# Discrete to continuum convergence rates in graph-based learning at percolation length scales 

Jeff Calder

School of Mathematics
University of Minnesota

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Joint work with: Leon Bungert (Hausdorff Center for Mathematics, University of Bonn) and Tim Roith (Friedrich-Alexander-Universität Erlangen-Nürnberg)

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## Graph-based learning

Let $(\mathcal{X}, \mathcal{W})$ be a graph.

- Vertices $\mathcal{X} \subset \mathbb{R}^{d}$.
- Nonnegative edge weights $\mathcal{W}=\left(w_{x y}\right)_{x, y \in \mathcal{X}}$.

Some common graph-based learning tasks:
(1) Clustering
(2) Semi-supervised learning
(3) Data Depth

- Link prediction
- Ranking

Applications of graph-based learning:
(1) Image classification
(2) Social media networks
(3 Biological networks
(- Drug discovery

(0) Wireless networks

## Similarity graphs

Some MNIST Digits

| 5 | 0 | 4 | 1 | 9 | 2 | 1 | 3 | 1 | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 3 | 5 | 3 | 6 | 1 | 7 | 2 | 8 | 6 | 9 |
| 4 | 0 | 9 | 1 | 1 | 2 | 4 | 3 | 2 | 7 |
| 3 | 8 | 6 | 9 | 0 | 5 | 6 | 0 | 7 | 6 |
| 1 | 8 | 1 | 9 | 3 | 9 | 8 | 5 | 9 | 3 |
| 3 | 0 | 7 | 4 | 9 | 8 | 0 | 9 | 4 | 1 |
| 4 | 4 | 6 | 9 | 4 | 5 | 6 | 1 | 0 | 0 |
| 1 | 7 | 1 | 6 | 3 | 0 | 2 | 1 | 1 | 1 |
| 9 | 0 | 2 | 6 | 7 | 8 | 3 | 9 | 0 | 4 |
| 6 | 7 | 4 | 6 | 8 | 0 | 7 | 8 | 3 | 1 |

- Each image is a datapoint

$$
x \in \mathbb{R}^{28 \times 28}=\mathbb{R}^{784}
$$

- Geometric weights:

$$
w_{x y}=\eta\left(\frac{|x-y|}{\varepsilon}\right)
$$

- $k$-nearest neighbor graph:

$$
w_{x y}=\eta\left(\frac{|x-y|}{\varepsilon_{k}(x)}\right)
$$

- Often $\eta(t)=e^{-t^{2}}$.


## Similarity graphs via deep learning

Set $w_{x y}=\eta\left(\frac{|\Psi(x)-\Psi(y)|}{\varepsilon}\right)$ where $\Psi: \mathbb{R}^{d} \rightarrow \mathbb{R}^{N}$ is learned.
Synthetic Aperture Radar (SAR) Images





Calder, J., Cook, B., Thorpe, M., \& Slepcev, D. (2020, November). Poisson learning: Graph based semi-supervised learning at very low label rates. In International Conference on Machine Learning (pp. 1306-1316). PMLR.

Miller, K., Mauro, J., Setiadi, J., Baca, X., Shi, Z., Calder, J., \& Bertozzi, A. L. (2022, May). Graph-based active learning for semi-supervised classification of SAR data. In Algorithms for Synthetic Aperture Radar Imagery XXIX (Vol. 12095, pp. 126-139). SPIE.

## Graph-based semi-supervised learning

Given: $\operatorname{Graph}(\mathcal{X}, \mathcal{W})$, labeled nodes $\Gamma \subset \mathcal{X}$, and labels $g: \Gamma \rightarrow \mathbb{R}^{k}$.
Task: Extend the labels to the rest of the graph $\mathcal{X} \backslash \Gamma$.
Semi-supervised: Goal is to use both the labeled and unlabeled data.
A common method is Laplacian regularized learning, which solves the equation

$$
\left\{\begin{aligned}
\mathcal{L} u=0 & \text { in } \mathcal{X} \backslash \Gamma \\
u=g & \text { on } \Gamma
\end{aligned}\right.
$$

where $u: \mathcal{X} \rightarrow \mathbb{R}^{k}$, and $\mathcal{L}$ is the graph Laplacian

$$
\mathcal{L} u(x)=\sum_{y \in \mathcal{X}} w_{x y}(u(x)-u(y))
$$

There are many other methods based on different graph PDEs or normalizations of the graph Laplacian.

Zhu, X., Ghahramani, Z., \& Lafferty, J. D. (2003). Semi-supervised learning using gaussian fields and harmonic functions. In Proceedings of the 20th International conference on Machine learning (ICML-03) (pp. 912-919).

## Spectral clustering

Spectral clustering: To cluster into $k$ groups:
(1) Compute first $k$ eigenvectors of the graph Laplacian $\mathcal{L}$ :

$$
u_{1}, \ldots, u_{k}: \mathcal{X} \rightarrow \mathbb{R}
$$

(2) Define the spectral embedding $\Psi: \mathcal{X} \rightarrow \mathbb{R}^{k}$ by

$$
\Psi(x)=\left(u_{1}(x), u_{2}(x), \ldots, u_{k}(x)\right) .
$$

(3) Cluster the point cloud $\mathcal{Y}=\Psi(\mathcal{X})$ with your favorite clustering algorithm.

Spectral methods are widely used for dimension reduction and clustering in data science and machine learning.

- Spectral clustering [Shi and Malik (2000)] [ Ng , Jordan, and Weiss (2002)]
- Laplacian eigenmaps [Belkin and Niyogi (2003)]
- Diffusion maps [Coifman and Lafon (2006)]


## Spectral embedding: MNIST



Digits 1 and 2 from MNIST visualized with spectral projection

## Spectral embedding: MNIST



Digits 1 (blue) and 2 (red) from MNIST visualized with spectral projection

## Application: Segmenting broken bone fragments



Spectral clustering with weights

$$
w_{i j}=\exp \left(-C\left|\mathbf{n}_{i}-\mathbf{n}_{j}\right|^{p}\right)
$$

between nearby points on the mesh, where $\mathbf{n}_{i}$ is the outward normal vector at vertex $i$.

## Discrete to continuum convergence

Let $\mathcal{X}_{n}=\left\{x_{1}, \ldots, x_{n}\right\}$ be an i.i.d. sample from a density $\rho$ on a smooth manifold $\mathcal{M} \subset \mathbb{R}^{D}$ of dimension $d$. Define a graph with geometric weights of the form

$$
w_{i j}=\eta\left(\varepsilon^{-1}\left|x_{i}-x_{j}\right|\right)
$$

The spectrum of the graph-Laplacian $\mathcal{L}$ converges $(n \rightarrow \infty, \varepsilon \rightarrow 0)$ to the spectrum of the weighted Laplace-Beltrami operator

$$
\Delta_{\mathcal{M}} u=-\rho^{-1} \operatorname{div}_{\mathcal{M}}\left(\rho^{2} \nabla_{\mathcal{M}} u\right)
$$

Sample of spectral convergence results

- Garcia Trillos, Gerlach, Hein, and Slepcev (2018):

$$
\left\|u-u_{n}\right\|_{L^{2}(\mathcal{M})} \leq C \sqrt{\frac{\delta_{n}}{\varepsilon}+\varepsilon}, \quad \delta_{n}=\left(\frac{\log n}{n}\right)^{1 / d}
$$

- Calder, Garcia Trillos (2022):

$$
\left\|u-u_{n}\right\|_{L^{2}(\mathcal{M})} \leq C \varepsilon, \quad \text { provided } \varepsilon \geq \delta_{n}^{d /(d+4)}
$$

Problem: Prove quantitative rates at the more practically relevant scaling $\varepsilon \sim \delta_{n}$.

## Loss of pointwise consistency

The graph Laplacian $\mathcal{L}$ is not consistent (nor convergent) when $\varepsilon \sim \delta_{n}$. At a high level:

$$
\begin{aligned}
\mathcal{L} u(x) & =\frac{1}{n \varepsilon^{d+2} \sigma_{\eta}} \sum_{j=1}^{n} \eta\left(\varepsilon^{-1}\left|x-x_{j}\right|\right)\left(u\left(x_{j}\right)-u(x)\right) \\
& =\frac{1}{\varepsilon^{d+2} \sigma_{\eta}} \int_{B(x, \varepsilon)} \eta\left(\varepsilon^{-1}|x-y|\right)(u(y)-u(x)) \rho(y) d y+O\left(\sqrt{\frac{\sigma^{2}}{n}}\right) \\
& =\Delta_{\rho} u(x)+O\left(\varepsilon+\sqrt{\frac{1}{n \varepsilon^{d+2}}}\right) .
\end{aligned}
$$

Since $\delta_{n}^{d}=\log (n) / n$ we can write the error term as (up to log factors)

$$
\mathcal{L} u(x)=\Delta_{\rho} u(x)+O\left(\varepsilon+\sqrt{\frac{\delta_{n}^{d}}{\varepsilon^{d+2}}}\right) .
$$

To match the $O(\varepsilon)$ error term we need $\delta_{n}^{d} \leq \varepsilon^{d+4}$, or

$$
\varepsilon \geq \delta_{n}^{d /(d+4)}
$$

## Numerical experiments

Rates of convergence for

$$
\varepsilon=\delta_{n}^{d /(d+2)}
$$

of the form $O\left(\varepsilon^{b}\right)$ (value of $b$ is shown) for eigenvalues and eigenvectors of the graph Laplacian on the 2 -sphere. Rates are all between $O\left(\varepsilon^{2}\right)$ and $O\left(\varepsilon^{3}\right)$.


We expect there is some kind of homogenization occurring at smaller length scales.

## Lipschitz learning

Lipschitz learning performs semi-supervised learning by solving the $\infty$-Laplace equation

$$
\left\{\begin{array}{cl}
\mathcal{L}_{\infty} u=0 & \text { in } \mathcal{X}_{n} \backslash \Gamma \\
u=g & \text { in } \Gamma,
\end{array}\right.
$$

where $\quad \mathcal{L}_{\infty} u(x):=\max _{y \in \mathcal{X}_{n}} w_{x y}(u(y)-u(x))+\min _{y \in \mathcal{X}_{n}} w_{x y}(u(y)-u(x))$.
Rough consistency argument: Assume $w_{x y}=1_{|x-y| \leq \varepsilon}$.

$$
\begin{aligned}
\mathcal{L}_{\infty} u(x) & =\left(\max _{y \in B(x, \varepsilon)}+\min _{y \in B(x, \varepsilon)}\right)(u(y)-u(x))+O\left(\delta_{n} \varepsilon\right) \\
& =u\left(x+\varepsilon \frac{\nabla u}{|\nabla u|}\right)-2 u(x)+u\left(x-\varepsilon \frac{\nabla u}{|\nabla u|}\right)+O\left(\delta_{n} \varepsilon+\varepsilon^{3}\right) \\
& =\varepsilon^{2} \frac{\nabla u^{T} \nabla^{2} u \nabla u}{|\nabla u|^{2}}+O\left(\delta_{n} \varepsilon+\varepsilon^{3}\right)=\varepsilon^{2} \Delta_{\infty} u(x)+O\left(\delta_{n} \varepsilon+\varepsilon^{3}\right) .
\end{aligned}
$$

We require $\delta_{n} \varepsilon \ll \varepsilon^{3}$ or $\varepsilon \gg \delta_{n}^{1 / 2}$ for $O(\varepsilon)$ consistency.

Kyng, R., Rao, A., Sachdeva, S., \& Spielman, D. A. (2015, June). Algorithms for Lipschitz learning on graphs. In Conference on Learning Theory (pp. 1190-1223). PMLR.

## Discrete to continuum for $\infty$-Laplacian

Letting $x_{1}, \ldots, x_{n}$ be i.i.d. on $\Omega \subset \mathbb{R}^{d}$, the continuum version of the discrete problem

$$
\left\{\begin{aligned}
\mathcal{L}_{\infty} u_{n}=0 & \text { in } \mathcal{X}_{n} \backslash \Gamma \\
u_{n}=g & \text { in } \Gamma,
\end{aligned}\right.
$$

is the $\infty$-Laplace equation

$$
\left\{\begin{align*}
\Delta_{\infty} u & =0, & & \text { in } \Omega \backslash \Gamma  \tag{1}\\
u & =g, & & \text { on } \Gamma \\
\frac{\partial u}{\partial n} & =0, & & \text { on } \partial \Omega \backslash \Gamma .
\end{align*}\right.
$$

## Discrete to continuum for $\infty$-Laplacian

- (Oberman 2005) On a uniform grid with we have $u_{n} \rightarrow u$ uniformly if $\varepsilon \gg \delta_{n}$.
- (Smart 2010) On a uniform grid

$$
\left\|u_{n}-u\right\|_{\infty} \leq C \sqrt[3]{\frac{\delta_{n}}{\varepsilon^{2}}} \quad \text { for } \delta_{n}^{1 / 2} \leq \varepsilon \leq \delta_{n}^{1 / 5}
$$

- (Calder 2019) On a random geometric graph (RGG) $w_{i j}=\eta\left(\varepsilon^{-1}\left|x_{i}-x_{j}\right|\right)$ on the Torus we have $u_{n} \rightarrow u$ provided $\varepsilon_{n} \gg \delta_{n}^{2 / 3}$.
- (Bungert \& Roith 2022) Gamma convergence on RGG provided $\varepsilon_{n} \gg \delta_{n}$.
- (Bungert, Calder, \& Roith, 2022a) On RGG we have

$$
\left\|u_{n}-u\right\|_{\infty} \leq C \sqrt[4]{\frac{\delta_{n}}{\varepsilon}} \quad \text { for } \delta_{n} \ll \varepsilon \leq \delta_{n}^{5 / 9}
$$

- (Bungert, Calder, \& Roith, 2022b) On uniform RGG with $\varepsilon \sim \delta_{n}$ we have

$$
\left\|u_{n}-u\right\|_{\infty} \leq C \delta_{n}^{1 / 9}
$$

## Numerical results




## Numerical results



Figure: Empirical convergence rates for (left) unit weights and (right) singular weights.

## Max Ball Theorem

For continuous $u: \mathbb{R}^{d} \rightarrow \mathbb{R}$ define

$$
u^{\varepsilon}(x)=\max _{B(x, \varepsilon)} u \text { and } u_{\varepsilon}(x)=\min _{B(x, \varepsilon)} u .
$$

Define the nonlocal $\infty$-Laplacian

$$
\Delta_{\infty}^{\varepsilon} u(x)=\left(\max _{B(x, \varepsilon)}+\min _{B(x, \varepsilon)}\right) u-2 u(x)=u^{\varepsilon}(x)+u_{\varepsilon}(x)-2 u(x)
$$

Recall the $\infty$-Laplacian is defined as

$$
\Delta_{\infty} u=\frac{\nabla u^{T} \nabla^{2} u \nabla u}{|\nabla u|^{2}} .
$$

## Theorem (Smart 2010)

If $\Delta_{\infty} u=0$ in the viscosity sense, then $\Delta_{\infty}^{\varepsilon} u_{\varepsilon} \leq 0$ and $\Delta_{\infty}^{\varepsilon} u^{\varepsilon} \geq 0$.

## Max Ball Theorem

## Theorem (Smart 2010)

If $\Delta_{\infty} u=0$ in the viscosity sense, then $\Delta_{\infty}^{\varepsilon} u_{\varepsilon} \leq 0$ and $\Delta_{\infty}^{\varepsilon} u^{\varepsilon} \geq 0$.

## Proof.

1. Check that $\Delta_{\infty}|x|=0$.
2. Use the comparison principle (comparison with cones) to obtain

$$
u(y) \geq u(x)-\left(\frac{u(x)-u_{2 \varepsilon}(x)}{2 \varepsilon}\right)|y-x|, \quad y \in B(x, 2 \varepsilon)
$$

3. Minimize both sides over $y \in B(x, \varepsilon)$ (i.e., $|x-y|=\varepsilon$ ) to find that
4. Now compute

$$
u_{\varepsilon} \geq \frac{1}{2}\left(u+u_{2 \varepsilon}\right)
$$

$$
\Delta_{\infty}^{\varepsilon} u_{\varepsilon}(x)=\left(\max _{B(x, \varepsilon)}+\max _{B(x, \varepsilon)}\right) u_{\varepsilon}-2 u_{\varepsilon}(x) \leq u(x)+u_{2 \varepsilon}(x)-2 u_{\varepsilon}(x) \leq 0
$$

## Max Ball on Graph Functions

For $u_{n}: \mathcal{X}_{n} \rightarrow \mathbb{R}$ define

$$
u_{n}^{h}(x)=\max _{\mathcal{X}_{n} \cap B(x, h)} u_{n} \text { and } u_{n, h}(x)=\min _{\mathcal{X}_{n} \cap B(x, h)} u_{n}
$$

Roughly speaking, we can show (using comparison against graph cones) that

$$
u_{n}(y) \geq u_{n}(x)-\left(\frac{u_{n}(x)-u_{n, 2 h}(x)}{\min _{y \in \mathcal{X}_{n} \backslash B(x, 2 h)} d_{n}(x, y)}\right) d_{n}(x, y), \quad y \in \mathcal{X}_{n} \cap B(x, 2 h)
$$

Minimize both sides over $y \in B(x, h)$ to obtain

$$
\begin{gathered}
u_{n, h}(x) \geq \frac{1}{2}\left(u_{n}(x)+u_{n, 2 h}\right)+s_{n}(x)\left(u_{n}-u_{n, 2 h}\right), \\
\text { where } \quad s_{n}(x)=\frac{1}{2}-\frac{\max _{x \in \mathcal{X}_{n} \cap B(x, h)} d_{n}(x, y)}{\min _{y \in \mathcal{X}_{n} \backslash B(x, 2 h)} d_{n}(x, y)} .
\end{gathered}
$$

This yields

$$
\Delta_{\infty}^{h} u_{n, h} \leq C s_{n} h
$$

## Percolation Theory

First passage percolation theory studies asymptotics of distance functions on random irregular domains, like geometric graphs or lattices.
(1) Lattice Percolation: Graph nodes are $\mathcal{X}=\varepsilon \mathbb{Z}^{d}$, edges between $x$ and $x \pm \varepsilon e_{i}$ with i.i.d. random edge weights.
(2) Power Weighted Percolation: Graph nodes are $n$ i.i.d. random variables, and the graph is complete with edge weights

$$
w_{x y}=|x-y|^{\alpha} \quad \text { for } \alpha>1
$$

(3) Euclidean Percolation: Graph nodes are $n$ i.i.d. random variables, and edge weights are geometric

$$
w_{x y}=\eta\left(\frac{|x-y|}{\varepsilon_{n}}\right)
$$

Auffinger, Antonio, Michael Damron, and Jack Hanson. 50 years of first-passage percolation. Vol. 68. American Mathematical Soc., 2017.

## Ratio Convergence in Euclidean Percolation

## Theorem (Bungert, Calder, Roith 2022)

Assume $\rho$ is uniform and $\eta(t)=t^{-1}$. Let $x_{0}, x \in \mathbb{R}^{d}$ and assume

$$
K \delta_{n} \leq \varepsilon \leq \frac{\left|x-x_{0}\right|}{2}
$$

Then there exist constants $C_{1}, C_{2}>0$ which are independent of $x_{0}$ and $x$ such that:
(1) (Concentration) For all $\lambda>0$ it holds that

$$
\mathbb{P}\left(\left|d_{n}\left(x_{0}, x\right)-\mathbb{E}\left[d_{n}\left(x_{0}, x\right)\right]\right|>\lambda K \delta_{n} \sqrt{\frac{\left|x-x_{0}\right|}{\varepsilon}}\right) \leq C_{1} \exp \left(-C_{2} \lambda\right)
$$

(2) (Ratio convergence in expectation) For $n$ sufficiently large, $x_{0}=0$, and $x \in \mathbb{R}^{d}$ such that $\varepsilon \leq|x|$ it holds that

$$
\left|\frac{\mathbb{E}\left[d_{n}(0, x)\right]}{\mathbb{E}\left[d_{n}(0,2 x)\right]}-\frac{1}{2}\right| \leq C_{1} \frac{\varepsilon}{|x|}+\frac{C_{2} K \delta_{n}}{\sqrt{\varepsilon|x|}} \log \left(n^{1 / d}|x|\right)
$$

## Ratio Convergence in Euclidean Percolation

## Theorem (Bungert, Calder, Roith 2022)

Assume $\rho$ is uniform and $\eta(t)=t^{-1}$. Let $x_{0}, x \in \mathbb{R}^{d}$ and assume $\varepsilon=K \delta_{n}$. Then up to log factors we have
(1) (Concentration) For all $\lambda>0$ it holds that

$$
\mathbb{P}\left(\frac{\left|d_{n}\left(x_{0}, x\right)-\mathbb{E}\left[d_{n}\left(x_{0}, x\right)\right]\right|}{\left|x-x_{0}\right|}>\lambda K \sqrt{\frac{\delta_{n}}{\left|x-x_{0}\right|}}\right) \leq C_{1} \exp \left(-C_{2} \lambda\right)
$$

(2) (Ratio convergence in expectation) For $n$ sufficiently large, $x_{0}=0$, and $x \in \mathbb{R}^{d}$ such that $K \delta_{n} \leq|x|$ it holds that

$$
\left|\frac{\mathbb{E}\left[d_{n}(0, x)\right]}{\mathbb{E}\left[d_{n}(0,2 x)\right]}-\frac{1}{2}\right| \leq C_{1} K \sqrt{\frac{\delta_{n}}{|x|}}
$$

Remark (Bungert, Calder, Roith 2022)
Compare this to the best known convergence rates to Euclidean distance

$$
d_{n}(x, y)=|x-y|+O\left(\varepsilon+|x-y| \frac{\delta_{n}}{\varepsilon}\right)
$$

## Future work, papers, and code

## Future Work:

(1) Extension of percolation results to non-uniform point clouds.
(2) Extension to general weights $\eta\left(\varepsilon^{-1}|x-y|\right)$.
(3) Extension to other types of graph Laplacians (i.e., 2-Laplacian, or spectral convergence)

Papers:
Bungert, L., Calder, J., \& Roith, T. (2022). Uniform Convergence Rates for Lipschitz Learning on Graphs. IMA Journal of Numerical Analysis.

Bungert, L., Calder, J., \& Roith, T. (2022). Ratio convergence rates for Euclidean first-passage percolation: Applications to the graph infinity Laplacian. arXiv preprint arXiv:2210.09023.

Code:

- https://github.com/jwcalder/LipschitzLearningRates
- https://github.com/TimRoith/PercolationConvergenceRates

