta \end{pmatrix} \\ \begin{pmatrix} 1 & 3 & 1 & 4 \\ 2 & 0 & -4 & 2 \\ -1 & 4 & 6 & 3 \end{pmatrix} \end{pmatrix},$$

$$(2) - 2U) \qquad \begin{pmatrix} 1 & 3 & 1 & 4 \\ 0 & -6 & -6 & -6 \\ 0 & 7 & 7 & 7 \end{pmatrix}, \quad \text{pow echelow fm.} \\ (3) + \frac{7}{6} ) \qquad \begin{pmatrix} 1 & 3 & 1 & 4 \\ 0 & -6 & -6 & -6 \\ 0 & 7 & 7 & 7 \end{pmatrix}, \quad \text{pow echelow fm.} \\ (3) + \frac{7}{6} ) \qquad \begin{pmatrix} 1 & 3 & 1 & 4 \\ 0 & -6 & -6 & -6 \\ 0 & 7 & 7 & 7 \end{pmatrix}, \quad \text{pow echelow fm.} \\ (3) + \frac{7}{6} ) \qquad \begin{pmatrix} 1 & 3 & 1 & 4 \\ 0 & -6 & -6 & -6 \\ 0 & 7 & 7 & 7 \end{pmatrix}, \quad \text{pow echelow fm.} \\ (3) + \frac{7}{6} ) \qquad (2 + C_{3} + C_{4} + C_{4} = D) \\ (2 + C_{3} + C_{4} + C_{4} = D) \\ (2 + C_{3} + C_{4} + C_{4} = D) \\ (2 + C_{3} + C_{4} + C_{4} = D) \\ (2 + C_{3} + C_{4} + C_{4} = D) \\ (2 + C_{3} - C_{4} + C_{4} = D) \\ (2 + C_{3} - C_{4} + C_{4} + C_{4} = D) \\ (2 + C_{3} - C_{4} + C_{4} + C_{4} = D) \\ (2 + C_{3} - C_{4} + C_{4} + C_{4} = D) \\ (2 + C_{3} - C_{4} + C_{4$$

- We can use the same logic to show the general fact: if  $\mathbf{v}_1, \ldots, \mathbf{v}_k$  are k vectors in  $\mathbb{R}^n$ , then they must be linearly dependent if k > n.
- In other words, we have the following fact:

**Fact:** If k > n, then any set of k vectors in  $\mathbb{R}^n$  is linearly dependent.