Lecture 21: Quick review from previous lecture • The Gram matrix is $K = \begin{pmatrix} \langle \mathbf{v}_1, \mathbf{v}_1 \rangle & \langle \mathbf{v}_1, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_1, \mathbf{v}_n \rangle \\ \langle \mathbf{v}_2, \mathbf{v}_1 \rangle & \langle \mathbf{v}_2, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_2, \mathbf{v}_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{v}_n, \mathbf{v}_1 \rangle & \langle \mathbf{v}_n, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_n, \mathbf{v}_n \rangle \end{pmatrix}_{\mathbf{p} \times \mathbf{v}}$ $K = \begin{pmatrix} \langle \mathbf{v}_1, \mathbf{v}_1 \rangle & \langle \mathbf{v}_1, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_1, \mathbf{v}_n \rangle \\ \langle \mathbf{v}_2, \mathbf{v}_1 \rangle & \langle \mathbf{v}_2, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_2, \mathbf{v}_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{v}_n, \mathbf{v}_1 \rangle & \langle \mathbf{v}_n, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_n, \mathbf{v}_n \rangle \end{pmatrix}_{\mathbf{p} \times \mathbf{v}}$

 $- \text{In } \mathbb{R}^n$, Gram matrices are always positive semidefinite

- they are positive definite precisely when the vectors $\mathbf{v}_1, \ldots, \mathbf{v}_n$ are linearly independent.

Today we will discuss "Orthogonal(Orthonormal) bases"

Lecture video can be found in Canvas "Media Gallery"

3.6 Complex Vector Spaces

To finish Chapter 3: let's briefly discuss complex vector spaces and complex inner products.

Recall that a **complex_number** as an expression of the form

$$z = x + iy, \qquad x, y \in \mathbb{R}. \qquad i = \sqrt{-1} \quad i^2 = (\sqrt{-1})^2 = -1.$$

The complex conjugate of $z = x + iy$ is
 $\overline{z} = x - iy.$

$$|z|^2 = z\overline{z}$$

- Everything we have done in Chapter 1 with \mathbb{R}^n and real-valued scalars works in \mathbb{C}^n with complex-valued scalars.
- In particular, Gaussian elimination works exactly the same way if the numbers are in \mathbb{C} instead of \mathbb{R} .

$$\begin{aligned} z &= 1 + \hat{z} \ (1 + \sqrt{-1}), \\ \bar{z} &= 1 - \hat{z}, \\ |z|^2 &= z \ \bar{z} \ \bar{z} \ = (Hi) (I - \hat{i}) \\ &= 1 - \hat{i} + \hat{i} - \hat{i}^2 \ = 1 + 1 = 2, \\ |z| &= |1 + \hat{i}| \ = \sqrt{2}, \\ |z|^2 &= x + \hat{i}y, \\ |z|^2 &= x^2 + y^2, \quad |z| = \sqrt{x^2 + y^2}. \end{aligned}$$

§ Inner product on \mathbb{C}^n :

$$\langle \mathbf{w}, \mathbf{z} \rangle = \sum_{i=1}^{n} w \overline{z_i}$$

- This way, $\langle \mathbf{z}, \mathbf{z} \rangle = \sum_{i=1}^{n} z_i \overline{z_i} = \sum_{i=1}^{n} |z_i|^2$, which is positive if $\mathbf{z} \neq 0$.
- Note that $\langle \mathbf{w}, \mathbf{z} \rangle$ is not symmetric; rather it is *conjugate-symmetric*: $\langle \mathbf{w}, \mathbf{z} \rangle \neq \overline{\langle \mathbf{z}, \mathbf{w} \rangle}$

• For
$$c, d \in \mathbb{C}$$
,
 $\langle c\mathbf{u} + d\mathbf{v}, \mathbf{w} \rangle = \underline{c} \langle \mathbf{u}, \mathbf{w} \rangle + \underline{d} \langle \mathbf{v}, \mathbf{w} \rangle$
 $\langle \mathbf{u}, c\mathbf{v} + d\mathbf{w} \rangle = \overline{c} \langle \mathbf{u}, \mathbf{v} \rangle + \overline{d} \langle \mathbf{u}, \mathbf{w} \rangle$

 $\cdot ||v||^{2} = (v,v) \geq 0; \quad \langle v,v \rangle = 0 \iff V=0$

$$EX: \quad \int = (1+i)^{2} (1+i$$

4 Orthogonality

4.1 Orthogonal and Orthonormal Bases

We've already seen that in an inner product space V, two vectors \mathbf{x} and \mathbf{y} are said to be *orthogonal* if $\langle \mathbf{x}, \mathbf{y} \rangle = 0$.

Fact: If $\mathbf{v}_1, \ldots, \mathbf{v}_n$ are nonzero vectors that are "mutually orthogonal", meaning $\langle \mathbf{v}_i, \mathbf{v}_j \rangle = 0$ if $i \neq j$, then $\mathbf{v}_1, \ldots, \mathbf{v}_n$ are linearly independent.
[To see this]: Consider $C_1V_1 + + C_nV_n = 0$.
We want to show $C_1 = 0, \dots, C_n = 0$.
$\langle c_i v_i + \cdots + c_n v_n, v_i \rangle = \langle 0, v_i \rangle.$
$G(v_1,v_1)+C_2(v_2,v_1)+\cdots+G_n(v_n,v_n) = 0$
$C_1 (V_1, V_1) = 0$ $C_1 (V_1, V_1)^2 = 0 = C_1 = 0.$ Similarly, we can get
Definition: Suppose $\mathbf{v}_1, \ldots, \mathbf{v}_n$ are nonzero vectors that are mutually orthogonal. If additionally $\ \mathbf{v}_i\ = 1$, we say $\mathbf{v}_1, \ldots, \mathbf{v}_n$ are orthonormal .
 Definition: If v₁,, v_n are mutually orthogonal vectors that are also a basis for V (so dim V = n), we say they are an orthogonal basis. If v₁,, v_n are orthonormal and a basis for V, we say they are an orthonormal basis. (IIV, II = = IIV, II = I).
Example. In \mathbb{R}^n equipped with the standard dot product, an orthonormal basis is the standard basis:
$\mathbf{e}_{1} = \begin{pmatrix} 1\\0\\0\\\vdots\\0\\0 \end{pmatrix}, \mathbf{e}_{2} = \begin{pmatrix} 0\\1\\0\\\vdots\\0\\0 \end{pmatrix}, \dots, \mathbf{e}_{n} = \begin{pmatrix} 0\\0\\0\\\vdots\\0\\1 \end{pmatrix}$ $(1) (\mathbf{e}_{1}, \mathbf{e}_{2}) = 0, \dots, (\mathbf{e}_{i}, \mathbf{e}_{j}) = 0, \text{ spring 2020}$ $MATH 4242-Week 9-2 (1) (\mathbf{e}_{1}, \mathbf{e}_{2}) = 0, \dots, (\mathbf{e}_{i}, \mathbf{e}_{j}) = 0, \text{ spring 2020}$

Fact: Suppose that $\mathbf{v}_1, \ldots, \mathbf{v}_n$ are nonzero, mutually orthogonal (resp. orthonormal) vectors. Then $\mathbf{v}_1, \ldots, \mathbf{v}_n$ form an orthogonal (resp. orthonormal) basis for their span $W = \text{span}\{\mathbf{v}_1, \ldots, \mathbf{v}_n\}$.



{vi, ..., vi) orthogonal (orthonormal) basis for W.

Fact: Suppose that $\mathbf{v}_1, \dots, \mathbf{v}_n$ is orthogonal basis. Then $\frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}, \dots, \frac{\mathbf{v}_n}{\|\mathbf{v}_n\|}$ form an orthonormal basis. $\int \int \left\| \int \left\| \int \left\| \mathbf{v}_1 \right\| \right\| = \int \left\| \int \left\| \int \left\| \int \left\| \mathbf{v}_1 \right\| \right\| \right\| = \int \left\| \int \left\| \int \left\| \mathbf{v}_1 \right\| \right\| = \int \left\| \int \left\| \mathbf{v}_1 \right\| \right\| = \int \left\| \int \left\| \mathbf{v}_1 \right\| \right\| = \int \left\| \mathbf{v}_1 \right\| = \int \left$

Example. Explain why vectors $\mathbf{x} = (1 \ 1 \ 0)^T$, $\mathbf{y} = (1 \ -1 \ 1)^T$, and $\mathbf{z} = (1 \ -1 \ -2)^T$ form an orthogonal basis in \mathbb{R}^3 ? Turn them into an orthonormal basis. **X**, **Y**, **Z** are motionally orthogonal. Fact $(\mathbf{x}, \mathbf{y}, \mathbf{z})$ linearly independent $(\mathbf{x}, \mathbf{y}, \mathbf{z}) = (\mathbf{x}, \mathbf{y}, \mathbf{z})$ linearly independent $(\mathbf{x}, \mathbf{y}) = (\mathbf{x}, \mathbf{y}, \mathbf{z})$ linearly independent $(\mathbf{x}, \mathbf{y}) = (\mathbf{x}, \mathbf{y}, \mathbf{z}) = (\mathbf{x}, \mathbf{y}, \mathbf{z}) = (\mathbf{x}, \mathbf{y}, \mathbf{z}) = (\mathbf{x}, \mathbf{z}) = (\mathbf{z}, \mathbf{z})$. Thus, $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is an orthogonal basis in \mathbb{R}^3 . $\{(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{z}\} = (\mathbf{x}, \mathbf{y}, \mathbf{z}) = (\mathbf{x}, \mathbf{z}, \mathbf{z}) = (\mathbf{x}, \mathbf{z}, \mathbf{z}) = (\mathbf{z}, \mathbf{z})$. Thus, $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is an orthogonal basis in \mathbb{R}^3 . $\{(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{z}\} = (\mathbf{x}, \mathbf{z}, \mathbf{z}) = (\mathbf{z}, \mathbf{z}, \mathbf{z}), (\mathbf{z}, \mathbf{z}) = (\mathbf{z}, \mathbf{z})$. Thus, $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is an orthogonal basis in \mathbb{R}^3 . $\{(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{z}\} = (\mathbf{z}, \mathbf{z}), (\mathbf{z}, \mathbf{z}), (\mathbf{z}, \mathbf{z}), (\mathbf{z}, \mathbf{z}) = (\mathbf{z}, \mathbf{z})$. Thus, $\mathbf{x}, \mathbf{y}, \mathbf{z}$ is an orthogonal basis for \mathbb{R}^3 . \mathbf{x} is an orthonormal basis for \mathbb{R}^3 . MATH 4242- Week 9-2

§ Computations in Orthogonal Bases

What are the advantages of orthogonal (orthonormal) bases?

It is simple to find the <u>coordinates of a vector</u> in the orthogonal (orthonormal) basis. However, in general this is not so easy.

Fact: If $\mathbf{v}_1, \ldots, \mathbf{v}_n$ is an orthogonal basis in any inner product space V, then for any vector $\mathbf{v} \in V$ we have (1) $a_i = \frac{\langle \mathbf{v}, \mathbf{v}_i \rangle}{\|\mathbf{v}_i\|^2}, \ i = 1, \cdots, n.$ where Moreover, we have (2) $\|\mathbf{v}\|^2 = a_1^2 \|\mathbf{v}_1\|^2 + \cdots + a_n^2 \|\mathbf{v}_n\|^2 = \sum_{i=1}^n \left(\frac{\langle \mathbf{v}, \mathbf{v}_i \rangle}{\|\mathbf{v}_i\|}\right)^2.$ [To see this:] For any vev, we can write $V = a_1 V_1 + a_2 V_2 + \dots + a_n V_n$ $\langle v, v_1 \rangle = \langle a_1 v_1 + a_2 v_2 + \dots + a_n v_n, v_1 \rangle$ $= a_1 < v_1, v_1 > + a_2 < v_2, v_1 > + \dots + a_2 < v_2, v_2 > + \dots + a_2 < \cdots + a_2 < v_2, v_2 > \dots + a_2 < \cdots + a_2 <$ Thus, $\langle \mathcal{J}, \mathcal{J}, \mathcal{J} \rangle = a_1 || \mathcal{J}_1 ||^2$. =) $a_1 = (J, J_1)$ Similarly, we can get $a_2 = \frac{(J, J_2)}{||J_2||^2}$,..., $a_n = \langle V, V_n \rangle$ $\frac{1}{\|V_n\|^2} \cdot \# \quad (a_1, a_2, \dots, a_n) \text{ is coordinate}$ $MATH 4242 \cdot Week 9^{-2}(Z) \quad Exercise.^{6} \quad of vector V \text{ in basis [String: 2020Un]}.$

Example. Consider the orthogonal basis
$$\mathbf{x} = (1 \ 1 \ 0)^T$$
, $\mathbf{y} = (1 \ -1 \ 1)^T$, and
 $\mathbf{z} = (1 \ -1 \ -2)^T$ of \mathbb{R}^3 . Write $\mathbf{v} = (1 \ 2 \ 3)^T$ as the linear combination of \mathbf{x} , \mathbf{y}
and \mathbf{z} .
 $\mathbf{v} = \left\langle \underbrace{\mathbf{v}, \mathbf{x}}_{11 \times 11^2} \times + \left\langle \underbrace{\mathbf{v}, \underbrace{\mathbf{y}}_{12}}_{11 \mathbf{y} \mathbf{y} \mathbf{y}} + \left\langle \underbrace{\mathbf{u}, \underbrace{\mathbf{z}}_{2}}_{11 \mathbf{z} \mathbf{1} \mathbf{z}} \right\rangle$
 $< \mathbf{v}, \mathbf{x} = \left\langle \left(\frac{1}{3} \right), \left(\frac{1}{9} \right) \right\rangle = 1 + 2 = 3$
 $||\mathbf{x}||^2 = \left\langle \left(\frac{1}{3} \right), \left(\frac{1}{9} \right) \right\rangle = 1 - 2 + 3 = 2$.
 $< \mathbf{v}, \mathbf{y} = \left\langle \left(\frac{1}{3} \right), \left(\frac{1}{9} \right) \right\rangle = 1 - 2 + 3 = 2$.
 $||\mathbf{y}||^2 = \left\langle \left(\frac{1}{9} \right), \left(\frac{1}{9} \right) \right\rangle = 3$.
 $< \mathbf{u}, \mathbf{z} = -7$.
 $||\mathbf{z}||^2 = 6$. Thus, $\mathbf{v} = \frac{3}{2} \times + \frac{2}{3} \mathbf{y} - \frac{2}{6} \mathbf{z}$.
Example.
(1) The basis $1, x, x^2$ do NOT form an orthogonal basis. for $P^{(2)}(\mathbf{r}, \mathbf{r})$.
 $< \mathbf{l}, \mathbf{x} > = \int_{0}^{1} + \mathbf{x} \, d\mathbf{x} = \frac{1}{2} \mathbf{x}^2 \Big|_{0}^{1} = \frac{1}{2} \pm 0$.
 $< \mathbf{x}, \mathbf{x}^2 = \int_{0}^{1} \mathbf{x} \, \mathbf{x}^2 \, d\mathbf{x} = \int_{0}^{1} \mathbf{x}^3 \, d\mathbf{x} = \frac{1}{4} \pm 0$.
(2) \mathbf{v} continue Next Monday.
 $\begin{bmatrix} p_1(x) = 1, \quad p_2(x) = x - \frac{1}{2}, \quad p_3(x) = x^2 - x + \frac{1}{6}. \end{bmatrix}$
is an orthogonal basis of $P^{(2)}([\mathbf{r}, \mathbf{r}])$.
Test p(x) = x^2 + x + 1 in terms of the basis p_1, p_2, p_3 in (2).
(**f**. (**f** \circ **i**)