Lecture 2: Quick review from previous lecture

- Gaussian elimination to solve a linear system $A\mathbf{x} = \mathbf{b}$.
- I_n is the *n*-by-*n* identity matrix, defined by:

$$I_n = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & 0 \\ 0 & 0 & 0 & \cdots & 0 & 1 \end{pmatrix}_{n \times n}$$

or $I_n = \operatorname{diag}(1, \cdots, 1)$.

- \bullet The first problem set has been posted on Canvas. It is due next Friday, 1/31 , at the end of class.
- There will be a quiz in class on Wednesday (1/29).

1.3 Gaussian Elimination

• Suppose E is a 3-by-3 elementary matrix that adds 7 times the 1^{st} row to the 3^{rd} row. Then:

$$E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 7 & 0 & 1 \end{pmatrix}$$

• How to UNDO the effect of this row operation? substracting $7 \oplus \text{From } 3$: We denote it by $E^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -7 & 0 & 1 \end{pmatrix}$. $EE^{-1} = E^{-1}E = I_3$.

• When performing Gaussian elimination, when we reach the j^{th} row, element (j, j) of the new augmented matrix is called the **pivot** for that row.

Example: We look at the example:

$$\begin{cases} x + 2y + 2z = 2 \\ 2x + 10y = 1 \\ 4x + y + 4z = 0 \end{cases}$$

$$\begin{pmatrix} 1 & 2 & 2 & | & 2 \\ 2 & (v & v) & | & | \\ 4 & | & 4 & | & 0 \end{pmatrix}$$

$$4st \text{ pivot } \text{is element } (1, 1), \text{ that } \text{is } 1, \text{ for } 1, \text{ fo$$

[Example Continue]

 \checkmark If at any point in the process one of the pivots is 0, then we are stuck! We can't use a row with a zero pivot to eliminate the entries beneath that pivot.

Example: Suppose we are solving a 4-by-4 system and after using the first row to eliminate entries (2, 1), (3, 1), and (4, 1), we have the following matrix:

(5	2	3	5	2
	0	\bigcirc	2	6	9
	0	1	3	8	3
	0	2	5	1	8

- How to fix this? We will permite vow @ with other vow (will discussed later).
- If a matrix A has all non-zero pivots, it is called **regular**. That is, regular matrices are those for which Gaussian elimination can be performed without switching the order of rows.

For any regular matrix A, we can multiply it on the left by a sequence of elementary matrices E_1, \ldots, E_m , so that the product is an upper triangular matrix U:

Then
$$E_m \cdots E_i A = \square$$

 $\begin{pmatrix} E_i^{\intercal} \cdots E_m^{\intercal}, E_m^{\intercal} \end{pmatrix} E_m \cdots E_i A = (E_i^{\intercal} \cdots E_m^{\intercal}, E_m^{\intercal}) \square$
 $5_0, A = IA = (E_i^{\intercal} \cdots E_m^{\intercal}, E_m^{\intercal}) \square$
denoted by \square
Facts:

(1) We have shown that any regular matrix A can be factored as A = LU, where U is upper triangular and L is lower triangular. Furthermore, L has 1's on its main diagonal, and U has non-zero elements on its main diagonal (the pivots of A).

- (2) L, \tilde{L} are $n \times n$ lower triangular matrices, so is $L\tilde{L}$.
- (3) U, \tilde{U} are $n \times n$ upper triangular matrices, so is $U\tilde{U}$.