

Office hours? MW 9:05
Tues 1:25

OVERVIEW

Chap 3 - approximating manifolds, linearly (tangent space)
quadratically (analyze max/mins, curvature) Math 3578
via higher degree polynomials (multivariate Taylor polynomials)

Chap 4 - integrating functions over \mathbb{R}^n ; mostly Riemannian, Lebesgue in §4.11 Math 5615

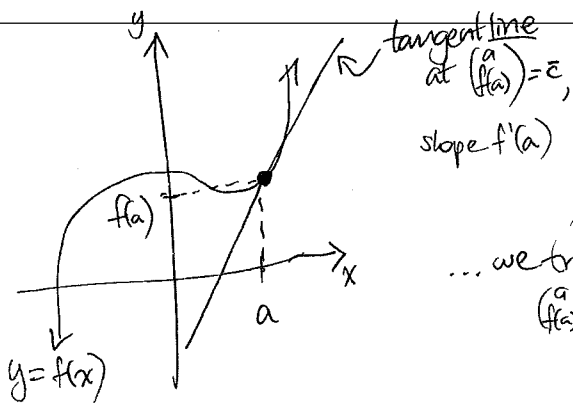
Chap 5 - arc length, surface area, higher volume via integration

Chap 6 - integration with orientations considered
- differential forms (divergence, Green, Stokes's Thms)

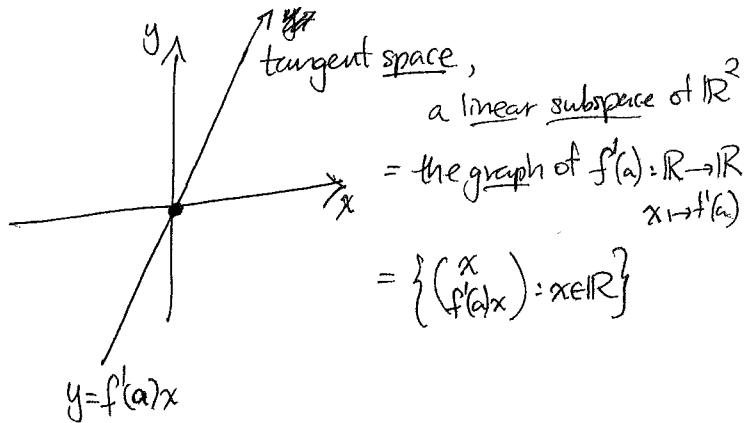
§ 3.2 Tangent spaces

As we've said in one variable, for the graph M of $f: \mathbb{R} \rightarrow \mathbb{R}$ near $(a, f(a)) = c \dots$

$$\left\{ \begin{pmatrix} x \\ f(x) \end{pmatrix} : x \in \mathbb{R} \right\}$$



... we translate $(a, f(a))$ to $(0, 0)$



DEFINITION (3.2.1) For $f: \mathbb{R}^k \rightarrow \mathbb{R}^{n-k}$ and M its graph $\left\{ \begin{pmatrix} \bar{x} \\ f(\bar{x}) \end{pmatrix} : \bar{x} \in \mathbb{R}^k \right\} \subset \mathbb{R}^n$,

define the tangent space $T_{\begin{pmatrix} \bar{a} \\ f(\bar{a}) \end{pmatrix}} M :=$ the graph $\left\{ \begin{pmatrix} \bar{x} \\ Df(\bar{a})\bar{x} \end{pmatrix} : \bar{x} \in \mathbb{R}^k \right\} \subset \mathbb{R}^n$
of $Df(\bar{a}): \mathbb{R}^k \rightarrow \mathbb{R}^{n-k}$

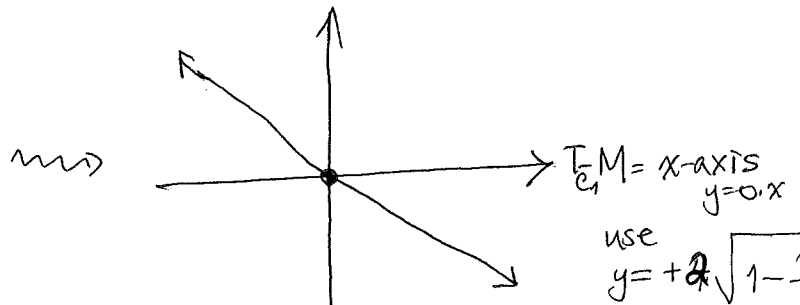
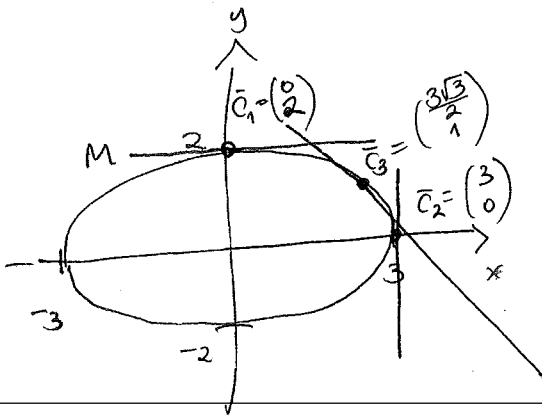
(2)

... and since for every k -dimensional manifold $M \subset \mathbb{R}^n$, by definition one can express it locally (by re-indexing the coordinates) around some $\bar{c} \in M$ as the graph $\left\{ \begin{pmatrix} \bar{x} \\ f(\bar{x}) \end{pmatrix} : \bar{x} \in U \right\}$ for some $U \xrightarrow{f} \mathbb{R}^{n-k}$, $\begin{pmatrix} \bar{a} \\ f(\bar{a}) \end{pmatrix}$

define the tangent space ~~of \mathbb{R}^k~~ $T_{\bar{c}}M := \text{the graph } \left\{ \begin{pmatrix} \bar{x} \\ Df(\bar{a})\bar{x} \end{pmatrix} : \bar{x} \in \mathbb{R}^k \right\}$
of ~~\mathbb{R}^k~~ $\mathbb{R}^k \xrightarrow{Df(\bar{a})} \mathbb{R}^{n-k}$

EXAMPLE: The ellipse $\frac{x^2}{9} + \frac{y^2}{4} = 1$ is a manifold $M \subset \mathbb{R}^2$

and here are 3 of its tangent lines & tangent spaces:



use $y = \pm \sqrt{1 - \frac{x^2}{9}}$

$T_{c2} M$
y-axis
 $x = 0 \cdot y$

$\frac{dy}{dx} = \frac{1}{2} \cdot \left(-\frac{2x}{9}\right) \cdot \left(1 - \frac{x^2}{9}\right)^{-1/2}$
graph of $\frac{dy}{dx} \Big|_{(0,2)} = 0 \Rightarrow y = 0 \cdot x$

use $x = \pm \sqrt{1 - \frac{y^2}{4}}$
 $\frac{dx}{dy} = \frac{1}{2} \cdot \left(-\frac{2y}{4}\right) \cdot \left(1 - \frac{y^2}{4}\right)^{-1/2}$
 $\frac{dx}{dy} \Big|_{(3,0)} = 0 \Rightarrow \text{graph of } x = 0 \cdot y$

For $T_{c3} M$, could use either parametrization to get the tangent space

e.g. $y = \pm \sqrt{1 - \frac{x^2}{9}}$ OR $x = \pm \sqrt{1 - \frac{y^2}{4}}$

$\frac{dy}{dx} = \frac{-2x}{9} \left(1 - \frac{x^2}{9}\right)^{-1/2}$ $\frac{dx}{dy} = \frac{-3y}{4} \left(1 - \frac{y^2}{4}\right)^{-1/2}$

$\frac{dy}{dx} \Big|_{\left(\frac{3\sqrt{3}}{2}, 1\right)} = \frac{-2 \cdot \frac{3\sqrt{3}}{2}}{9} \left(1 - \left(\frac{3\sqrt{3}}{2}\right)^2 / 9\right)^{-1/2} = \frac{-\sqrt{3}}{3} \left(\frac{1}{4}\right)^{-1/2} = \frac{2}{\sqrt{3}}$ \Rightarrow graph of $y = \frac{2}{\sqrt{3}}x$

$\frac{dx}{dy} \Big|_{\left(\frac{3\sqrt{3}}{2}, 1\right)} = \frac{-3 \cdot 1}{4} \left(1 - \frac{1}{4}\right)^{-1/2} = \frac{-3}{4} \left(\frac{3}{4}\right)^{-1/2} = \frac{-\sqrt{3}}{2} \Rightarrow$ graph of $x = \frac{\sqrt{3}}{2}y$

(3) How do we know either local parametrization should work there?

A more "parametrization" formulation of $T_{\bar{c}}M$ when M is defined implicitly...

THM 3.2.4: If \bar{c} is a point on a k -dimensional manifold $M \subset \mathbb{R}^n$ defined locally by $\bar{F}(\bar{z}) = \bar{0}$ for some $U \subset \mathbb{R}^n \xrightarrow{\bar{F}} \mathbb{R}^{n-k}$ with $D\bar{F}(\bar{c})$ of full rank $n-k$

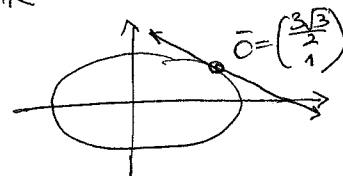
then $T_{\bar{c}}M = \ker D\bar{F}(\bar{c}) \subset \mathbb{R}^n$.

EXAMPLES:

① $M = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : \frac{x^2}{9} + \frac{y^2}{4} = 1 \right\} = \{ \bar{F}(\bar{z}) = \bar{0} \}$
 for $F \begin{pmatrix} x \\ y \end{pmatrix} = \frac{x^2}{9} + \frac{y^2}{4} - 1$
 $\mathbb{R}^2 \xrightarrow{\quad} \mathbb{R}$

$$D\bar{F} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} \frac{2x}{9} & \frac{y}{2} \end{bmatrix}$$

$$\mathbb{R}^2 \xrightarrow{\quad} \mathbb{R}$$

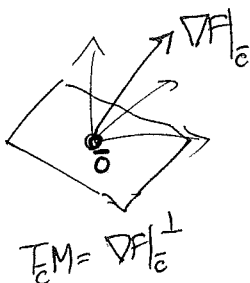


so $D\bar{F} \begin{pmatrix} \frac{\sqrt{3}}{2} \\ 1 \end{pmatrix} = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{2} \end{bmatrix}$
 $\mathbb{R}^2 \xrightarrow{\quad} \mathbb{R}$

which has $\ker D\bar{F}(\bar{c}) = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} : \frac{y}{\sqrt{3}} + \frac{x}{2} = 0 \right\}$
 $= \left\{ y = -\frac{\sqrt{3}}{2}x \right\}$
 $= \left\{ x = -\frac{2}{\sqrt{3}}y \right\}$

② A surface $M \subset \mathbb{R}^3$ defined by $F \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0$

will have tangent space $T_{\begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}} M$ given by $\ker D\bar{F} \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} = \ker \begin{bmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} & \frac{\partial F}{\partial z} \end{bmatrix} \Big|_{\begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}}$



$$= \left(\nabla F \Big|_{\begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}} \right)^\perp$$

gradient vector for F at \bar{c}