

Ephaptic conduction in a cardiac strand model with 3D electrodiffusion

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Contributed by Charles S. Peskin, February 6, 2008 (sent for review July 29, 2007)

We study cardiac action potential propagation under severe reduction in gap junction conductance. We use a mathematical model of cellular electrical activity that takes into account both three-dimensional geometry and ionic concentration effects. Certain anatomical and biophysical parameters are varied to see their impact on cardiac action potential conduction velocity. This study uncovers quantitative features of ephaptic propagation that differ from previous studies based on one-dimensional models. We also identify a mode of cardiac action potential propagation in which the ephaptic and gap-junction-mediated mechanisms alternate. Our study demonstrates the usefulness of this modeling approach for electrophysiological systems especially when detailed membrane geometry plays an important role.

3D model of electrophysiology | ephaptic coupling | gap junction

Cellular electrical activity is central to physiology. It is the basis of sensory perception, communication between neurons, initiation and coordination of skeletal muscle contraction, synchronization of the heart beat, and the secretion of hormones (1). Most mathematical models of cellular electrical activity are based on the cable model, which can be derived from a current continuity relation on a one-dimensional ohmic cable (2–4). As such, its derivation rests on several assumptions (4): ionic concentrations are assumed not to change appreciably over the time of interest, and a one-dimensional picture of cell geometry is assumed to be adequate for purposes of describing cellular electrical activity. These assumptions, however, may not hold in many systems of biological significance, especially in the central nervous system and cardiac tissue, where microhistological features may play an essential role in shaping physiological responses (4, 5).

Previous attempts at generalizing the cable model include refs. 6 and 7. In ref. 6, the authors include electrodiffusion of ions in their framework while retaining the one-dimensional character of the cable model. Their pioneering work seems not to have seen widespread use, possibly because of the numerical difficulty the authors encountered in integrating their system (4). In ref. 7, the authors propose a model that addresses the limitations of the cable model discussed in the previous paragraph. Their attention is, however, restricted mostly to stationary problems (8). Their model is numerically difficult to deal with because of the need to resolve boundary layers associated with space charge layers near the membrane.

In refs. 9 and 10, we proposed a model that addresses the limitations of the cable model as stated above and developed an efficient numerical algorithm that makes dynamic simulations possible. We view biological tissue as 3D space partitioned into intracellular and extracellular spaces by the membrane. In these regions, ionic concentrations and the electrostatic potential obey a system of partial differential equations (PDEs). Transmembrane ionic currents are incorporated in the form of interface conditions to be satisfied on both sides of the membrane.

In this article, we shall apply this modeling methodology to the study of cardiac action potential propagation when gap junction conductance between neighboring cells is severely suppressed. It

is widely accepted that gap junctions, which serve as low-resistance connections between cells, are essential to cardiac action potential propagation (11). There has, however, been some controversy as to whether gap junctions are absolutely necessary (12). This controversy has been given renewed attention in recent years in light of the experimental finding that mice engineered not to express gap junctions in the heart (connexin 43 knockout mice) still exhibit cardiac electric conduction, albeit at a reduced velocity (13).

One possible hypothesis that may explain such anomalous conduction is the ephaptic mechanism, first proposed in ref. 14. Simple models of cardiac electrical circuitry have been used to argue that cardiac propagation is possible without gap junctions (15). In ref. 16, the authors address this question using a simple ohmic current model with realistic cardiac ion channel dynamics.

We apply our modeling methodology to perform a more complete study of this issue. As in ref. 16, we consider a linear strand of cardiac cells. Several biophysical parameters are varied to assess their impact on cardiac action potential propagation. Our methodology allows us to explore the effects that membrane geometry, extracellular space, and ionic diffusion have on ephaptic propagation, aspects that cannot be addressed by using conventional models of electrophysiology.

Model

We give a brief introduction to our mathematical model. For a detailed discussion, we refer the reader to refs. 9 and 10. Let the biological tissue of interest be divided into subregions $\Omega^{(k)}$, indexed by k . We denote the membrane separating the regions $\Omega^{(k)}$ and $\Omega^{(l)}$ by $\Gamma^{(kl)}$ (Fig. 1).

In $\Omega^{(k)}$, the equations satisfied by the ionic concentration c_i and the electrostatic potential ϕ are the following:

$$\frac{\partial c_i}{\partial t} = -\nabla \cdot \mathbf{f}_i, \quad \mathbf{f}_i = -D_i \left(\nabla c_i + \frac{qz_i c_i}{k_B T} \nabla \phi \right) \quad [1]$$

$$0 = \rho_0 + \sum_{i=1}^N qz_i c_i. \quad [2]$$

Here, \mathbf{f}_i denotes the flux of the i th species of ion, and Eq. 1 is a statement of ionic conservation. \mathbf{f}_i is expressed as a sum of a diffusive and a drift flux. D_i is the diffusion coefficient of the i th species of ion, and qz_i is the amount of charge on the i th species ion, where q is the elementary charge—i.e., the charge on a proton. The coefficient $qz_i D_i / (k_B T)$ is the mobility of the ionic species (Einstein relation), where k_B is the Boltzmann constant

Author contributions: Y.M., G.I.F., and C.S.P. designed research; Y.M. performed research; Y.M., G.I.F., and C.S.P. analyzed data; and Y.M., G.I.F., and C.S.P. wrote the paper.

The authors declare no conflict of interest.

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This article contains supporting information online at www.pnas.org/cgi/content/full/0801089105/DCSupplemental.

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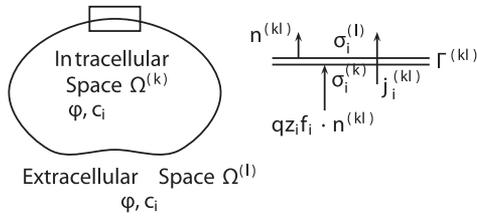


Fig. 1. The potential ϕ and the ionic concentrations c_i are defined in the regions $\Omega^{(k)}$ and $\Omega^{(l)}$, which are here identified with the intracellular and extracellular spaces. The membrane region enclosed by the rectangular box is magnified on the right. This membrane, denoted $\Gamma^{(kl)}$ with unit normal $\mathbf{n}^{(kl)}$ pointing out of $\Omega^{(k)}$ into $\Omega^{(l)}$, has a surface charge layers on both sides, the densities of which are denoted $\sigma^{(k)} = -\sigma^{(l)}$. The current per unit area incident onto face k of the membrane carried by the i th species of ion is $qz_i f_i \cdot \mathbf{n}^{(kl)}$, and the current per unit area carried through the membrane (via ionic channels) by the i th species of ion is $j_i^{(kl)}$.

and T is the absolute temperature. Eq. 2 is a statement of electroneutrality, and ρ_0 is the immobile background charge density, which may come from charge contributions from extracellular or cytoskeletal matrix proteins. An alternative would be to replace Eq. 2 with the Poisson equation, which would then constitute the familiar Poisson–Nernst–Planck system (7). This system, however, is very difficult to simulate numerically because of the presence of Debye layers (to be discussed below).

We now turn to the boundary conditions, satisfied at both the intracellular and extracellular sides of the cell membrane. Across the cell membrane, a jump in electrostatic potential (membrane potential) is maintained, and the cell membrane acts as a capacitor. There is thus a thin layer on both sides of the membrane where electric charge accumulates whose thickness is on the order of the Debye length r_d , which is approximately 1 nm in physiological systems. In Eq. 2, we have taken the electroneutrality condition to hold inside and outside of the cell, and this implies that we must treat the presence of Debye layers in the form of boundary conditions.

Ionic current that flows into the membrane either goes across the membrane through ionic channels, transporters, or pumps, or contributes to the change in surface charge. The boundary condition satisfied at the $\Omega^{(k)}$ side of the membrane $\Gamma^{(kl)}$ is

$$\frac{\partial \sigma_i^{(k)}}{\partial t} + j_i^{(kl)}(\mathbf{x}, t) = qz_i \mathbf{f}_i^{(k)}(\mathbf{x}, t) \cdot \mathbf{n}^{(kl)}(\mathbf{x}). \quad [3]$$

The term $j_i^{(kl)}$ denotes the transmembrane current from region $\Omega^{(k)}$ into $\Omega^{(l)}$. We note by definition that $j_i^{(kl)} = -j_i^{(lk)}$. The variable $\sigma_i^{(k)}$ denotes the contribution of the i th species of ion to the surface charge density on the $\Omega^{(k)}$ face of the membrane.

The term $\sigma_i^{(k)}$ is expressed as

$$\sigma_i^{(k)}(\mathbf{x}, t) = \lambda_i^{(k)}(\mathbf{x}, t) \sigma^{(k)}, \quad \sigma^{(k)} = C_m \phi^{(kl)} \quad [4]$$

$$\frac{\partial \lambda_i^{(k)}}{\partial t} = \frac{\tilde{\lambda}_i^{(k)} - \lambda_i^{(k)}}{r_d^2/D_0}, \quad \tilde{\lambda}_i^{(k)} = \frac{z_i^2 c_i^{(k)}(\mathbf{x}, t)}{\sum_{i'=1}^N z_{i'}^2 c_{i'}^{(k)}(\mathbf{x}, t)}, \quad [5]$$

where $D_0 = 1.0 \mu\text{m}^2/\text{ms}$ is a typical ionic diffusion coefficient and r_d is the aforementioned Debye length. $\sigma^{(k)}$ is the total charge per unit area on the membrane surface facing $\Omega^{(k)}$ and is the product of C_m , the capacitance of the membrane, and $\phi^{(kl)} = \phi^{(k)} - \phi^{(l)}$, the membrane potential. Note that $\lambda_i^{(k)}$ is the fractional contribution of the i th species of ion to the surface charge density on face k of the membrane (Eq. 4). The quantity r_d^2/D_0 is the time scale in which $\lambda_i^{(k)}$ relaxes to $\tilde{\lambda}_i^{(k)}$. The form of λ_i , and also the differential equation that related λ_i to $\tilde{\lambda}_i$, as given in Eq. 5 can be obtained by using a matched asymptotic analysis at the membrane as derived in ref. 10. The time scale r_d^2/D_0 , which is on

the order of 1 ns, is in fact so fast that $\lambda_i^{(k)} \approx \tilde{\lambda}_i^{(k)}$ for physiological time scales of interest.

The term $j_i^{(kl)}$ denotes transmembrane currents that flow through ion channels, transporters, or pumps that are located within the cell membrane (17–19). We use the formalism introduced by Hodgkin and Huxley for ion channel currents (2–4), generalized to allow for nonlinear instantaneous current–voltage relations and ion concentration effects. We refer the reader to [supporting information \(SI\) Text, Table S1, and Movies S1–S9](#) for details.

Eqs. 1 and 2 with the interface condition 3 constitute the full system of equations. This is a differential algebraic system in which the electrostatic potential evolves so that the electroneutrality condition 2 is satisfied at each instant. We may derive an elliptic equation that is satisfied by ϕ , by taking the derivative of 2 in time t and substituting 1 for $\partial c_i/\partial t$:

$$\nabla \cdot (a(\mathbf{x}, t) \nabla \phi + \nabla b(\mathbf{x}, t)) = 0 \quad [6]$$

$$a = \sum_{i=1}^N \frac{(qz_i)^2 D_i}{k_B T} c_i, \quad b = \sum_{i=1}^N qz_i D_i c_i. \quad [7]$$

This may be interpreted as a current conservation relation where $a \nabla \phi$ is the ohmic contribution and ∇b is the diffusive contribution to the electric current. We may identify $a(\mathbf{x}, t)$ with the electrolyte ohmic conductivity. We note that the equation satisfied by ϕ is Eq. 6, and not the Laplace equation. The electroneutral limit is one in which a small imbalance of large absolute ionic charge densities results in a nonzero Laplacian of the electrostatic potential (see ref. 9 for further discussion of this subtle issue).

In the simulations to follow, we apply the above model to cardiac geometries in which the smallest dimension is the width of an intercellular cleft that we vary from 2 to 50 nm. Since the Debye length is ≈ 1 nm, this raises the question as to whether electroneutrality is a valid approximation within such a narrow cleft, especially at the lower end of the thickness range that we consider. It turns out, however, that the electroneutral model is still a remarkably good approximation even at this length scale. We have demonstrated this by both asymptotic analysis and high-resolution one-dimensional computations (see refs. 9 and 10).

Application to Cardiac Physiology

Cardiac muscle consists of a network of cardiac muscle fibers. Each cardiac fiber may be seen as a linear strand of cardiomyocytes, separated from one another by a thin gap known as the intercalated disk. The intercalated disk is believed to be the site of both electrical and mechanical coupling between cells. Gap junctions are primarily located at the intercalated disk, providing a low-resistance pathway of electric current between the cells facing this gap. As discussed in the Introduction, it is not clear as to whether gap junctions are absolutely necessary for cardiac action potential propagation, especially given that connexin 43 knockout mice exhibit cardiac electric conduction (13). In this section, the foregoing model is used to explore the consequences of severely reduced gap junction conductance and the preferential localization of Na^+ channels to the intercalated disk in a model cardiac muscle fiber.

Model. We model a cardiac fiber as a strand of N_c cardiac cells all of which are assumed to be cylindrical in shape (Fig. 2). We take the radius of the circular cross-section of the cell to be $l_R = 24.7/2 \mu\text{m}$ and the length of the cell to be $l_A = 157.9 \mu\text{m}$ (experimentally measured values). Place the N_c cells so that the cylindrical axes of all of the cells lie along a single line. Take this line to be the z axis, and the radial coordinate to be the r axis.

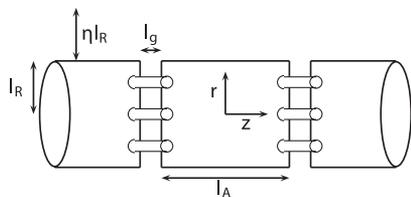


Fig. 2. Schematic diagram of the setting of the computational experiments. Each rectangular box represents a cylindrical cardiac cell. The cylinders connecting the cells are a schematic indication of the presence of gap-junctional coupling. l_R , radius of cell; l_A , length of cell; l_g , gap width; ηl_r , radial width of extracellular bath. In the computations of this article, the central cell shown here is replicated multiple times to produce a strand of cardiac cells.

Label the cells $k = 1 \dots N_c$ in order of increasing z coordinate. Only half of cell 1 and N_c are included in the computational domain. The intracellular region of cells 1 and N_c thus meet the outer boundary of the computational domain at the middle of the cell. The width of the gap between cells is l_g , which we vary in our simulations. The computational domain is taken to be a cylindrical domain of radius $(1 + \eta)l_R$ with the z axis as the center line. Since the N_c cells have radius l_R , the extracellular space corresponds to the region $l_R < r < (1 + \eta)l_R$ (which we shall call the extracellular bath) as well as the gaps between cells. We take $\eta = 1$ unless indicated otherwise.

We seek radially symmetric solutions, thus obviating the necessity to introduce an angular coordinate. No-flux boundary conditions are imposed at the outer boundary of the computational domain. We consider four ion types in the calculation, Na^+ , K^+ , Ca^{2+} , and Cl^- . Initial conditions are set to satisfy electroneutrality (see *SI Text* for details). To facilitate comparison with experimental data on mice (13, 20), we shall use the mouse cardiac model of Bondarenko *et al.* (21) as the ion channel model in our simulations with the following modifications. We do not include intracellular calcium handling in the Bondarenko model, since this would require a detailed geometric model of intracellular organelles. In addition, we do not include the background Na^+ conductance and the background Ca^{2+} conductance, which we have seen induce unwanted spontaneous membrane potential oscillations. The gap junctions are modeled as cytoplasmic pores, the details of which can be found in *SI Text*.

In the following sections, we vary several parameters to examine their effects on cardiac action potential propagation. First, we vary the total gap junction conductance per gap, G^{gap} , within the experimentally observed range (20). The next parameter of interest is the gap width l_g . The exact width of the gap is unknown, and we vary this parameter in the range 2–50 nm. As documented in refs. 16 and 22, recent evidence suggests the preferential localization of Na^+ channels on the membranes facing the intercellular gap. Denote the proportion of Na^+ channels expressed in the gap by p_{Na} . Following ref. 16, we vary p_{Na} [from $p_{\text{Na}} = \text{uniform}$ (no redistribution) to $p_{\text{Na}} = 0.99$ in which 99% of Na^+ channels reside on the membrane facing the gap], while keeping the total number of Na^+ channels on each cell constant. Finally, we vary η , which controls the size of the extracellular bath.

As documented in refs. 9 and 10, the equations we must simulate are numerically stiff. We use a finite volume discretization in space and an implicit discretization in time to perform the simulations to follow. The details may be found in ref. 10.

Normal Conduction. We first tested the model for normal conduction. According to ref. 20, the intercellular conductance along the fiber direction, which we identify as the conductance across gap junctions over the intercalated discs, is $G^{\text{gap}} = G_{\text{normal}} \equiv 5.58 \times 10^{-4}$ mS. In this and all ensuing simulations, gap

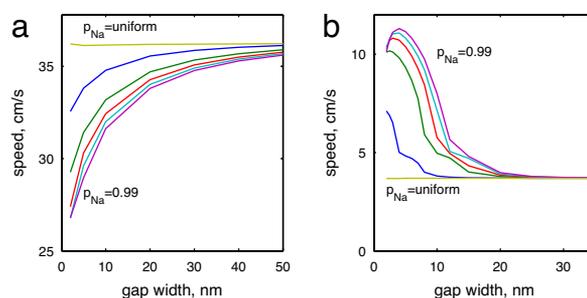


Fig. 3. CV for different values of p_{Na} as l_g is varied. (a) Gap junction conductance at its normal physiological value. (b) $G^{\text{gap}} = G_{\text{reduced}}$. In both panels, the ordinate is CV in centimeters/second, and the abscissa is the gap width l_g in nanometers. The different traces correspond to $p_{\text{Na}} = \text{uniform}$, 0.5, 0.8, 0.9, 0.95, and 0.99.

junction conductance is distributed uniformly over the membrane facing the intercalated disk so that the gap junction conductance per unit area, g^{gap} is given by $g^{\text{gap}} = G^{\text{gap}}/\pi l_R^2$ mS/ μm^2 . We initiate an action potential by transiently increasing the Na^+ conductance of cell 1.

The conduction velocities (CVs) when p_{Na} and l_g are varied are plotted in Fig. 3a (see *Movie S1* for a movie of the propagating action potential). When $p_{\text{Na}} = \text{uniform}$, we see that CV is insensitive to gap width l_g at ≈ 36 cm/s. When we redistribute Na^+ channels so that the density is higher facing the gap, CV decreases as l_g decreases, and this decrease is greater for higher values of p_{Na} .

There can be at least two factors that contribute to the decrease in CV with l_g . The first is that concentration changes can decrease the driving force for Na^+ channel currents, which are responsible for membrane depolarization. The narrower the gap, the quicker the depletion of Na^+ ions in the gaps, thereby reducing the equilibrium potential for Na^+ ions. The second factor is that the greater resistance of the narrower gap makes it difficult for current to flow through channels facing the gap. This will make the channels facing the gap less effective, thereby decreasing CV. This drop in CV as l_g decreases is also documented in ref. 16.

According to ref. 13, CV under normal conditions is approximately 40 cm/s in the transverse direction and 60 cm/s in the longitudinal direction. Given that the ion channel model of Bondarenko *et al.* (21) was only calibrated to voltage clamp data, the simulated propagation speed of approximately 30 cm/s may be considered relatively close to the experimentally observed value. We shall henceforth express the simulated CVs in percentages with respect to this value (30 cm/s) as well as in centimeters/second.

The source of the discrepancy between the computed and physiological CVs may be our simplification of taking only a single strand of cardiac cells, thus ignoring the 3D arrangement of cardiomyocytes. In a true cardiac preparation, electric current can go through many pathways to get from one cell to another, thereby reducing the effective resistance between two cells.

Conduction with Reduced Gap Junction Conductance. We now take a detailed look at conduction when gap junction conductance is severely reduced. According to ref. 20, the gap junction conductance at the intercalated disk space for connexin 43 (dominant gap junction expressed in cardiac tissue) knockout mice is $G^{\text{gap}} = G_{\text{reduced}} \equiv 1.10 \times 10^{-5}$ mS. Thus, G^{gap} is now reduced to $\approx 2\%$ of the normal value G_{normal} .

In the simulations shown in Fig. 4 (see *Movies S2–S6*), we have taken $l_g = 5$ nm and $p_{\text{Na}} = 0.95$. We initiate an action potential by transiently increasing the Na^+ conductance to the membrane

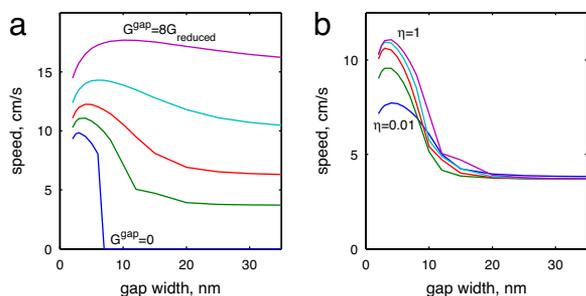


Fig. 6. CV when G^{gap} (a) and η (b) are varied. In both panels, the ordinate is CV in centimeters/second, and the abscissa is the gap width l_g in nanometers. (a) CV and G^{gap} . From top, $G^{\text{gap}}/G_{\text{reduced}} = 8, 4, 2, 1,$ and 0 . p_{Na} is fixed at 0.95 . Note that conduction completely fails for large values of l_g when $G^{\text{gap}} = 0$. (b) CV and η . $\eta = 0.01, 0.03, 0.1, 0.3,$ and 1 . Note the drop in CV for small η .

stimulus, the electrostatic potential in the gap is negative with respect to the extracellular bath. This tends to accelerate the propagation of the action potential (see [Movies S2 and S7](#)).

Varying Parameters. First of all, we study the effect of G^{gap} on CV as l_g is varied while keeping $p_{\text{Na}} = 0.95$. The most notable point about [Fig. 6a](#) is that propagation fails completely when $l_g \geq 7$ nm if there are no gap junctions connecting two adjacent cells. The propagation velocity is seen to increase with greater gap junction density at the gap, and at $G^{\text{gap}} = 8 \times G_{\text{reduced}}$, CV can reach ≈ 18 cm/s (60%).

We next study the effect of p_{Na} and l_g on CV, while fixing $G^{\text{gap}} = G_{\text{reduced}}$. The plot of CV is given in [Fig. 3b](#). We first note that even when p_{Na} is low, we do see action potential propagation albeit at a reduced velocity (3~4 cm/s). This is because cardiac action potentials have a long plateau phase during which the cell is depolarized, and a small gap junctional conductance is enough to inject sufficient current to the next cell to induce depolarization. CV increases with an increase in p_{Na} . For each fixed value of p_{Na} , CV does not increase (or decrease) monotonically with l_g . The velocity attains its maximum at approximately $l_g = 5$ nm, and this value is at most ≈ 12 cm/s (40%). The ratio is comparable with that seen in experiments [$\approx 36/62 = 58\%$ in the experimental case (13)]. This nonmonotonic behavior can also be seen in the 1D computations plotted in [Fig. 5a](#) and is also reported in [ref. 16](#). The explanation for this behavior, given in the following paragraph, is essentially the same as that given in [ref. 16](#).

Suppose that cell A and cell B are separated by a narrow gap and an excited action potential is to propagate from cell A into cell B. As discussed earlier, a narrower gap implies a greater drop in the electrostatic potential in the gap with respect to the extracellular bath. This facilitates action potential propagation by making it easier for ion channels on cell B facing the gap to be activated. However, a narrower gap means that it is more difficult for electric current to flow from the extracellular bath into cell B through the ion channels facing the gap. Cell B will not fully depolarize unless a sufficient amount of current is injected into it. Thus, a gap too narrow will tend to slow down action potential propagation. The propagation velocity slowing effect dominates for smaller (< 5 nm) gap widths, and the accelerating effect dominates for larger gap widths. At $l_g = 5$ nm, these effects balance and CV reaches a maximum. The length $l_g = 5$ nm is approximately equal to the distance between two membranes when bridged by gap junctions (16, 23) and may thus be considered the absolute minimum distance between two opposing membranes (16). It is interesting to note that the maximum CV is achieved at this gap width.

In [Fig. 3b](#) there is a small kink in the graph when CV is at ≈ 5 –6 cm/sec. In [Fig. 7](#), we plot the time points at which the action

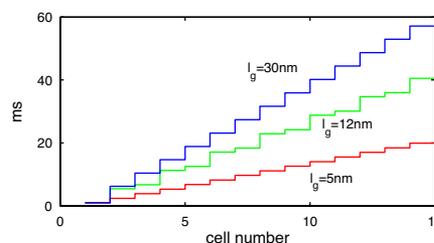


Fig. 7. Plot of action potential arrival times for a strand of 15 cells. $p_{\text{Na}} = 0.95$, $G^{\text{gap}} = G_{\text{reduced}}$, and $l_g = 30, 12,$ and 5 nm. Note the biphasic character of the arrival times for the middle trace ($l_g = 12$ nm).

potential reaches cell k when $l_g = 5, 12,$ or 30 nm while taking $p_{\text{Na}} = 0.95$. At $l_g = 12$ nm, we see a biphasic time series. Conduction is rapid between two cells k and $k + 1$ when k is even but is slow when k is odd.

As explained in the foregoing, at $l_g = 5$ nm, propagation can be attributed to the ephaptic mechanism. At $l_g = 30$ nm, the slow propagation is driven by the plateau phase of the cardiac action potential. At $l_g = 12$ nm, these two mechanisms play an equal role. Fast conduction between cells k and $k + 1$ when k is even is driven primarily by the ephaptic mechanism, and the slow conduction between cells k and $k + 1$ when k is odd is driven by the plateau phase mechanism (see [Movies S8 and S9](#)). The slower modes of propagation at $l_g = 12$ and 30 nm depend on L-type calcium current $I_{\text{Ca}}(\text{L})$, which is in turn influenced by intracellular calcium concentration $[\text{Ca}^{2+}]_{\text{int}}$. Given that our model does not incorporate the biophysical machinery of intracellular calcium handling, we tested whether the slower modes of propagation depend strongly on $I_{\text{Ca}}(\text{L})$ inactivation by $[\text{Ca}^{2+}]_{\text{int}}$. In place of $[\text{Ca}^{2+}]_{\text{int}}$, we used $f \times [\text{Ca}^{2+}]_{\text{int}}$, $0.01 \leq f \leq 100$ to inactivate $I_{\text{Ca}}(\text{L})$. Regardless of the value of f , we observed these modes of propagation.

In detail, propagation in the intermediate regime ($l_g = 12$ nm) proceeds as follows. Consider propagation from cell 1 to cell 2. Cell 1 depolarizes and a strong electric current rushes into the gap, generating a negative electrostatic potential in the gap with respect to the extracellular bath. This drop is not sufficient to depolarize cell 2 and soon dissipates without initiating a depolarization in cell 2. The action potential of cell 1, meanwhile, reaches a plateau phase. Since the electrostatic potential inside of cell 1 is higher than that inside of cell 2, electric current flows into cell 2, slowly depolarizing the cell. Cell 3 also receives current from cell 2, and its membrane potential slowly increases but at a slower rate than that of cell 2. Cell 2 eventually reaches threshold and is fully depolarized. Depolarization of cell 2 induces a negative drop in the electrostatic potential in the gap between cells 2 and 3. This time, the ephaptic mechanism is successful, and cell 3 rapidly depolarizes, unlike what happened between cells 1 and 2. The key difference is that cell 3 was primed during the slow depolarization phase of cell 2. This cycle repeats itself because cell 3 must now activate an unprimed cell 4.

Under reduced gap junction coupling, conduction is primarily due to the ephaptic mechanism when l_g is small, whereas the gap-junction-mediated mechanism dominates, despite the drastic reduction in gap junction conduction when l_g is larger. There is a transition zone between the two regimes, in which the ephaptic and gap-junction-mediated mechanisms alternate in propagating the action potential to the neighboring cell.

We finally study the effect of the size of the extracellular bath on CV ([Fig. 6b](#)). We see that CV tends to decrease with a decrease in η , when the gap width is set to $l_g = 5$ nm. This is because a large current flux into the cell is required for rapid conduction. When the extracellular space is limited, as may be

