

(116) Two more important properties of $\omega \mapsto d\omega$:

THM 6.7.7: (i) For $\varphi \in A^k(U)$ having coefficients in $C^2(U)$, $d(d\varphi) = 0$.

6.7.8:

(ii) For $\varphi \in A^k(U)$ and $\psi \in A^l(U)$,

$$d(\varphi \wedge \psi) = d\varphi \wedge \psi + (-1)^k \varphi \wedge d\psi$$

proof: (ii) IS EXER 6.7.11 on your HW!

For (i), it's enough to check it (by linearity of d) when

$$\varphi = f(x) dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

where one has

$$\begin{aligned} d(d\varphi) &= d\left(\sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k}\right) \\ &= \left(\sum_{i=1}^n \sum_{j=1}^n \frac{\partial^2 f}{\partial x_j \partial x_i} dx_j \wedge dx_i\right) \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k} \end{aligned}$$

$$= 0 \text{ since } dx_i \wedge dx_j = \begin{cases} 0 & \text{if } i=j \\ -dx_j \wedge dx_i & \text{if } i \neq j \end{cases}$$

but $\frac{\partial^2 f}{\partial x_j \partial x_i} = \frac{\partial^2 f}{\partial x_i \partial x_j}$ ▣

4/24/2017 >

EXAMPLE: $d(d(x^2y^3)) = d(2xy^3dx + 3x^2y^2dy) = 6xy^3dydx + 6xy^3dxdy = 0$

§6.8 DIV, grad, & curl

There are 3 operations in vector calculus of \mathbb{R}^3 and physics that have nice interpretations/unifications via $\omega \mapsto d\omega$:

For $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, $\text{grad } f := \begin{bmatrix} \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{bmatrix} = \text{"}\nabla f\text{"} = \text{gradient of } f$

For a vector field $\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $\text{curl } \vec{F} := \text{"}\nabla \times \vec{F}\text{"} = \begin{bmatrix} \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{bmatrix} \times \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix} = \text{curl of } \vec{F}$

$$= \begin{bmatrix} \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \\ -\left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z}\right) \\ \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \end{bmatrix}$$

$\text{div } \vec{F} := \text{"}\nabla \cdot \vec{F}\text{"} = \begin{bmatrix} \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{bmatrix} \cdot \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = \text{divergence of } \vec{F}$

(117) THM 6.8.3: (i) For $f \in A^0(\mathbb{R}^3)$, i.e. $f: \mathbb{R}^3 \rightarrow \mathbb{R}$,
~~then~~ then $df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz = W \nabla f$ = the work form
of $\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{bmatrix} \in A^1(\mathbb{R}^3)$

(ii) For $W_{\mathbf{F}} = F_1 dx + F_2 dy + F_3 dz \in A^1(\mathbb{R}^3)$
= Work form of $\mathbf{F} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix}$,

$$\text{then } dW_{\mathbf{F}} = \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx \wedge dy + \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) dx \wedge dz + \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) dy \wedge dz$$

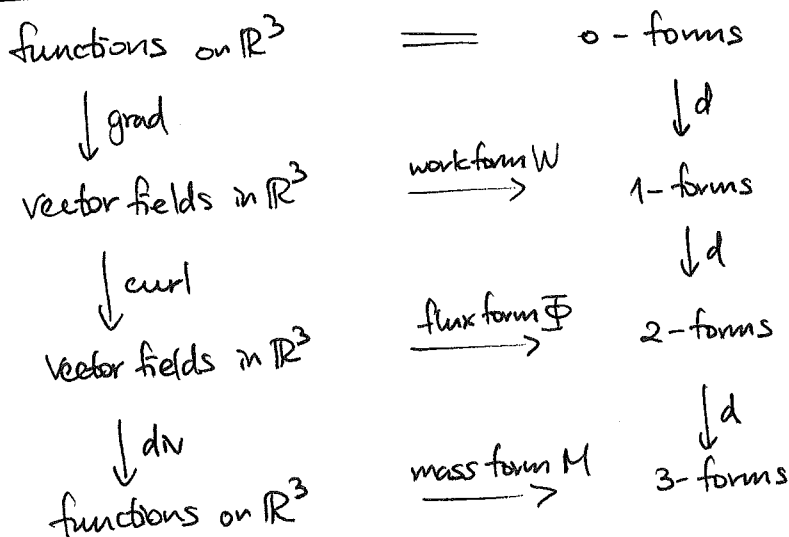
$$= \Phi_{\text{curl } \mathbf{F}} = \text{the flux form of } \text{curl } \mathbf{F} \in A^2(\mathbb{R}^3)$$

(iii) For $\Phi_{\mathbf{F}} = \cancel{F_1 dy \wedge dz} - F_2 dx \wedge dz + F_3 dx \wedge dy \in A^2(\mathbb{R}^3)$
= the flux 2-form of $\mathbf{F} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix}$,

$$\text{then } d\Phi_{\mathbf{F}} = \left(\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right) dx \wedge dy \wedge dz = M_{\text{div } \mathbf{F}}$$

$$= \text{the mass 3-form of } \text{div } \mathbf{F} \in A^3(\mathbb{R}^3)$$

SUMMARY TABLE from p.630



Note (RMK 6.8.6) that $d(d\varphi) = 0$ implies

$$\text{curl}(\text{grad } f) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

"gradient flows (or conservative vector fields) are irrotational"
 $\uparrow \text{curl} = 0$
 $\nwarrow \mathbf{F} = \nabla f$ for some f

$$\text{div}(\text{grad } \mathbf{F}) = 0$$

"a flow that comes from a curl is incompressible"
 $\uparrow \text{div} = 0$

(118) Why should a vector field $\vec{F} = \begin{pmatrix} F_1 \\ F_2 \\ F_3 \end{pmatrix}$ of the form $\vec{F} = \nabla f$ for some function $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ be called conservative?

Dipping into §6.10, the Fundamental Thm. for Line Integrals says

THM 6.10.1: For an oriented curve $C \subset \mathbb{R}^2$ or \mathbb{R}^3 and $f \in A^0(U)$ in some open neighborhood U of C will have

$$\int_C df = f(b) - f(a) \quad (= \int_C f)$$

$$\int_C \vec{F} \cdot \vec{\gamma}(t) dt$$

the line integral of \vec{F} over C

(i.e. Stokes's Thm!)

the answer only depends on the starting and endpoints b, a and the ^{difference in the} value of the potential function $f(x)$ there, not the path $[C] = [\gamma(V)]$ taken to get there

conservative

What does $\text{curl } \vec{F}$ "mean"?

The book discusses the curl probe ^(pp. 631-632): put a paddle at $\vec{x} \in \mathbb{R}^3$ inside the flow with velocity vectors locally $\vec{F}(\vec{x}) = \begin{pmatrix} F_1 \\ F_2 \\ F_3 \end{pmatrix}$, and the torque ^{locally} exerted on the paddles will be proportional to $\text{curl } \vec{F}(\vec{x}) \cdot \vec{n}$ if the handle points toward \vec{n}

why? Call the paddle wheel blades \vec{v}_1, \vec{v}_2 , so that $\vec{n} = \vec{v}_1 \times \vec{v}_2$

Then

$$\begin{aligned} \text{curl } \vec{F} \cdot \vec{n} &= \text{curl } \vec{F}(\vec{x}) \cdot (\vec{v}_1 \times \vec{v}_2) \\ &= \underbrace{\Phi}_{\text{curl } \vec{F}(\vec{x})} (P_{\vec{x}}(\vec{v}_1, \vec{v}_2)) \\ &= dW_{\vec{F}} \end{aligned}$$

$$= \lim_{h \rightarrow 0} \frac{1}{h^2} \int_{\partial P_{\vec{x}}(h\vec{v}_1, h\vec{v}_2)} W_{\vec{F}}$$

work done by \vec{F} as a force field going around the boundary of $P_{\vec{x}}(h\vec{v}_1, h\vec{v}_2)$

