## Lecture 2: Quick review from previous lecture

- Gaussian elimination to solve a linear system $A \mathbf{x}=\mathbf{b}$.
- $I_{n}$ is the $n$-by-n identity matrix, defined by:

$$
I_{n}=\left(\begin{array}{cccccc}
1 & 0 & 0 & \cdots & 0 & 0 \\
0 & 1 & 0 & \cdots & 0 & 0 \\
0 & 0 & 1 & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & 1 & 0 \\
0 & 0 & 0 & \cdots & 0 & 1
\end{array}\right)_{n \times n}
$$

or $I_{n}=\operatorname{diag}(1, \cdots, 1)$.

- The first problem set has been posted on Canvas. It is due next Friday, $1 / 31$, at the end of class.
- There will be a quiz in class on Wednesday $(1 / 29)$.
1.3 Gaussian Elimination
- Suppose $E$ is a 3 -by- 3 elementary matrix that adds 7 times the $1^{\text {st }}$ row to the $3^{\text {rd }}$ row. Then:

$$
E=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
7 & 0 & 1
\end{array}\right)
$$

- How to UNDO the effect of this row operation?
substracting 7 (1) from 3:
We denote it by $E^{-1}=\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & 1 & 0 \\ -\eta & 0 & 1\end{array}\right)$.

$$
E E^{-1}=E^{-1} E=I_{3}
$$

- When performing Gaussian elimination, when we reach the $j^{\text {th }}$ row, element $(j, j)$ of the new augmented matrix is called the pivot for that row.

Example: We look at the example:

$$
\left\{\begin{array}{l}
x+2 y+2 z=2 \\
2 x+10 y=1 \\
4 x+y+4 z=0
\end{array}\right.
$$

$$
\left(\begin{array}{ccc|c}
\sqrt[1]{2} & 2 & 2 & 2 \\
2 & 10 & 0 & 1 \\
4 & 1 & 4 & 0
\end{array}\right)
$$

1st pout is element $(1,1)$, that is, 1 .

$$
\xrightarrow[\substack{\text { MATH } 4242}]{\stackrel{(2)-2(1)}{(30}}\left(\begin{array}{ccc|c}
1 & 2 & 2 & 2 \\
0 & 6 & -4 & -3 \\
0 & -7 & -4 & -8
\end{array}\right) \quad \text { and pint } \quad 1, \quad(2,2) \text {, that is, } 6
$$

[Example Continue]
$\xrightarrow{(3)+\frac{7}{6}(2)}\left(\begin{array}{ccc|c}1 & 2 & 2 & 2 \\ 0 & 6 & -4 & -3 \\ 0 & 0 & \frac{-26}{3} & \frac{-23}{2}\end{array}\right)$.
ard pinot 1, $(3,3)$, that is, $-26 / 3$
[Exercise]: find $x, y, z$ by using "back-sibstitution".
$\checkmark$ If at any point in the process one of the pivots is 0 , then we are stuck! We can't use a row with a zero pivot to eliminate the entries beneath that pivot.

Example: Suppose we are solving a 4-by-4 system and after using the first row to eliminate entries $(2,1),(3,1)$, and $(4,1)$, we have the following matrix:

$$
\left(\begin{array}{cccc|c}
5 & 2 & 3 & 5 & 2 \\
0 & 0 & 2 & 6 & 9 \\
0 & 1 & 3 & 8 & 3 \\
0 & 2 & 5 & 1 & 8
\end{array}\right)
$$

- How to fixthis? We mill permute row (2) with other row (will discussed later).
- If a matrix $A$ has all non-zero pivots, it is called regular. That is, regular matrices are those for which Gaussian elimination can be performed without switching the order of rows.

For any regular matrix $A$, we can multiply it on the left by a sequence of elementary matrices $E_{1}, \ldots, E_{m}$, so that the product is an upper triangular matrix $U$ :

$$
E_{m} E_{m-1} \cdots E_{1} A=U
$$

* Some observation:

$$
\begin{aligned}
& E_{1}=\left(\begin{array}{lll}
1 & 0 & 0 \\
a & 1 & 0 \\
0 & 0 & 1
\end{array}\right), \text { associtited to row (2) }+ \text { a row (1) } \\
& E_{2}=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
b & 0 & 1
\end{array}\right), \quad \text { row } 3+b \text { row (1) } \\
& \left.E_{3}=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & c & 1
\end{array}\right), c\right) \\
& E_{1}^{-1}=\left(\begin{array}{ccc}
1 & 0 & 0 \\
-a & 1 & 0 \\
0 & 0 & 1
\end{array}\right), E_{2}^{-1}=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
-b & 0 & 1
\end{array}\right), E_{3}^{+}=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & -c 1
\end{array}\right) .
\end{aligned}
$$

Then $E_{1}^{-1} E_{2}^{-1} E_{3}^{-1}=\left(\begin{array}{ccc}1 & 0 & 0 \\ -a & 1 & 0 \\ 0 & 0 & 1\end{array}\right)\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & 1 & 0 \\ -b & 0 & 1\end{array}\right)\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -c & 1\end{array}\right)$

$$
=\left(\begin{array}{ccc}
1 & 0 & 0 \\
-a & 1 & 0 \\
-b & -c & 1
\end{array}\right)
$$

We now can see that (zero above main diagonal
$E_{1}^{-1} E_{2}^{-1} \cdots E_{m}^{-1}$ has the form

$$
L=\left[\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
x & 1 & & \\
x & & \ddots & 0 \\
\dot{x} & \cdots & x & 1
\end{array}\right]
$$

Then

$$
E_{m} \cdots E_{1} A=L
$$

$$
\begin{aligned}
& \left(E_{1}^{1} \cdots E_{m-1}^{-1} E_{m}^{1}\right) E_{m} \ldots E_{1} A=\left(E_{1}^{-1} \cdots E_{m-1}^{-1} E_{m}^{-1}\right) \\
& \quad \text { So, } \quad A=I A=\underbrace{\left.E_{1}^{-1} \cdots E_{m-1}^{-1} E_{m}^{-1}\right)}_{\text {denoted by } L} U .
\end{aligned}
$$

## Facts:

(1) We have shown that any regular matrix $A$ can be factored as $A=L U$, where $U$ is upper triangular and $L$ is lower triangular.
Furthermore, $L$ has 1's on its main diagonal, and $U$ has non-zero elements on its main diagonal (the pivots of $A$ ).
(2) $L, \tilde{L}$ are $n \times n$ lower triangular matrices, so is $L \tilde{L}$.
(3) $U, \tilde{U}$ are $n \times n$ upper triangular matrices, so is $U \tilde{U}$.

