

## Lecture 4: Quick review from previous lecture

- We have discussed how to find LU factorization for a matrix  $A$  has  $n$  nonzero pivots :
  - either by elementary row operator type 1 (adding/subtracting one row to another row);
  - or type 2 (permutation)

pivoting

- $A$  is nonsingular  $\Leftrightarrow A$  has a permuted  $LU$  factorization:  $PA = LU$

Today we will discuss the **inverse** of a matrix.

- Homework 1 will be due this Friday.

## 1.5 Matrix Inverse

The inverse of a matrix is analogous to  $a^{-1} = \frac{1}{a}$  of a scalar  $a \neq 0$ . Thus, for  $[5]$  1 by 1 matrix, it has inverse  $[\frac{1}{5}]$ . Then

$$[5][\frac{1}{5}] = [1].$$

- $A$  is a square matrix, then its **inverse**  $A^{-1}$  is the  $n \times n$  matrix satisfying

$$AA^{-1} = I_n = A^{-1}A.$$

Note that "Not every matrix has an inverse !!!"

$A = \begin{pmatrix} 1 & 0 \\ 4 & 0 \end{pmatrix}$ . There is NO matrix  $\underline{X}$  with size  $2 \times 2$  satisfying  $\underline{X}A = I_2$  or  $A\underline{X} = I_2$

In fact, we will see a square matrix has an **inverse** when it is **nonsingular**.

- We've already seen how to find the inverse of elementary row matrices:

**Example.** The inverse of the matrix

$$E = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

is simply the matrix

$$E^{-1} = \begin{pmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

**Example.** A permutation matrix

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \quad PP = I_3.$$

Thus,  
 $P^{-1} = P$ .

- In general, however, finding  $A^{-1}$  will not be so easy. We will see a systematic method for doing so in the next class, known as *Gauss-Jordan elimination*.
- In the following, we will discuss 3 key facts:

**Fact 1.** If the inverse of a matrix exists, then this inverse matrix is unique. In other words, if  $B$  and  $C$  are both inverse of  $A$ , then

Since  $B, C$  are inverse of  $A$ ,  $B = C$ .  
 $AB = I = BA$ .  
 $AC = I = CA$ .

$$B = BI = B(AC) = (BA)C = IC = C. \quad \#$$

**Fact 2.** the inverse of the inverse is the original matrix. More precisely,  
 $(A^{-1})^{-1} = A$ .

*Proof.* This is an immediate consequence of the defining property of  $A^{-1}$ .

$$\underline{A^{-1}}A = I. \quad \Rightarrow \quad (A^{-1})^{-1} = A.$$

- Continue the 3 key facts:

**Fact 3.** If  $A$  and  $B$  are two invertible  $n$ -by- $n$  matrices, then their product  $AB$  is invertible, and  $(AB)^{-1} = B^{-1}A^{-1}$ .

$$\underline{X} = B^{-1}A^{-1}$$

$$(1) \quad \underline{X} AB = (B^{-1}A^{-1})AB = B^{-1}(A^{-1}A)B = B^{-1}IB = B^{-1}B = I$$

$$(2) \quad AB \underline{X} = AB(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I$$

Thus the inverse of  $AB$  is  $B^{-1}A^{-1} = (AB)^{-1}$ .

**Remark:** In general,

$$(A_1A_2 \cdots A_k)^{-1} = A_k^{-1} \cdots A_2^{-1}A_1^{-1}.$$

### § The inverse of a $2 \times 2$ matrix.

We will find a simple formula of the inverse of  $2 \times 2$  matrix.

Consider a general  $2 \times 2$  matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ .

Let's compute its inverse  $X = \begin{pmatrix} x & y \\ z & w \end{pmatrix}$  if it exists.

$$A \bar{X} = I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{cases} ax + bz = 1 \\ ay + bw = 0 \\ cx + dz = 0 \\ cy + dw = 1 \end{cases} \Rightarrow \begin{pmatrix} a & 0 & b & 0 \\ 0 & a & 0 & b \\ c & 0 & d & 0 \\ 0 & c & 0 & d \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Case 1:  $a \neq 0$

$$\textcircled{3} \xrightarrow{-\frac{c}{a} \textcircled{1}} \left( \begin{array}{cccc|c} a & 0 & b & 0 & 1 \\ 0 & a & 0 & b & 0 \\ 0 & 0 & d - \frac{bc}{a} & 0 & -\frac{c}{a} \\ 0 & c & 0 & d & 1 \end{array} \right)$$

$$\textcircled{4} \xrightarrow{-\frac{c}{a} \textcircled{2}} \left( \begin{array}{cccc|c} a & 0 & b & 0 & 1 \\ 0 & a & 0 & b & 0 \\ 0 & 0 & d - \frac{bc}{a} & 0 & -\frac{c}{a} \\ 0 & 0 & 0 & d - \frac{bc}{a} & 1 \end{array} \right)$$

$$w = \frac{a}{ad - bc} \quad \text{if } ad - bc \neq 0.$$

$A$  has no inverse if  $ad - bc = 0$

$$x = \frac{d}{ad - bc}, \quad y = \frac{-b}{ad - bc}, \quad z = \frac{-c}{ad - bc}.$$

[Continue the computation:]

Case 2 =  $a=0, c \neq 0$ . Similar computation gives the same formula for  $x, y, z, w$ . if  $ad-bc \neq 0$ .

Case 3 =  $a=0=c$ .

$A$  has NO inverse.

(2)  $\exists A = I_2$ . Following a similar computation as above. #

## Remark:

- If  $ad - bc \neq 0$ , then the 2-by-2 matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  has an inverse given by:

$$A^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

- The number “ $ad - bc$ ” is known as the **determinant of  $A$** , denoted by

$$\det(A) = ad - bc.$$

- In general, the determinant  $\det(A)$  can be defined for a square matrix  $A$  of any size [Will discussed in later lectures], and

$A$  is invertible if and only if  $\det(A) \neq 0$ .